

Software Interface

CCURPMFC (WC-CP-FIO)

PCIe Programmable Multi-Function I/O Card (MIOC)

<i>Driver</i>	ccurpmfc (WC-CP-FIO)	v 23.0.3
<i>OS</i>	RedHawk (CentOS or Ubuntu based)	5.4, 6.0, 6.3, 6.5, 7.0, 7.2 and 7.3
<i>Vendor</i>	Concurrent Real-Time	
<i>Hardware</i>	PCIe Programmable Multi-Function Card (CP-FPGA-Ax)	
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1. Introduction

This document provides the software interface to the *ccurpmfc* driver which communicates with the Concurrent Real-Time PCI Express Programmable Multi-Function FPGA I/O Card (MIOC). For additional information on programming, please refer to the *Concurrent Real-Time PCIe Programmable Multi-Function I/O Cards (MIOC) Design Specification (No. 0610104)* document.

The software package that accompanies this board provides the ability for advanced users to communicate directly with the board via the driver *ioctl(2)* and *mmap(2)* system calls. When programming in this mode, the user needs to be intimately familiar with both the hardware and the register programming interface to the board. Failure to adhere to correct programming will result in unpredictable behavior.

Additionally, the software package is accompanied with an extensive set of application programming interface (API) calls that allow the user to access all capabilities of the board. The API library also allows the user the ability to communicate directly with the board through the *ioctl(2)* and *mmap(2)* system calls. In this case, there is a risk of this direct access conflicting with API calls and therefore should only be used by advanced users who are intimately familiar with the hardware, board registers and the driver code.

Various example tests have been provided in the *test* and *test/lib* directories to assist the user in developing their applications.

1.1 Related Documents

- PCIe Programmable Multi-Function Driver Installation on RedHawk Release Notes by Concurrent Real-Time.
- PCIe Programmable Multi-Function Card I/O (MIOC) Design Specification (No. 0610104) by Concurrent Real-Time.

2. Software Support

Software support is provided for users to communicate directly with the board using the kernel system calls (*Direct Driver Access*) or the supplied *API*. Both approaches are identified below to assist the user in software development.

2.1 Direct Driver Access

2.1.1 *open(2)* system call

In order to access the board, the user first needs to open the device using the standard system call *open(2)*.

```
int fp;
fp = open("/dev/ccurpmfc0", O_RDWR);
```

The file pointer '*fp*' is then used as an argument to other system calls. The user can also supply the *O_NONBLOCK* flag if the user does not wish to block waiting for reads to complete. In that case, if the read is not satisfied, the call will fail. The device name specified is of the format *"/dev/ccurpmfc<num>"* where *num* is a digit 0..9 which represents the board number that is to be accessed. Basically, the driver only allows one application to open a board at a time. The reason for this is that the application can have full access to the card, even at the board and API level. If another application were to communicate with the same card concurrently, the results would be unpredictable unless proper synchronization between applications is performed external to the driver. This driver allows multiple applications to open the same board by specifying the additional *oflag O_APPEND*. It is then the responsibility of the user to ensure that the various applications communicating with the same cards are properly synchronized. Various tests supplied in this package has the *O_APPEND* flags enabled, however, it is strongly recommended that only one application be

used with a single card at a time, unless the user is well aware of how the applications are going to interact with each other and accept any unpredictable results.

2.1.2 `ioctl(2)` system call

This system call provides the ability to control and get responses from the board. The nature of the control/response will depend on the specific *ioctl* command.

```
int    status;
int    arg;
status = ioctl(fp, <IOCTL_COMMAND>, &arg);
```

where, '*fp*' is the file pointer that is returned from the *open(2)* system call. *<IOCTL_COMMAND>* is one of the *ioctl* commands below and *arg* is a pointer to an argument that could be anything and is dependent on the command being invoked. If no argument is required for a specific command, then set to *NULL*.

Driver IOCTL command:

```
IOCTL_CCURPMFC_ABORT_DMA
IOCTL_CCURPMFC_ADD_IRQ
IOCTL_CCURPMFC_DISABLE_PCI_INTERRUPTS
IOCTL_CCURPMFC_ENABLE_PCI_INTERRUPTS
IOCTL_CCURPMFC_GET_DRIVER_ERROR
IOCTL_CCURPMFC_GET_DRIVER_INFO
IOCTL_CCURPMFC_GET_PHYSICAL_MEMORY
IOCTL_CCURPMFC_GET_ADC_READ_MODE
IOCTL_CCURPMFC_GET_DAC_WRITE_MODE
IOCTL_CCURPMFC_INIT_BOARD
IOCTL_CCURPMFC_INTERRUPT_TIMEOUT_SECONDS
IOCTL_CCURPMFC_MMAP_SELECT
IOCTL_CCURPMFC_NO_COMMAND
IOCTL_CCURPMFC_PCI_CONFIG_REGISTERS
IOCTL_CCURPMFC_REMOVE_IRQ
IOCTL_CCURPMFC_RESET_BOARD
IOCTL_CCURPMFC_SELECT_ADC_READ_MODE
IOCTL_CCURPMFC_SELECT_DAC_WRITE_MODE
IOCTL_CCURPMFC_WAIT_FOR_INTERRUPT
IOCTL_CCURPMFC_WAIT_FOR_DAC_FIFO_TO_DRAIN
IOCTL_CCURPMFC_RELOAD_FIRMWARE
IOCTL_CCURPMFC_GET_ALL_BOARDS_DRIVER_INFO
IOCTL_CCURPMFC_WAKEUP_DIO_COS_INTERRUPT
IOCTL_CCURPMFC_WAIT_FOR_DIO_COS_INTERRUPT
```

IOCTL_CCURPMFC_ABORT_DMA: This *ioctl* does not have any arguments. Its purpose is to abort any DMA already in progress..

IOCTL_CCURPMFC_ADD_IRQ: This *ioctl* does not have any arguments. Its purpose is to setup the driver *interrupt handler* to handle interrupts. If support for MSI interrupts are configured, they will be enabled. Normally, there is no need to call this *ioctl* as the interrupt handler is already added when the driver is loaded. This *ioctl* should only be invoked if the user has issued the *IOCTL_CCURPMFC_REMOVE_IRQ* call earlier to remove the interrupt handler.

IOCTL_CCURPMFC_DISABLE_PCI_INTERRUPTS: This *ioctl* does not have any arguments. Its purpose is to disable PCI interrupts. This call shouldn't be used during normal reads or writes, as calls could time out. The driver handles enabling and disabling interrupts during its normal course of operation.

IOCTL_CCURPMFC_ENABLE_PCI_INTERRUPTS: This *ioctl* does not have any arguments. Its purpose is to enable PCI interrupts. This call shouldn't be used during normal reads or writes as calls could time out. The driver handles enabling and disabling interrupts during its normal course of operation.

IOCTL_CCURPMFC_GET_DRIVER_ERROR: The argument supplied to this *ioctl* is a pointer to the *ccurpmfc_user_error_t* structure. Information on the structure is located in the *ccurpmfc_user.h* include file. The error returned is the last reported error by the driver. If the argument pointer is *NULL*, the current error is reset to *CCURPMFC_SUCCESS*.

IOCTL_CCURPMFC_GET_DRIVER_INFO: The argument supplied to this *ioctl* is a pointer to the *ccurpmfc_driver_info_t* structure. Information on the structure is located in the *ccurpmfc_user.h* include file. This *ioctl* provides useful driver information.

IOCTL_CCURPMFC_GET_PHYSICAL_MEMORY: The argument supplied to this *ioctl* is a pointer to the *ccurpmfc_user_phys_mem_t* structure. Information on the structure is located in the *ccurpmfc_user.h* include file. If physical memory is not allocated, the call will fail; otherwise the call will return the physical memory address and size in bytes. The only reason to request and get physical memory from the driver is to allow the user to perform DMA operations and bypass the driver and library. Care must be taken when performing user level DMA, as incorrect programming could lead to unpredictable results, including but not limited to corrupting the kernel and any device connected to the system.

IOCTL_CCURPMFC_GET_ADC_READ_MODE: The argument supplied to this *ioctl* is a pointer to an *unsigned long int*. The value returned will be one of the ADC read modes as defined by the *enum_ccurpmfc_driver_ADC_read_mode_t* located in the *ccurpmfc_user.h* include file.

IOCTL_CCURAOCC_GET_DAC_WRITE_MODE: The argument supplied to this *ioctl* is a pointer to an *unsigned long int*. The value returned will be one of the DAC write modes as defined by the *enum_ccurpmfc_driver_DAC_write_mode_t* located in the *ccurpmfc_user.h* include file.

IOCTL_CCURPMFC_INIT_BOARD: This *ioctl* does not have any arguments. This call resets the board to a known initial default state. This call is currently identical to the *IOCTL_CCURPMFC_RESET_BOARD* call.

IOCTL_CCURPMFC_INTERRUPT_TIMEOUT_SECONDS: The argument supplied to this *ioctl* is a pointer to an *int*. It allows the user to change the default time out from 30 seconds to user supplied time out. This is the time that the read call will wait before it times out. The call could time out if a DMA fails to complete. The device should have been opened in the block mode (*O_NONBLOCK* not set) for reads to wait for an operation to complete.

IOCTL_CCURPMFC_MMAP_SELECT: The argument to this *ioctl* is a pointer to the *ccurpmfc_mmap_select_t* structure. Information on the structure is located in the *ccurpmfc_user.h* include file. This call needs to be made prior to the *mmap(2)* system call so as to direct the *mmap(2)* call to perform the requested mapping specified by this *ioctl*. The four possible mappings that are performed by the driver are to *mmap* the local register space (*CCURPMFC_SELECT_LOCAL_MMAP*), the configuration register space (*CCURPMFC_SELECT_CONFIG_MMAP*) the physical memory (*CCURPMFC_SELECT_PHYS_MEM_MMAP*) that is created by the *mmap(2)* system call and the driver/library mapping (*CCURPMFC_SELECT_DRIVER_LIBRARY_MMAP*).

IOCTL_CCURPMFC_NO_COMMAND: This *ioctl* does not have any arguments. It is only provided for debugging purpose and should not be used as it serves no purpose for the application.

IOCTL_CCURPMFC_PCI_CONFIG_REGISTERS: The argument supplied to this *ioctl* is a pointer to the *ccurpmfc_pci_config_reg_addr_mapping_t* structure whose definition is located in the *ccurpmfc_user.h* include file.

IOCTL_CCURPMFC_REMOVE_IRQ: This *ioctl* does not have any arguments. Its purpose is to remove the interrupt handler that was previously setup. The interrupt handler is managed internally by the driver and the library. The user should not issue this call, otherwise reads will time out.

IOCTL_CCURPMFC_RESET_BOARD: This *ioctl* does not have any arguments. This call resets the board to a known initial default state. This call is currently identical to the *IOCTL_CCURPMFC_INIT_BOARD* call.

IOCTL_CCURPMFC_SELECT_ADC_READ_MODE: The argument supplied to this *ioctl* is a pointer to an *unsigned long int*. The value set will be one of the ADC read modes as defined by the *enum_ccurpmfc_driver_adc_read_mode_t* located in the *ccurpmfc_user.h* include file.

IOCTL_CCURPMFC_SELECT_DAC_WRITE_MODE: The argument supplied to this *ioctl* is a pointer to an *unsigned long int*. The value set will be one of the DAC write modes as defined by the *enum_ccurpmfc_driver_dac_write_mode_t* located in the *ccurpmfc_user.h* include file.

IOCTL_CCURPMFC_WAIT_FOR_INTERRUPT: The argument to this *ioctl* is a pointer to the *ccurpmfc_driver_int_t* structure. Information on the structure is located in the *ccurpmfc_user.h* include file. The user can wait for a DMA or Analog signal complete interrupt. If a time out value greater than zero is specified, the call will time out after the specified seconds, otherwise it will not time out.

IOCTL_CCURPMFC_WAIT_FOR_DAC_FIFO_TO_DRAIN: The argument to this *ioctl* is a pointer to *threshold*. The call will block until the samples in the DAC FIFO falls below the threshold value.

IOCTL_CCURPMFC_RELOAD_FIRMWARE: This *ioctl* does not have any arguments. This call performs a reload of the latest firmware that was loaded into the board. Typically, this is used after a new firmware has been installed. It eliminates the need to reboot the kernel after a firmware update.

IOCTL_CCURPMFC_GET_ALL_BOARDS_DRIVER_INFO: The argument to this *ioctl* is a pointer to *ccurpmfc_all_boards_driver_info*. It provides the ability to supply all driver information for all the *ccurpmfc* cards in the system to the user.

IOCTL_CCURPMFC_WAKEUP_DIO_COS_INTERRUPT: This *ioctl* does not have any arguments. The purpose of this call is to wake up a process that is blocked using the *IOCTL_CCURPMFC_WAIT_FOR_DIO_COS_INTERRUPT* *ioctl* waiting for a DIO change-of-state interrupt.

IOCTL_CCURPMFC_WAIT_FOR_DIO_COS_INTERRUPT: The argument to this *ioctl* is a pointer to the *ccurpmfc_driver_dio_cos_int_t* structure. Information on the structure is located in the *ccurpmfc_user.h* include file. The user can wait for a DIO complete interrupt with the *WakeupInterruptMas* mask. This call blocks indefinitely until a DIO change-of-state interrupt occurs. If a change-of-state interrupt occurs, this call returns useful DIO related statistics to the user. To cancel a pending wait, users can use the *IOCTL_CCURPMFC_WAKEUP_DIO_COS_INTERRUPT* *ioctl()* call.

2.1.3 mmap(2) system call

This system call provides the ability to map either the local board registers, the configuration board registers, create and map a physical memory that can be used for user DMA or driver/library structure mapping. Prior to making this system call, the user needs to issue the *ioctl(2)* system call with the *IOCTL_CCURPMFC_MMAP_SELECT* command. When mapping either the local board registers or the configuration board registers, the *ioctl* call returns the size of the register mapping which needs to be specified in the *mmap(2)* call. In the case of mapping a physical memory, the size of physical memory to be created is supplied to the *mmap(2)* call.

```
int *munmap_local_ptr;
ccurpmfc_local_ctrl_data_t *local_ptr;
ccurpmfc_mmap_select_t mmap_select;
unsigned long mmap_local_size;
```

```

mmap_select.select = CCURPMFC_SELECT_LOCAL_MMAP;
mmap_select.offset=0;
mmap_select.size=0;
ioctl(fp, IOCTL_CCURPMFC_MMAP_SELECT, (void *)&mmap_select);
mmap_local_size = mmap_select.size;

munmap_local_ptr = (int *) mmap((caddr_t)0, map_local_size,
                               (PROT_READ|PROT_WRITE), MAP_SHARED, fp, 0);

local_ptr = (ccurpmfc_local_ctrl_data_t *)munmap_local_ptr;
local_ptr = (ccurpmfc_local_ctrl_data_t *)((char *)local_ptr +
                                           mmap_select.offset);

.
.
.

if(munmap_local_ptr != NULL)
    munmap((void *)munmap_local_ptr, mmap_local_size);

```

2.1.4 read(2) system call

This system call currently supports ADC programmed I/O reads of channel registers and FIFO. The option selected is determined by the *ccurPMFC_ADC_Set_Driver_Read_Mode()* call.

CCURPMFC_ADC_PIO_CHANNEL: Perform .channel registers programmed I/O reads.

CCURPMFC_ADC_PIO_FIFO: Perform FIFO reads using programmed I/O.

2.1.5 write(2) system call

This system call currently supports DAC programmed I/O writes of channel registers and FIFO. The option selected is determined by the *ccurPMFC_DAC_Set_Driver_Write_Mode()* call.

CCURPMFC_DAC_PIO_CHANNEL: Perform .channel registers programmed I/O writes.

CCURPMFC_DAC_PIO_FIFO: Perform FIFO writes using programmed I/O.

2.2 Application Program Interface (API) Access

The API is the recommended method of communicating with the board for most users.

There are a lot of APIs that have multiple arguments to set various parameters. If the user only wishes to change certain parameters for the call, they need to get the current settings via a query API, change only those parameters that need to be modified and then invoke a setting API to update these parameters (*i.e. read/modify/write*). This is a two API call operation.

A nice feature has been implemented in these APIs to simplify the user programming by having a common parameter `CCURPMFC_DO_NOT_CHANGE` which is a `#define`, that can be used for a lot of these calls. Arguments with this parameter will therefore cause the API to perform the read/modify/write operation instead of the user performing the same function with two API calls. The drawback to this approach is that some compilers will complain about the use of this parameter and therefore the user will require appropriate casting to get rid of warnings/errors.

The following are a list of calls that are available.

```
ccurPMFC_Abort_DMA()
ccurPMFC_ADC_Activate()
ccurPMFC_ADC_Get_CSR()
ccurPMFC_ADC_Get_Driver_Read_Mode()
ccurPMFC_ADC_Get_Fifo_Channel_Select()
ccurPMFC_ADC_Get_Fifo_Info()
ccurPMFC_ADC_Get_Fifo_Threshold()
ccurPMFC_ADC_Get_Negative_Cal()
ccurPMFC_ADC_Get_Offset_Cal()
ccurPMFC_ADC_Get_Positive_Cal()
ccurPMFC_ADC_Perform_Auto_Calibration()
ccurPMFC_ADC_Perform_External_Negative_Calibration()
ccurPMFC_ADC_Perform_External_Offset_Calibration()
ccurPMFC_ADC_Perform_External_Positive_Calibration()
ccurPMFC_ADC_Perform_Negative_Calibration()
ccurPMFC_ADC_Perform_Offset_Calibration()
ccurPMFC_ADC_Perform_Positive_Calibration()
ccurPMFC_ADC_Read_Channels()
ccurPMFC_ADC_Read_Channels_Calibration()
ccurPMFC_ADC_Reset_Fifo()
ccurPMFC_ADC_Set_CSR()
ccurPMFC_ADC_Set_Driver_Read_Mode()
ccurPMFC_ADC_Set_Fifo_Channel_Select()
ccurPMFC_ADC_Set_Fifo_Threshold()
ccurPMFC_ADC_Set_Negative_Cal()
ccurPMFC_ADC_Set_Offset_Cal()
ccurPMFC_ADC_Set_Positive_Cal()
ccurPMFC_ADC_Write_Channels_Calibration()
ccurPMFC_Add_Irq()
ccurPMFC_BoardExpirationTimeRemaining()
ccurPMFC_Clear_Driver_Error()
ccurPMFC_Clear_Lib_Error()
ccurPMFC_Clock_Generator_Soft_Reset()
ccurPMFC_Clock_Get_Generator_CSR()
ccurPMFC_Clock_Get_Generator_Info()
ccurPMFC_Clock_Get_Generator_Input_Clock_Enable()
ccurPMFC_Clock_Get_Generator_Input_Clock_Select()
ccurPMFC_Clock_Get_Generator_Input_Clock_Status()
ccurPMFC_Clock_Get_Generator_M_Divider()
```

```

ccurPMFC_Clock_Get_Generator_N_Divider()
ccurPMFC_Clock_Get_Generator_Output_Config()
ccurPMFC_Clock_Get_Generator_Output_Format()
ccurPMFC_Clock_Get_Generator_Output_Mode()
ccurPMFC_Clock_Get_Generator_Output_Mux()
ccurPMFC_Clock_Get_Generator_P_Divider()
ccurPMFC_Clock_Get_Generator_P_Divider_Enable()
ccurPMFC_Clock_Get_Generator_R_Divider()
ccurPMFC_Clock_Get_Generator_Revision()
ccurPMFC_Clock_Get_Generator_Value()
ccurPMFC_Clock_Get_Generator_Voltage_Select()
ccurPMFC_Clock_Get_Generator_Zero_Delay()
ccurPMFC_ReturnOutputFrequency()
ccurPMFC_Clock_Set_Generator_CSR()
ccurPMFC_Clock_Set_Generator_Input_Clock_Enable()
ccurPMFC_Clock_Set_Generator_Input_Clock_Select()
ccurPMFC_Clock_Set_Generator_M_Divider()
ccurPMFC_Clock_Set_Generator_N_Divider()
ccurPMFC_Clock_Set_Generator_Output_Config()
ccurPMFC_Clock_Set_Generator_Output_Format()
ccurPMFC_Clock_Set_Generator_Output_Mode()
ccurPMFC_Clock_Set_Generator_Output_Mux()
ccurPMFC_Clock_Set_Generator_P_Divider()
ccurPMFC_Clock_Set_Generator_P_Divider_Enable()
ccurPMFC_Clock_Set_Generator_R_Divider()
ccurPMFC_Clock_Set_Generator_Value()
ccurPMFC_Clock_Set_Generator_Voltage_Select()
ccurPMFC_Clock_Set_Generator_Zero_Delay()
ccurPMFC_Close()
ccurPMFC_Compute_All_Output_Clocks()
ccurPMFC_Convert_Physmem2avmm_Address()
ccurPMFC_Create_UserDioCosInterruptHandler()
ccurPMFC_Create_UserProcess()
ccurPMFC_DAC_Activate()
ccurPMFC_DAC_Get_CSR()
ccurPMFC_DAC_Get_Driver_Write_Mode()
ccurPMFC_DAC_Get_Fifo_Channel_Select()
ccurPMFC_DAC_Get_Fifo_Info()
ccurPMFC_DAC_Get_Fifo_Threshold()
ccurPMFC_DAC_Get_Fifo_Write_Count()
ccurPMFC_DAC_Get_Gain_Cal()
ccurPMFC_DAC_Get_Offset_Cal()
ccurPMFC_DAC_Get_Update_Source_Select()
ccurPMFC_DAC_Perform_Auto_Calibration()
ccurPMFC_DAC_Perform_Gain_Calibration()
ccurPMFC_DAC_Perform_Offset_Calibration()
ccurPMFC_DAC_Read_Channels_Calibration()
ccurPMFC_DAC_ReadBack_Channels()
ccurPMFC_DAC_Read_Channels()
ccurPMFC_DAC_Reset_Fifo()
ccurPMFC_DAC_Set_CSR()
ccurPMFC_DAC_Set_Driver_Write_Mode()
ccurPMFC_DAC_Set_Fifo_Channel_Select()
ccurPMFC_DAC_Set_Fifo_Threshold()
ccurPMFC_DAC_Set_Fifo_Write_Count()
ccurPMFC_DAC_Set_Gain_Cal()
ccurPMFC_DAC_Set_Offset_Cal()

```

```

ccurPMFC_DAC_Set_Update_Source_Select()
ccurPMFC_DAC_Wait_For_Channel_Idle()
ccurPMFC_DAC_Wait_For_Fifo_To_Drain()
ccurPMFC_DAC_Write_Channels()
ccurPMFC_DataToVolts()
ccurPMFC_Destroy_AllUserProcess()
ccurPMFC_Destroy_UserDioCosInterruptHandler()
ccurPMFC_Destroy_UserProcess()
ccurPMFC_DIO_Activate()
ccurPMFC_DIO_Get_Channels_Polarity()
ccurPMFC_DIO_Get_COS_Channels_Edge_Sense()
ccurPMFC_DIO_Get_COS_Channels_Enable()
ccurPMFC_DIO_Get_COS_Channels_Mode()
ccurPMFC_DIO_Get_COS_Channels_Overflow()
ccurPMFC_DIO_Get_COS_Channels_Status()
ccurPMFC_DIO_Get_Input_Channels_Filter()
ccurPMFC_DIO_Get_Input_Snapshot()
ccurPMFC_DIO_Get_Mode()
ccurPMFC_DIO_Get_Output_Sync()
ccurPMFC_DIO_Get_Ports_Direction()
ccurPMFC_DIO_Read_Custom_Channel_Registers()
ccurPMFC_DIO_Read_Input_Channel_Registers()
ccurPMFC_DIO_Read_Output_Channel_Registers()
ccurPMFC_DIO_Set_Channels_Polarity()
ccurPMFC_DIO_Set_COS_Channels_Edge_Sense()
ccurPMFC_DIO_Set_COS_Channels_Enable()
ccurPMFC_DIO_Set_COS_Channels_Mode()
ccurPMFC_DIO_Set_Input_Channels_Filter()
ccurPMFC_DIO_Set_Input_Snapshot()
ccurPMFC_DIO_Set_Mode()
ccurPMFC_DIO_Set_Output_Sync()
ccurPMFC_DIO_Set_Ports_Direction()
ccurPMFC_DIO_Set_Ports_Direction_To_Input()
ccurPMFC_DIO_Set_Ports_Direction_To_Output()
ccurPMFC_DIO_Write_Output_Channel_Registers()
ccurPMFC_DIO_Write_Output_Channel_High_Registers()
ccurPMFC_DIO_Write_Output_Channel_Low_Registers()
ccurPMFC_Disable_Pci_Interrupts()
ccurPMFC_DMA_Configure()
ccurPMFC_DMA_Fire()
ccurPMFC_Enable_Pci_Interrupts()
ccurPMFC_Fast_Memcpy()
ccurPMFC_Fast_Memcpy_Unlocked()
ccurPMFC_Fast_Memcpy_Unlocked_FIFO()
ccurPMFC_Fraction_To_Hex()
ccurPMFC_Get_All_Boards_Driver_Info()
ccurPMFC_Get_Board_CSR()
ccurPMFC_Get_Board_Info()
ccurPMFC_Get_Calibration_CSR()
ccurPMFC_Get_Driver_Error()
ccurPMFC_Get_Driver_Info()
ccurPMFC_Get_Interrupt_Status()
ccurPMFC_Get_Interrupt_Timeout_Seconds()
ccurPMFC_Get_Lib_Error()
ccurPMFC_Get_Library_Info()
ccurPMFC_Get_Mapped_Config_Ptr()
ccurPMFC_Get_Mapped_Driver_Library_Ptr()

```



```

ccurPMFC_Get_Mapped_Local_Ptr()
ccurPMFC_Get_Open_File_Descriptor()
ccurPMFC_Get_Physical_Memory()
ccurPMFC_Get_RunCount_UserProcess()
ccurPMFC_Get_TestBus_Control()
ccurPMFC_Get_Value()
ccurPMFC_Hex_To_Fraction()
ccurPMFC_Identify_Board()
ccurPMFC_Initialize_Board()
ccurPMFC_IpCore_COS_Activate()
ccurPMFC_IpCore_COS_Configure()
ccurPMFC_IpCore_COS_Decode_Timestamp()
ccurPMFC_IpCore_COS_Get_Info()
ccurPMFC_IpCore_COS_Read()
ccurPMFC_IpCore_COS_Start_Stop()
ccurPMFC_IpCore_Get_Info()
ccurPMFC_IpCore_Get_Mapped_Ptr()
ccurPMFC_MMap_Physical_Memory()
ccurPMFC_MsgDma_Configure_Descriptor()
ccurPMFC_MsgDma_Configure_Single()
ccurPMFC_MsgDma_Fire()
ccurPMFC_MsgDma_Fire_Single()
ccurPMFC_MsgDma_Free_Descriptor()
ccurPMFC_MsgDma_Get_Descriptor()
ccurPMFC_MsgDma_Get_Dispatcher_CSR()
ccurPMFC_MsgDma_Get_Prefetcher_CSR()
ccurPMFC_MsgDma_Release()
ccurPMFC_MsgDma_Sieze()
ccurPMFC_MsgDma_Setup()
ccurPMFC_Munmap_Physical_Memory()
ccurPMFC_NanoDelay()
ccurPMFC_Open()
ccurPMFC_Pause_UserProcess()
ccurPMFC_Program_All_Output_Clocks()
ccurPMFC_Read()
ccurPMFC_Reload_Firmware()
ccurPMFC_Remove_Irq()
ccurPMFC_Reset_Board()
ccurPMFC_Reset_Clock()
ccurPMFC_Resume_UserProcess()
ccurPMFC_Return_Board_Info_Description()
ccurPMFC_SDRAM_Activate()
ccurPMFC_SDRAM_Get_CSR()
ccurPMFC_SDRAM_Read()
ccurPMFC_SDRAM_Set_CSR()
ccurPMFC_SDRAM_Write()
ccurPMFC_Set_Board_CSR()
ccurPMFC_Set_Calibration_CSR()
ccurPMFC_Set_Interrupt_Status()
ccurPMFC_Set_Interrupt_Timeout_Seconds()
ccurPMFC_Set_TestBus_Control()
ccurPMFC_Set_Value()
ccurPMFC_SPROM_Read()
ccurPMFC_SPROM_Read_Item()
ccurPMFC_SPROM_Write()
ccurPMFC_SPROM_Write_Item()
ccurPMFC_SPROM_Write_Override()

```

```
ccurPMFC_Transfer_Data()  
ccurPMFC_Update_Clock_Generator_Divider()  
ccurPMFC_UserProcess_Command()  
ccurPMFC_VoltsToData()  
ccurPMFC_Wait_For_Interrupt()  
ccurPMFC_Write()
```

2.2.1 ccurPMFC_Abort_DMA()

This call will abort any DMA operation that is in progress. Normally, the user should not use this call unless they are providing their own DMA handling.

```

/*****
  _ccurpmfc_lib_error_number_t ccurPMFC_Abort_DMA(void *Handle)

Description: Abort any DMA in progress

Input:   void *Handle           (Handle pointer)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
         # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
         # CCURPMFC_LIB_IOCTL_FAILED      (driver ioctl call failed)
*****/
```

2.2.2 ccurPMFC_ADC_Activate()

This call must be the first call to activate the ADC. Without activation, all other calls will fail. The user can also use this call to return the current state of the ADC without any change.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_ADC_Activate (void *Handle,
                        _ccurpmfc_adc_all_enable_t activate,
                        _ccurpmfc_adc_all_enable_t *current_state)

Description: Activate/DeActivate ADC module

Input:   void *Handle           (Handle pointer)
         _ccurpmfc_adc_all_enable_t activate (activate/deactivate)
         # CCURPMFC_ADC_ALL_DISABLE
         # CCURPMFC_ADC_ALL_ENABLE
         # CCURPMFC_ADC_ALL_DO_NOT_CHANGE

Output:  _ccurpmfc_adc_all_enable_t *current_state (active/deactive)
         # CCURPMFC_ADC_ALL_DISABLE
         # CCURPMFC_ADC_ALL_ENABLE

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
         # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
*****/
```

2.2.3 ccurPMFC_ADC_Get_CSR()

This call returns information from the ADC registers for the selected channel group.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_ADC_Get_CSR (void *Handle,
                       _ccurpmfc_adc_mask_t adc_mask,
                       ccurpmfc_adc_csr_t *adc_csr)

Description: Get ADC Control and Status information

Input:   void *Handle           (Handle pointer)
*****/
```

```

        _ccurpmfc_adc_mask_t                adc_mask (selected ADC mask)
        # CCURPMFC_ADC_MASK_0_7
        # CCURPMFC_ADC_MASK_8_15
        # CCURPMFC_ALL_ADC_MASK
Output:  ccurpmfc_adc_csr_t                *adc_csr (pointer to ADC csr)
        _ccurpmfc_adccsr_update_clock_t    adc_update_clock;
        # CCURPMFC_ADC_UPDATE_CLOCK_NONE
        # CCURPMFC_ADC_UPDATE_CLOCK_0
        # CCURPMFC_ADC_UPDATE_CLOCK_1
        # CCURPMFC_ADC_UPDATE_CLOCK_2
        # CCURPMFC_ADC_UPDATE_CLOCK_3
        # CCURPMFC_ADC_UPDATE_CLOCK_4
        # CCURPMFC_ADC_UPDATE_CLOCK_5
        # CCURPMFC_ADC_UPDATE_CLOCK_6
        _ccurpmfc_adccsr_input_signal_t    adc_input_signal;
        # CCURPMFC_ADC_EXTERNAL_SIGNAL
        # CCURPMFC_ADC_CALIBRATION_BUS
        _ccurpmfc_adccsr_dataformat_t      adc_data_format;
        # CCURPMFC_ADC_OFFSET_BINARY
        # CCURPMFC_ADC_TWOS_COMPLEMENT
        _ccurpmfc_adccsr_input_range_t     adc_input_range;
        # CCURPMFC_ADC_BIPOLAR_10V
        # CCURPMFC_ADC_BIPOLAR_5V
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR            (successful)
        # CCURPMFC_LIB_BAD_HANDLE         (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN           (device not open)
        # CCURPMFC_LIB_INVALID_ARG        (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE  (ADC is not active)
*****/

```

2.2.4 ccurPMFC_ADC_Get_Driver_Read_Mode()

This call returns the current driver ADC read mode. When a *read(2)* system call is issued, it is this mode that determines the type of read being performed by the driver.

```

/*****
        _ccurpmfc_lib_error_number_t
        ccurPMFC_ADC_Get_Driver_Read_Mode (void                *Handle,
                                           _ccurpmfc_driver_ADC_read_mode_t *mode)

Description: Get current ADC read mode that will be selected by the 'read()'
            call

Input:      void                *Handle (Handle pointer)
Output:     _ccurpmfc_driver_ADC_read_mode_t *mode (select ADC read mode)
            # CCURPMFC_ADC_PIO_CHANNEL
            # CCURPMFC_ADC_PIO_FIFO

Return:     _ccurpmfc_lib_error_number_t
            # CCURPMFC_LIB_NO_ERROR            (successful)
            # CCURPMFC_LIB_BAD_HANDLE         (no/bad handler supplied)
            # CCURPMFC_LIB_NOT_OPEN           (library not open)
            # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
            # CCURPMFC_LIB_IOCTL_FAILED      (driver ioctl call failed)
            # CCURPMFC_LIB_INVALID_ARG        (invalid argument)
*****/

```

2.2.5 ccurPMFC_ADC_Get_Fifo_Channel_Select()

This call returns the current Fifo Channel selection mask. Only samples for these selected channels are placed in the fifo during sample collection.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Get_Fifo_Channel_Select(void          *Handle,
                                     _ccurpmfc_adc_channel_mask_t *adc_fifo_channel_select_mask)

Description: ADC Get Fifo Channel Selection

Input:   void          *Handle          (handle pointer)
Output:  _ccurpmfc_adc_channel_mask_t *adc_fifo_channel_select_mask
                                               (channel select mask)

# CCURPMFC_ADC_CHANNEL_MASK_0
# CCURPMFC_ADC_CHANNEL_MASK_1
# CCURPMFC_ADC_CHANNEL_MASK_2
# CCURPMFC_ADC_CHANNEL_MASK_3
# CCURPMFC_ADC_CHANNEL_MASK_4
# CCURPMFC_ADC_CHANNEL_MASK_5
# CCURPMFC_ADC_CHANNEL_MASK_6
# CCURPMFC_ADC_CHANNEL_MASK_7
# CCURPMFC_ADC_CHANNEL_MASK_8
# CCURPMFC_ADC_CHANNEL_MASK_9
# CCURPMFC_ADC_CHANNEL_MASK_10
# CCURPMFC_ADC_CHANNEL_MASK_11
# CCURPMFC_ADC_CHANNEL_MASK_12
# CCURPMFC_ADC_CHANNEL_MASK_13
# CCURPMFC_ADC_CHANNEL_MASK_14
# CCURPMFC_ADC_CHANNEL_MASK_15
# CCURPMFC_ALL_ADC_CHANNELS_MASK

Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR          (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
# CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
*****/

```

2.2.6 ccurPMFC_ADC_Get_Fifo_Info()

This call returns ADC FIFO information to the user.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Get_Fifo_Info(void          *Handle,
                               ccurpmfc_adc_fifo_info_t *adc_fifo)

Description: Get ADC FIFO control and Status information

Input:   void          *Handle          (Handle pointer)
Output:  ccurpmfc_adc_fifo_info_t      *adc_fifo (pointer to ADC
                                               fifo struct)

_ccurpmfc_adc_fifo_reset_t      reset;
# CCURPMFC_ADC_FIFO_ACTIVE
# CCURPMFC_ADC_FIFO_RESET
_ccurpmfc_adc_fifo_overflow_t   overflow;
# CCURPMFC_ADC_FIFO_NO_OVERFLOW
# CCURPMFC_ADC_FIFO_OVERFLOW
_ccurpmfc_adc_fifo_underflow_t  underflow;
# CCURPMFC_ADC_FIFO_NO_UNDERFLOW
# CCURPMFC_ADC_FIFO_UNDERFLOW
_ccurpmfc_adc_fifo_full_t       full;
# CCURPMFC_ADC_FIFO_NOT_FULL
# CCURPMFC_ADC_FIFO_FULL
_ccurpmfc_adc_fifo_threshold_t  threshold_exceeded;

```

```

        # CCURPMFC_ADC_FIFO_THRESHOLD_NOT_EXCEEDED
        # CCURPMFC_ADC_FIFO_THRESHOLD_EXCEEDED
    _ccurpmfc_adc_fifo_empty_t        empty;
        # CCURPMFC_ADC_FIFO_NOT_EMPTY
        # CCURPMFC_ADC_FIFO_EMPTY
    uint                               data_counter;
    uint                               threshold;
    uint                               max_threshold;
    uint                               driver_threshold;
    _ccurpmfc_adc_channel_mask_t     channel_select_mask;
        # CCURPMFC_ADC_CHANNEL_MASK_0
        # CCURPMFC_ADC_CHANNEL_MASK_1
        # CCURPMFC_ADC_CHANNEL_MASK_2
        # CCURPMFC_ADC_CHANNEL_MASK_3
        # CCURPMFC_ADC_CHANNEL_MASK_4
        # CCURPMFC_ADC_CHANNEL_MASK_5
        # CCURPMFC_ADC_CHANNEL_MASK_6
        # CCURPMFC_ADC_CHANNEL_MASK_7
        # CCURPMFC_ADC_CHANNEL_MASK_8
        # CCURPMFC_ADC_CHANNEL_MASK_9
        # CCURPMFC_ADC_CHANNEL_MASK_10
        # CCURPMFC_ADC_CHANNEL_MASK_11
        # CCURPMFC_ADC_CHANNEL_MASK_12
        # CCURPMFC_ADC_CHANNEL_MASK_13
        # CCURPMFC_ADC_CHANNEL_MASK_14
        # CCURPMFC_ADC_CHANNEL_MASK_15
        # CCURPMFC_ALL_ADC_CHANNELS_MASK
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
    *****/

```

2.2.7 ccurPMFC_ADC_Get_Fifo_Threshold()

This call returns the ADC Fifo threshold information.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_ADC_Get_Fifo_Threshold(void *Handle,
                                    uint *adc_threshold)

```

Description: ADC Get Fifo Threshold

```

Input:   void           *Handle           (handle pointer)
Output:  uint           *adc_threshold    (ADC fifo threshold)
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
    *****/

```

2.2.8 ccurPMFC_ADC_Get_Negative_Cal()

This call returns the ADC negative calibration information for all the channels.

```

/*****

```

```

_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Get_Negative_Cal(void          *Handle,
                              ccurpmfc_adc_cal_t *cal)

```

Description: Get the ADC Negative Calibration data.

```

Input:  void          *Handle (handle pointer)
Output: ccurpmfc_adc_cal_t *cal (pointer to board cal)
        uint    Raw[CCURPMFC_MAX_ADC_CHANNELS];
        double  Float[CCURPMFC_MAX_ADC_CHANNELS];
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)

```

*****/

2.2.9 ccurPMFC_ADC_Get_Offset_Cal()

This call returns the ADC offset calibration information for all the channels.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Get_Offset_Cal(void          *Handle,
                              ccurpmfc_adc_cal_t *cal)

```

Description: Get the ADC Offset Calibration data.

```

Input:  void          *Handle (handle pointer)
Output: ccurpmfc_adc_cal_t *cal (pointer to board cal)
        uint    Raw[CCURPMFC_MAX_ADC_CHANNELS];
        double  Float[CCURPMFC_MAX_ADC_CHANNELS];
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)

```

*****/

2.2.10 ccurPMFC_ADC_Get_Positive_Cal()

This call returns the ADC positive calibration information for all the channels.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Get_Positive_Cal(void          *Handle,
                              ccurpmfc_adc_cal_t *cal)

```

Description: Get the ADC Positive Calibration data.

```

Input:  void          *Handle (handle pointer)
Output: ccurpmfc_adc_cal_t *cal (pointer to board cal)
        uint    Raw[CCURPMFC_MAX_ADC_CHANNELS];
        double  Float[CCURPMFC_MAX_ADC_CHANNELS];
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)

```

```

        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE  (ADC is not active)
    *****/

```

2.2.11 ccurPMFC_ADC_Perform_Auto_Calibration()

This single call performs a full ADC calibration of all the channels using the internal reference voltages.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_ADC_Perform_Auto_Calibration(void *Handle)

    Description: Perform ADC Auto Calibration

    Input:      void    *Handle                (handle pointer)
    Output:     none
    Return:     _ccurpmfc_lib_error_number_t
                # CCURPMFC_LIB_NO_ERROR        (successful)
                # CCURPMFC_LIB_BAD_HANDLE     (no/bad handler supplied)
                # CCURPMFC_LIB_NOT_OPEN      (library not open)
                # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
                # CCURPMFC_LIB_NO_RESOURCE   (no free PLL available)
                # CCURPMFC_LIB_IO_ERROR      (read error)
                # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
                # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
    *****/

```

2.2.12 ccurPMFC_ADC_Perform_External_Negative_Calibration()

Use this call to perform an external negative calibration. Prior to calling this function, the ADC inputs must be provided with a negative signal close to -10 Volts, otherwise this call will fail. Additionally, the user can specify a range of channels.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_ADC_Perform_External_Negative_Calibration(void *Handle,
                                                       _ccurpmfc_adc_channel_t chan_start,
                                                       _ccurpmfc_adc_channel_t chan_end,
                                                       double ReferenceVoltage)

    Description: Perform ADC External Negative Calibration

    Input:      void    *Handle                (handle pointer)
                _ccurpmfc_adc_channel_t chan_start (start channel)
                _ccurpmfc_adc_channel_t chan_end   (end channel)
                double   ReferenceVoltage         (Reference Voltage)

    Output:     none
    Return:     _ccurpmfc_lib_error_number_t
                # CCURPMFC_LIB_NO_ERROR        (successful)
                # CCURPMFC_LIB_BAD_HANDLE     (no/bad handler supplied)
                # CCURPMFC_LIB_NOT_OPEN      (library not open)
                # CCURPMFC_LIB_INVALID_ARG   (invalid argument)
                # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
                # CCURPMFC_LIB_NO_RESOURCE   (no free PLL available)
                # CCURPMFC_LIB_IO_ERROR      (read error)
                # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
                # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
    *****/

```

2.2.13 ccurPMFC_ADC_Perform_External_Offset_Calibration()

Use this call to perform an external offset calibration. Prior to calling this function, the ADC inputs must be provided with an offset signal close to 0 Volts, otherwise this call will fail. Additionally, the user can specify a

range of channels. Once this call is executed, the user will need to perform external negative and external positive calibrations as this call resets these gains to 1.0 prior to calibration.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Perform_External_Offset_Calibration(void          *Handle,
                                                _ccurpmfc_adc_channel_t chan_start,
                                                _ccurpmfc_adc_channel_t chan_end)

Description: Perform ADC External Offset Calibration

Input:   void          *Handle          (handle pointer)
         _ccurpmfc_adc_channel_t chan_start (start channel)
         _ccurpmfc_adc_channel_t chan_end (end channel)

Output:  none

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR          (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN         (library not open)
         # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
         # CCURPMFC_LIB_NO_RESOURCE      (no free PLL available)
         # CCURPMFC_LIB_IO_ERROR         (read error)
         # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
         # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.14 ccurPMFC_ADC_Perform_External_Positive_Calibration()

Use this call to perform an external positive calibration. Prior to calling this function, the ADC inputs must be provided with a positive signal close to +10 Volts, otherwise this call will fail. Additionally, the user can specify a range of channels.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Perform_External_Positive_Calibration(void          *Handle,
                                                _ccurpmfc_adc_channel_t chan_start,
                                                _ccurpmfc_adc_channel_t chan_end,
                                                double              ReferenceVoltage)

Description: Perform ADC External Positive Calibration

Input:   void          *Handle          (handle pointer)
         _ccurpmfc_adc_channel_t chan_start (start channel)
         _ccurpmfc_adc_channel_t chan_end (end channel)
         double          ReferenceVoltage (Reference Voltage)

Output:  none

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR          (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN         (library not open)
         # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
         # CCURPMFC_LIB_NO_RESOURCE      (no free PLL available)
         # CCURPMFC_LIB_IO_ERROR         (read error)
         # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
         # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.15 ccurPMFC_ADC_Perform_Negative_Calibration()

This call performs a negative calibration using the internal reference voltage.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_ADC_Perform_Negative_Calibration(void *Handle)

  Description: Perform ADC Negative Calibration

  Input:   void   *Handle           (handle pointer)
  Output:  none
  Return:  _ccurpmfc_lib_error_number_t
          # CCURPMFC_LIB_NO_ERROR           (successful)
          # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
          # CCURPMFC_LIB_NOT_OPEN          (library not open)
          # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
          # CCURPMFC_LIB_NO_RESOURCE       (no free PLL available)
          # CCURPMFC_LIB_IO_ERROR          (read error)
          # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
          # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.16 ccurPMFC_ADC_Perform_Offset_Calibration()

This call performs an offset calibration using the internal reference voltage. Once this call is executed, the user will need to perform negative and positive calibrations as this call resets these gains to 1.0 prior to calibration.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_ADC_Perform_Offset_Calibration(void *Handle)

  Description: Perform ADC Offset Calibration

  Input:   void   *Handle           (handle pointer)
  Output:  none
  Return:  _ccurpmfc_lib_error_number_t
          # CCURPMFC_LIB_NO_ERROR           (successful)
          # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
          # CCURPMFC_LIB_NOT_OPEN          (library not open)
          # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
          # CCURPMFC_LIB_NO_RESOURCE       (no free PLL available)
          # CCURPMFC_LIB_IO_ERROR          (read error)
          # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
          # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.17 ccurPMFC_ADC_Perform_Positive_Calibration()

This call performs a positive calibration using the internal reference voltage.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_ADC_Perform_Positive_Calibration(void *Handle)

  Description: Perform ADC Positive Calibration

  Input:   void   *Handle           (handle pointer)
  Output:  none
  Return:  _ccurpmfc_lib_error_number_t
          # CCURPMFC_LIB_NO_ERROR           (successful)
          # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
          # CCURPMFC_LIB_NOT_OPEN          (library not open)
          # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
          # CCURPMFC_LIB_NO_RESOURCE       (no free PLL available)
          # CCURPMFC_LIB_IO_ERROR          (read error)
*****/

```

```

# CCURPMFC_LIB_ADC_IS_NOT_ACTIVE      (ADC is not active)
# CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE    (Clock is not active)
*****/

```

2.2.18 ccurPMFC_ADC_Read_Channels ()

This call provides the user an easy method of reading the ADC channels. User can supply a channel mask. If pointer to *adc_csr* is NULL, then the routine itself computes the current ADC configuration. For performance, the user should get the current ADC configuration using the *ccurPMFC_ADC_Get_CSR()* call to get the current settings and pass it to this routine. Hence, if the configuration is not changed, the user can continuously invoke *ccurPMFC_ADC_Read_Channels()* routine without incurring the additional overhead of routine calling the *ccurPMFC_ADC_Get_CSR()* call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Read_Channels(void          *Handle,
                                _ccurpmfc_adc_channel_mask_t ChanMask,
                                _ccurpmfc_adc_csr_t          *adc_csr,
                                ccurpmfc_adc_volts_t          *adc_volts)

```

Description: Read ADC Channels

```

Input:  void          *Handle      (Handle pointer)
        _ccurpmfc_adc_channel_mask_t ChanMask (specify channel mask)
        # CCURPMFC_ADC_CHANNEL_MASK_0
        # CCURPMFC_ADC_CHANNEL_MASK_1
        # CCURPMFC_ADC_CHANNEL_MASK_2
        # CCURPMFC_ADC_CHANNEL_MASK_3
        # CCURPMFC_ADC_CHANNEL_MASK_4
        # CCURPMFC_ADC_CHANNEL_MASK_5
        # CCURPMFC_ADC_CHANNEL_MASK_6
        # CCURPMFC_ADC_CHANNEL_MASK_7
        # CCURPMFC_ADC_CHANNEL_MASK_8
        # CCURPMFC_ADC_CHANNEL_MASK_9
        # CCURPMFC_ADC_CHANNEL_MASK_10
        # CCURPMFC_ADC_CHANNEL_MASK_11
        # CCURPMFC_ADC_CHANNEL_MASK_12
        # CCURPMFC_ADC_CHANNEL_MASK_13
        # CCURPMFC_ADC_CHANNEL_MASK_14
        # CCURPMFC_ADC_CHANNEL_MASK_15
        # CCURPMFC_ALL_ADC_CHANNELS_MASK
        _ccurpmfc_adc_csr_t          *adc_csr (pointer to ADC csr)
        _ccurpmfc_adccsr_update_clock_t  adc_update_clock
        # CCURPMFC_ADC_UPDATE_CLOCK_NONE
        # CCURPMFC_ADC_UPDATE_CLOCK_0
        # CCURPMFC_ADC_UPDATE_CLOCK_1
        # CCURPMFC_ADC_UPDATE_CLOCK_2
        # CCURPMFC_ADC_UPDATE_CLOCK_3
        # CCURPMFC_ADC_UPDATE_CLOCK_4
        # CCURPMFC_ADC_UPDATE_CLOCK_5
        # CCURPMFC_ADC_UPDATE_CLOCK_6
        _ccurpmfc_adccsr_input_signal_t  adc_input_signal
        # CCURPMFC_ADC_EXTERNAL_SIGNAL
        # CCURPMFC_ADC_CALIBRATION_BUS
        _ccurpmfc_adccsr_data_format_t  adc_data_format
        # CCURPMFC_ADC_OFFSET_BINARY
        # CCURPMFC_ADC_TWOS_COMPLEMENT
        _ccurpmfc_adccsr_input_range_t  adc_input_range
        # CCURPMFC_ADC_BIPOLAR_10V
        # CCURPMFC_ADC_BIPOLAR_5V
Output: ccurpmfc_adc_volts_t          *adc_volts (pointer to ADC volts)
        uint      Raw[CCURPMFC_MAX_ADC_CHANNELS];
        double    Float[CCURPMFC_MAX_ADC_CHANNELS];

```

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```

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (library not open)
         # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
         # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
*****/

```

2.2.19 ccurPMFC_ADC_Read_Channels_Calibration()

This routine reads the ADC channel calibration registers and dumps them to the user specified file. If the file name specified is NULL, then information is written to *stdout*.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Read_Channels_Calibration(void *Handle,
                                         char *filename)

Description: Read ADC Channels Calibration

Input:   void *Handle           (handle pointer)
Output:  char *filename         (pointer to filename)
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (library not open)
         # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
         # CCURPMFC_LIB_CANNOT_OPEN_FILE (cannot open calib. file)
         # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
*****/

```

2.2.20 ccurPMFC_ADC_Reset_Fifo()

This call provides the ability to reset the ADC Fifo to the power-on state. User can elect to activate the FIFO after a reset in order for data collection to resume immediately.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Reset_Fifo(void *Handle,
                         _ccurpmfc_adc_fifo_reset_t activate)

Description: ADC Reset Fifo

Input:   void *Handle           (handle pointer)
         _ccurpmfc_adc_fifo_reset_t activate (activate converter)
         # CCURPMFC_ADC_FIFO_ACTIVATE
         # CCURPMFC_ADC_FIFO_RESET

Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
         # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
         # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
*****/

```

2.2.21 ccurPMFC_ADC_Set_CSR()

This call sets the ADC control registers for the selected channel group.

```

/*****

```

```

_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Set_CSR (void          *Handle,
                        _ccurpmfc_adc_mask_t  adc_mask,
                        ccurpmfc_adc_csr_t    *adc_csr)

```

Description: Set ADC Control and Status information

```

Input:  void          *Handle (Handle pointer)
        _ccurpmfc_adc_mask_t  adc_mask (selected ADC mask)
        # CCURPMFC_ADC_MASK_0_7
        # CCURPMFC_ADC_MASK_8_15
        # CCURPMFC_ALL_ADC_MASK
        ccurpmfc_adc_csr_t    *adc_csr (pointer to ADC csr)
        _ccurpmfc_adccsr_update_clock_t  adc_update_clock;
        # CCURPMFC_ADC_UPDATE_CLOCK_NONE
        # CCURPMFC_ADC_UPDATE_CLOCK_0
        # CCURPMFC_ADC_UPDATE_CLOCK_1
        # CCURPMFC_ADC_UPDATE_CLOCK_2
        # CCURPMFC_ADC_UPDATE_CLOCK_3
        # CCURPMFC_ADC_UPDATE_CLOCK_4
        # CCURPMFC_ADC_UPDATE_CLOCK_5
        # CCURPMFC_ADC_UPDATE_CLOCK_6
        # CCURPMFC_ADC_UPDATE_CLOCK_DO_NOT_CHANGE
        _ccurpmfc_adccsr_input_signal_t  adc_input_signal;
        # CCURPMFC_ADC_EXTERNAL_SIGNAL
        # CCURPMFC_ADC_CALIBRATION_BUS
        # CCURPMFC_ADC_INPUT_SIGNAL_DO_NOT_CHANGE
        _ccurpmfc_adccsr_data_format_t  adc_data_format;
        # CCURPMFC_ADC_OFFSET_BINARY
        # CCURPMFC_ADC_TWOS_COMPLEMENT
        # CCURPMFC_ADC_DATA_FORMAT_DO_NOT_CHANGE
        _ccurpmfc_adccsr_input_range_t  adc_input_range;
        # CCURPMFC_ADC_BIPOLAR_10V
        # CCURPMFC_ADC_BIPOLAR_5V
        # CCURPMFC_ADC_INPUT_RANGE_DO_NOT_CHANGE

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (library not open)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not
        present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
*****

```

2.2.22 ccurPMFC_ADC_Set_Driver_Read_Mode()

This call sets the current driver ADC read mode. When a *read(2)* system call is issued, it is this mode that determines the type of read being performed by the driver. Refer to the *read(2)* system call under *Direct Driver Access* section for more information on the various modes.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Set_Driver_Read_Mode (void          *Handle,
                                   _ccurpmfc_driver_ADC_read_mode_t  mode)

```

Description: Select Driver ADC Read Mode

```

Input:  void          *Handle (Handle pointer)
        _ccurpmfc_driver_ADC_read_mode_t mode (select ADC read mode)

```

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```

        # CCURPMFC_ADC_PIO_CHANNEL
        # CCURPMFC_ADC_PIO_FIFO
Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN               (device not open)
        # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
*****/

```

2.2.23 ccurPMFC_ADC_Set_Fifo_Channel_Select()

This call allows the user to select a set of channels that need to be captured in the ADC Fifo.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_ADC_Set_Fifo_Channel_Select(void      *Handle,
                                          _ccurpmfc_adc_channel_mask_t
                                          adc_fifo_channel_select_mask)

Description: ADC Set Fifo Channel Selection

Input:  void      *Handle      (handle pointer)
        _ccurpmfc_adc_channel_mask_t adc_fifo_channel_select_mask
                                          (channel select mask)

        # CCURPMFC_ADC_CHANNEL_MASK_0
        # CCURPMFC_ADC_CHANNEL_MASK_1
        # CCURPMFC_ADC_CHANNEL_MASK_2
        # CCURPMFC_ADC_CHANNEL_MASK_3
        # CCURPMFC_ADC_CHANNEL_MASK_4
        # CCURPMFC_ADC_CHANNEL_MASK_5
        # CCURPMFC_ADC_CHANNEL_MASK_6
        # CCURPMFC_ADC_CHANNEL_MASK_7
        # CCURPMFC_ADC_CHANNEL_MASK_8
        # CCURPMFC_ADC_CHANNEL_MASK_9
        # CCURPMFC_ADC_CHANNEL_MASK_10
        # CCURPMFC_ADC_CHANNEL_MASK_11
        # CCURPMFC_ADC_CHANNEL_MASK_12
        # CCURPMFC_ADC_CHANNEL_MASK_13
        # CCURPMFC_ADC_CHANNEL_MASK_14
        # CCURPMFC_ADC_CHANNEL_MASK_15
        # CCURPMFC_ALL_ADC_CHANNELS_MASK

Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN               (device not open)
        # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE     (ADC is not active)
*****/

```

2.2.24 ccurPMFC_ADC_Set_Fifo_Threshold()

This call allows the user to set the ADC Fifo Threshold.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_ADC_Set_Fifo_Threshold(void *Handle,
                                       uint adc_threshold)

Description: ADC Set Fifo Threshold

```

```

Input:  void                *Handle        (handle pointer)
        uint                adc_threshold  (ADC fifo threshold)
Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
*****/

```

2.2.25 ccurPMFC_ADC_Set_Negative_Cal()

This call allows the user to set the negative calibration data for all the channels by supplying floating point *Float* gains to the call. Users can supply CCURPMFC_DO_NOT_CHANGE as a gain for any channel that should not be changed. Additionally, this call will return the *RAW* value of the gain supplied that is written to the board.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_ADC_Set_Negative_Cal(void                *Handle,
                                   ccurpmfc_adc_cal_t *cal)

Description: Set the ADC Negative Calibration data.

Input:  void                *Handle        (handle pointer)
        ccurpmfc_adc_cal_t  *cal          (pointer to board cal)
        uint                Raw[CCURPMFC_MAX_ADC_CHANNELS];
        double              Float[CCURPMFC_MAX_ADC_CHANNELS];

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (library not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_NO_RESOURCE       (no free PLL available)
        # CCURPMFC_LIB_IO_ERROR          (read error)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
*****/

```

2.2.26 ccurPMFC_ADC_Set_Offset_Cal()

This call allows the user to set the offset calibration data for all the channels by supplying floating point *Float* offset to the call. Users can supply CCURPMFC_DO_NOT_CHANGE as a gain for any channel that should not be changed. Additionally, this call will return the *Raw* value of the offset supplied that is written to the board.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_ADC_Set_Offset_Cal(void                *Handle,
                                   ccurpmfc_adc_cal_t *cal)

Description: Set the ADC Offset Calibration data.

Input:  void                *Handle        (handle pointer)
        ccurpmfc_adc_cal_t  *cal          (pointer to board cal)
        uint                Raw[CCURPMFC_MAX_ADC_CHANNELS];
        double              Float[CCURPMFC_MAX_ADC_CHANNELS];

Output: none
Return: _ccurpmfc_lib_error_number_t

```

```

# CCURPMFC_LIB_NO_ERROR                (successful)
# CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN                (library not open)
# CCURPMFC_LIB_INVALID_ARG            (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
# CCURPMFC_LIB_NO_RESOURCE            (no free PLL available)
# CCURPMFC_LIB_IO_ERROR                (read error)
# CCURPMFC_LIB_ADC_IS_NOT_ACTIVE      (ADC is not active)
*****/

```

2.2.27 ccurPMFC_ADC_Set_Positive_Cal()

This call allows the user to set the positive calibration data for all the channels by supplying floating point *Float* gains to the call. Users can supply CCURPMFC_DO_NOT_CHANGE as a gain for any channel that should not be changed. Additionally, this call will return the *Raw* value of the gain supplied that is written to the board.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Set_Positive_Cal(void          *Handle,
                                ccurpmfc_adc_cal_t *cal)

Description: Set the ADC Positive Calibration data.

Input:      void          *Handle      (handle pointer)
            ccurpmfc_adc_cal_t      *cal      (pointer to board cal)
            uint          Raw[CCURPMFC_MAX_ADC_CHANNELS];
            double        Float[CCURPMFC_MAX_ADC_CHANNELS];

Output:     none

Return:     _ccurpmfc_lib_error_number_t
            # CCURPMFC_LIB_NO_ERROR                (successful)
            # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
            # CCURPMFC_LIB_NOT_OPEN                (library not open)
            # CCURPMFC_LIB_INVALID_ARG            (invalid argument)
            # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
            # CCURPMFC_LIB_NO_RESOURCE            (no free PLL available)
            # CCURPMFC_LIB_IO_ERROR                (read error)
            # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE      (ADC is not active)
*****/

```

2.2.28 ccurPMFC_ADC_Write_Channels_Calibration()

This call allows the user to write the calibration registers from a user supplied calibration file.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_ADC_Write_Channels_Calibration(void *Handle,
                                           char *filename)

Description: Write Channels Calibration

Input:      void      *Handle      (handle pointer)
Output:     char      *filename    (pointer to filename)
Return:     _ccurpmfc_lib_error_number_t
            # CCURPMFC_LIB_NO_ERROR                (successful)
            # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
            # CCURPMFC_LIB_NOT_OPEN                (library not open)
            # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
            # CCURPMFC_LIB_CANNOT_OPEN_FILE      (cannot open calib. file)
            # CCURPMFC_LIB_INVALID_ARG            (invalid argument)
            # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE      (ADC is not active)
*****/

```


2.2.29 ccurPMFC_Add_Irq()

This call will add the driver interrupt handler if it has not been added. Normally, the user should not use this call unless they want to disable the interrupt handler and then re-enable it.

```

/*****
  int ccurPMFC_Add_Irq(void *Handle)

Description: By default, the driver assigns an interrupt handler to handle
             device interrupts. If the interrupt handler was removed using
             the ccurPMFC_Remove_Irq(), then this call adds it back.

Input:   void *Handle           (Handle pointer)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (library not open)
         # CCURPMFC_LIB_IOCTL_FAILED      (driver ioctl call failed)
*****/
```

2.2.30 ccurPMFC_BoardExpirationTimeRemaining()

This call provides useful information about the expiration date of the card if it has restricted licensing.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_BoardExpirationTimeRemaining(void *Handle,
                                       time_t *SecondsToExpire,
                                       ccurpmfc_date_string_t *GmtDateTimeString,
                                       ccurpmfc_date_string_t *LocalDateTimeString,
                                       _ccurpmfc_firmware_state *FirmwareState)

Description: Number of seconds to expire on a restricted card

Input:   void *Handle           (Handle pointer)
Output:  time_t *SecondsToExpire (seconds to expire)
         ccurpmfc_date_string_t *GmtDateTimeString (GMT date/time
                                                    string)
         char date[CCURPMFC_DATE_TIME_STRING_SIZE]
         ccurpmfc_date_string_t *LocalDateTimeString (Local date/time
                                                    string)
         char date[CCURPMFC_DATE_TIME_STRING_SIZE]
         _ccurpmfc_firmware_state *FirmwareState (Firmware State)
         # CCURPMFC_FIRMWARE_STATE_UNRESTRICTED
         # CCURPMFC_FIRMWARE_STATE_RESTRICTED
         # CCURPMFC_FIRMWARE_STATE_EXPIRED

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (library not open)
*****/
```

Mandatory arguments to the call are **Handle* and **SecondsToExpire*. Rest of the arguments are optional and be set to *NULL*.

SecondsToExpire* – If the board has an expiration date, this call will return the number of seconds this card can be used before it expires. *Once the card has expired, this call will not be reached as the device open will fail with an authorization error.***

If the board has no expiration date, this call will return zero as the number of seconds.

*GmtDateTimeString – If the board has an expiration date, this ascii GMT date representation of the expiration date is available in this variable if it is not NULL

*LocalDateTimeString – If the board has an expiration date, this ascii Local date representation of the expiration date is available in this variable if it is not NULL

*FirmwareState – This returns the current state of the installed firmware. I can be one of:

- CCURPMFC_FIRMWARE_STATE_UNRESTRICTED. This firmware has no restrictions.
- CCURPMFC_FIRMWARE_STATE_RESTRICTED. This firmware has restrictions. It is possible that and expiration date restriction is not present.
- CCURPMFC_FIRMWARE_STATE_EXPIRED. This firmware has restrictions. One of the restrictions is the expiration date which has expired. Typically, you may not see this state as the utility will fail during the open with an authentication error.

2.2.31 ccurPMFC_Clear_Driver_Error()

This call resets the last driver error that was maintained internally by the driver to *CCURPMFC_SUCCESS*.

```
/*
  _ccurpmfc_lib_error_number_t ccurPMFC_Clear_Driver_Error(void *Handle)

  Description: Clear any previously generated driver related error.

  Input:   void *Handle           (Handle pointer)
  Output:  none
  Return:  _ccurpmfc_lib_error_number_t
           # CCURPMFC_LIB_NO_ERROR           (successful)
           # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
           # CCURPMFC_LIB_NOT_OPEN         (device not open)
           # CCURPMFC_LIB_IOCTL_FAILED     (driver ioctl call failed)
*/
```

2.2.32 ccurPMFC_Clear_Lib_Error()

This call resets the last library error that was maintained internally by the API.

```
/*
  _ccurpmfc_lib_error_number_t ccurPMFC_Clear_Lib_Error(void *Handle)

  Description: Clear any previously generated library related error.

  Input:   void *Handle           (Handle pointer)
  Output:  none
  Return:  _ccurpmfc_lib_error_number_t
           # CCURPMFC_LIB_NO_ERROR           (successful)
           # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
           # CCURPMFC_LIB_NOT_OPEN         (device not open)
*/
```

2.2.33 ccurPMFC_Clock_Generator_Soft_Reset()

Perform a soft clock reset on all the output clocks.

```
/*
  _ccurpmfc_lib_error_number_t ccurPMFC_Clock_Generator_Soft_Reset(void *Handle)

  Description: Perform Soft Reset to Clock Generator
*/
```

```

Input:   void *Handle           (Handle pointer)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.34 ccurPMFC_Clock_Get_Generator_CSR()

Return the clock generator control and status register.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_CSR (void           *Handle,
                                ccurpmfc_clkgen_csr_t *CgCsr)

Description: Get Generator Control and Status information

Input:   void           *Handle   (Handle pointer)
Output:  ccurpmfc_clkgen_csr_t   *CgCsr (pointer to clock
                                        generator csr)

        _ccurpmfc_clkgen_interface_t   interface
        # CCURPMFC_CLOCK_GENERATOR_INTERFACE_IDLE
        # CCURPMFC_CLOCK_GENERATOR_INTERFACE_BUSY
        _ccurpmfc_clkgen_output_t      output
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_DISABLE
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_ENABLE
        _ccurpmfc_clkgen_state_t       state
        # CCURPMFC_CLOCK_GENERATOR_ACTIVE
        # CCURPMFC_CLOCK_GENERATOR_RESET

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler
                                        supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not
                                        present)
*****/

```

2.2.35 ccurPMFC_Clock_Get_Generator_Info()

This call returns the clock generator information for the selected output.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Info (void           *Handle,
                                   _ccurpmfc_clock_generator_output_t WhichOutput,
                                   ccurpmfc_clock_generator_info_t   *CgInfo)

Description: Get Clock Generator Information

Input:   void           *Handle   (Handle pointer)
        _ccurpmfc_clock_generator_output_t WhichOutput (select output)
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6

```

```

# CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
Output: ccurpmfc_clock_generator_info_t *CgInfo (pointer to clock
generator info)
    __u64 M_divider_num
    __u32 M_divider_den
    __u64 N_divider_num
    __u32 N_divider_den
    __u32 R_divider_value
    __u32 R_divider
    _ccurpmfc_cg_zero_delay_t ZeroDelay
    # CCURPMFC.CG_ZERO_DELAY_MODE
    # CCURPMFC.CG_NORMAL_MODE
    _ccurpmfc_cg_stat_ctrl_voltsel_t Voltage_select
    # CCURPMFC.CG_VOLTAGE_SELECT_1_8V
    # CCURPMFC.CG_VOLTAGE_SELECT_3_3V
    _ccurpmfc_cg_input_xaxb_extclk_sel_t Input_xaxb_selection
    # CCURPMFC.CG_INPUT_XAXB_USE_CRYSTAL
    # CCURPMFC.CG_INPUT_XAXB_USE_EXTCLK_SOURCE
    _ccurpmfc_cg_xaxb_power_down_t Input_xaxb_power
    # CCURPMFC.CG_XAXB_POWER_DOWN
    # CCURPMFC.CG_XAXB_DO_NOT_POWER_DOWN
    ccurpmfc_clkgen_csr_t Clkcsr
    _ccurpmfc_clkgen_interface_t interface
    # CCURPMFC.CLOCK_GENERATOR_INTERFACE_IDLE
    # CCURPMFC.CLOCK_GENERATOR_INTERFACE_BUSY
    _ccurpmfc_clkgen_output_t output
    # CCURPMFC.CLOCK_GENERATOR_OUTPUT_DISABLE
    # CCURPMFC.CLOCK_GENERATOR_OUTPUT_ENABLE
    _ccurpmfc_clkgen_state_t state
    # CCURPMFC.CLOCK_GENERATOR_ACTIVE
    # CCURPMFC.CLOCK_GENERATOR_RESET
    ccurpmfc_clkgen_output_config_t Config
    _ccurpmfc_cg_outcfg_force_rdiv2_t force_rdiv2
    # CCURPMFC.CG_OUTPUT_CONFIG_DONT_FORCE_RDIV2
    # CCURPMFC.CG_OUTPUT_CONFIG_FORCE_RDIV2
    _ccurpmfc_cg_outcfg_enable_t enable
    # CCURPMFC.CG_OUTPUT_CONFIG_DISABLE
    # CCURPMFC.CG_OUTPUT_CONFIG_ENABLE
    _ccurpmfc_cg_outcfg_shutdown_t shutdown
    # CCURPMFC.CG_OUTPUT_CONFIG_POWER_UP
    # CCURPMFC.CG_OUTPUT_CONFIG_SHUTDOWN
    ccurpmfc_clkgen_output_format_t Format
    _ccurpmfc_cg_outfmt_cmos_drive_t cmos_drive
    # CCURPMFC.CG_OUTPUT_FORMAT_CMOS_DRIVE_LVDS
    # CCURPMFC.CG_OUTPUT_FORMAT_CMOS_DRIVE_CMOS
    _ccurpmfc_cg_outfmt_disable_state_t disable_state
    # CCURPMFC.CG_OUTPUT_FORMAT_DISABLE_LOW
    # CCURPMFC.CG_OUTPUT_FORMAT_DISABLE_HIGH
    _ccurpmfc_cg_outfmt_sync_t sync
    # CCURPMFC.CG_OUTPUT_FORMAT_SYNC_DISABLE
    # CCURPMFC.CG_OUTPUT_FORMAT_SYNC_ENABLE
    _ccurpmfc_cg_outfmt_format_t format
    # CCURPMFC.CG_OUTPUT_FORMAT_FORMAT_LVDS
    # CCURPMFC.CG_OUTPUT_FORMAT_FORMAT_CMOS
    ccurpmfc_clkgen_output_mode_t Mode
    _ccurpmfc_cg_outmode_amplitude_t amplitude
    # CCURPMFC.CG_OUTPUT_AMPLITUDE_CMOS
    # CCURPMFC.CG_OUTPUT_AMPLITUDE_LVDS
    _ccurpmfc_cg_outmode_common_t common
    # CCURPMFC.CG_OUTPUT_COMMON_CMOS
    # CCURPMFC.CG_OUTPUT_COMMON_LVDS

```

```

# CCURPMFC_CG_OUTPUT_COMMON_LVPECL
ccurpmfc_clkgen_output_mux_t           Mux
  _ccurpmfc_cg_outmux_inversion_t      inversion
    # CCURPMFC_CG_OUTPUT_MUX_COMPLEMENTARY
    # CCURPMFC_CG_OUTPUT_MUX_IN_PHASE
    # CCURPMFC_CG_OUTPUT_MUX_INVERTED
    # CCURPMFC_CG_OUTPUT_MUX_OUT_OF_PHASE
  _ccurpmfc_cg_outmux_ndiv_select_t    ndiv_mux
    # CCURPMFC_CG_OUTPUT_MUX_NDIV_0
    # CCURPMFC_CG_OUTPUT_MUX_NDIV_1
    # CCURPMFC_CG_OUTPUT_MUX_NDIV_2
    # CCURPMFC_CG_OUTPUT_MUX_NDIV_3
    # CCURPMFC_CG_OUTPUT_MUX_NDIV_4
ccurpmfc_clkgen_input_clock_enable_t   Input_clock_enable
  _ccurpmfc_cg_input_clock_enable_t    input_0_clock
    # CCURPMFC_CG_INPUT_CLOCK_DISABLE
    # CCURPMFC_CG_INPUT_CLOCK_ENABLE
  _ccurpmfc_cg_input_clock_enable_t    input_1_clock
    # CCURPMFC_CG_INPUT_CLOCK_DISABLE
    # CCURPMFC_CG_INPUT_CLOCK_ENABLE
  _ccurpmfc_cg_input_clock_enable_t    input_2_clock
    # CCURPMFC_CG_INPUT_CLOCK_DISABLE
    # CCURPMFC_CG_INPUT_CLOCK_ENABLE
  _ccurpmfc_cg_input_clock_enable_t    input_fb_clock
    # CCURPMFC_CG_INPUT_CLOCK_DISABLE
    # CCURPMFC_CG_INPUT_CLOCK_ENABLE
ccurpmfc_clkgen_input_clock_select_t   Input_clock_select
  _ccurpmfc_cg_input_clock_select_control_t control
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_PIN_CONTROL
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_REG_CONTROL
  _ccurpmfc_cg_input_clock_select_register_t select
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN0
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN1
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN2
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_INXAXB
ccurpmfc_pdiv_all_info_t               Pdiv_info
  _u64                                  Pfb_divider
  ccurpmfc_pdiv_info_t                 P0
    _u64                                  Divider
    _ccurpmfc_cg_pdiv_enable_t           Enable
      # CCURPMFC_CG_PDIV_DISABLE
      # CCURPMFC_CG_PDIV_ENABLE
    _ccurpmfc_cg_pdiv_input_state_t      State
      # CCURPMFC_CG_PDIV_INPUT_UNUSED
      # CCURPMFC_CG_PDIV_INPUT_DISABLED
      # CCURPMFC_CG_PDIV_INPUT_SELECTED
ccurpmfc_pdiv_info_t                   P1
  _u64                                  Divider
  _ccurpmfc_cg_pdiv_enable_t           Enable
    # CCURPMFC_CG_PDIV_DISABLE
    # CCURPMFC_CG_PDIV_ENABLE
  _ccurpmfc_cg_pdiv_input_state_t      State
    # CCURPMFC_CG_PDIV_INPUT_UNUSED
    # CCURPMFC_CG_PDIV_INPUT_DISABLED
    # CCURPMFC_CG_PDIV_INPUT_SELECTED
ccurpmfc_pdiv_info_t                   P2
  _u64                                  Divider
  _ccurpmfc_cg_pdiv_enable_t           Enable
    # CCURPMFC_CG_PDIV_DISABLE
    # CCURPMFC_CG_PDIV_ENABLE
  _ccurpmfc_cg_pdiv_input_state_t      State
    # CCURPMFC_CG_PDIV_INPUT_UNUSED
    # CCURPMFC_CG_PDIV_INPUT_DISABLED

```

```

        # CCURPMFC_CG_PDIV_INPUT_SELECTED
ccurpmfc_pdiv_info_t          Pxab
        _u64                  Divider
        _ccurpmfc_cg_pdiv_enable_t      Enable
        # CCURPMFC_CG_PDIV_DISABLE
        # CCURPMFC_CG_PDIV_ENABLE
        _ccurpmfc_cg_pdiv_input_state_t      State
        # CCURPMFC_CG_PDIV_INPUT_UNUSED
        # CCURPMFC_CG_PDIV_INPUT_DISABLED
        # CCURPMFC_CG_PDIV_INPUT_SELECTED
int                            Which_Pdiv_Selected
int                            P_Divider
long double                    OutputClockFrequency;
        # <valid positive output clock frequency>
        # CCURPMFC_CLOCK_ERROR_INVALID_P_DIVIDER
        # CCURPMFC_CLOCK_ERROR_VCO_CLOCK_NOT_IN_RANGE
        # CCURPMFC_CLOCK_ERROR_N_DIVIDER_NOT_IN_RANGE
        # CCURPMFC_CLOCK_ERROR_P_DIVIDER_NOT_IN_RANGE
        # CCURPMFC_CLOCK_ERROR_R_DIVIDER_NOT_IN_RANGE
        # CCURPMFC_CLOCK_ERROR_INVALID_CLOCK_FREQUENCY
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR              (successful)
        # CCURPMFC_LIB_BAD_HANDLE            (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN              (device not open)
        # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION       (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE   (Clock is not active)
*****/

```

2.2.36 ccurPMFC_Clock_Get_Generator_Input_Clock_Enable()

This call returns the status of all the input clocks.

```

/*****
    _ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Input_Clock_Enable (void *Handle,
        ccurpmfc_clkgen_input_clock_enable_t *InputClockEnable)

Description: Return the Clock Generator Input Clock Enable

Input:  void *Handle (Handle pointer)
Output: ccurpmfc_clkgen_input_clock_enable_t *InputClockEnable (pointer to
        input clock enable)
        _ccurpmfc_cg_input_clock_enable_t input_0_clock
        # CCURPMFC_CG_INPUT_CLOCK_DISABLE
        # CCURPMFC_CG_INPUT_CLOCK_ENABLE
        _ccurpmfc_cg_input_clock_enable_t input_1_clock
        # CCURPMFC_CG_INPUT_CLOCK_DISABLE
        # CCURPMFC_CG_INPUT_CLOCK_ENABLE
        _ccurpmfc_cg_input_clock_enable_t input_2_clock
        # CCURPMFC_CG_INPUT_CLOCK_DISABLE
        # CCURPMFC_CG_INPUT_CLOCK_ENABLE
        _ccurpmfc_cg_input_clock_enable_t input_fb_clock
        # CCURPMFC_CG_INPUT_CLOCK_DISABLE
        # CCURPMFC_CG_INPUT_CLOCK_ENABLE
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR              (successful)
        # CCURPMFC_LIB_BAD_HANDLE            (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN              (device not open)
        # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION       (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE   (Clock is not active)
*****/

```

2.2.37 ccurPMFC_Clock_Get_Generator_Input_Clock_Select()

This call returns the input clock selection.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Input_Clock_Select (void *Handle,
                                                ccurpmfc_clkgen_input_clock_select_t *ClkSel)

Description: Get Input Clock Selection

Input:   void *Handle (Handle pointer)
Output:  ccurpmfc_clkgen_input_clock_select_t *ClkSel (pointer to
                                                input clock selection)

_ccurpmfc_cg_input_clock_select_control_t control;
# CCURPMFC_CG_INPUT_CLOCK_SELECT_PIN_CONTROL
# CCURPMFC_CG_INPUT_CLOCK_SELECT_REG_CONTROL
_ccurpmfc_cg_input_clock_select_register_t select;
# CCURPMFC_CG_INPUT_CLOCK_SELECT_IN0
# CCURPMFC_CG_INPUT_CLOCK_SELECT_IN1
# CCURPMFC_CG_INPUT_CLOCK_SELECT_IN2
# CCURPMFC_CG_INPUT_CLOCK_SELECT_INXAXB

Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region error)
# CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/
```

2.2.38 ccurPMFC_Clock_Get_Generator_Input_Clock_Status()

The call returns the input clock status.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Input_Clock_Status (void *Handle,
                                                ccurpmfc_clkgen_input_clock_status_t *ClkStatus)

Description: Get Input Clock Status

Input:   void *Handle (Handle pointer)
Output:  ccurpmfc_clkgen_input_clock_status_t *ClkStatus (pointer to input
                                                clock status)

_ccurpmfc_cg_calibration_status_t calstat
# CCURPMFC_CG_STATUS_DEVICE_IS_NOT_CALIBRATING
# CCURPMFC_CG_STATUS_DEVICE_IS_CALIBRATING
_ccurpmfc_cg_lol_pll_locked_t PLL_locked
# CCURPMFC_CG_STATUS_LOL_PLL_LOCKED
# CCURPMFC_CG_STATUS_LOL_PLL_NOT_LOCKED
_ccurpmfc_cg_smbus_timeout_error_t SMBUS_timeout
# CCURPMFC_CG_STATUS_LOL_SMBUS_NOT_TIMEDOUT
# CCURPMFC_CG_STATUS_LOL_SMBUS_TIMEDOUT
_ccurpmfc_cg_los_signal_present_t input_signal
# CCURPMFC_CG_STATUS_LOS_SIGNAL_PRESENT
# CCURPMFC_CG_STATUS_LOS_SIGNAL_NOT_PRESENT
_ccurpmfc_cg_los_alarm_t input_0_clock
# CCURPMFC_CG_LOS_INPUT_CLOCK_PRESENT
# CCURPMFC_CG_LOS_INPUT_CLOCK_NOT_PRESENT
_ccurpmfc_cg_los_alarm_t input_1_clock
# CCURPMFC_CG_LOS_INPUT_CLOCK_PRESENT
# CCURPMFC_CG_LOS_INPUT_CLOCK_NOT_PRESENT
*****/
```

```

    _ccurpmfc_cg_los_alarm_t          input_2_clock
    # CCURPMFC_CG_LOS_INPUT_CLOCK_PRESENT
    # CCURPMFC_CG_LOS_INPUT_CLOCK_NOT_PRESENT
    _ccurpmfc_cg_los_alarm_t          input_fb_clock
    # CCURPMFC_CG_LOS_INPUT_CLOCK_PRESENT
    # CCURPMFC_CG_LOS_INPUT_CLOCK_NOT_PRESENT
    _ccurpmfc_cg_losxaxb_signal_present_t  input_xaxb_clock
    # CCURPMFC_CG_LOS_INPUT_CLOCK_PRESENT
    # CCURPMFC_CG_LOS_INPUT_CLOCK_NOT_PRESENT
Return:  _ccurpmfc_lib_error_number_t
    # CCURPMFC_LIB_NO_ERROR              (successful)
    # CCURPMFC_LIB_BAD_HANDLE            (no/bad handler supplied)
    # CCURPMFC_LIB_NOT_OPEN              (device not open)
    # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
    # CCURPMFC_LIB_NO_LOCAL_REGION       (local region not present)
    # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE   (Clock is not active)
*****/

```

2.2.39 ccurPMFC_Clock_Get_Generator_M_Divider()

This call returns the M-Divider numerator, denominator and value.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Clock_Get_Generator_M_Divider (void          *Handle,
                                           __u64          *Numerator,
                                           __u32          *Denominator,
                                           long double *Value)

Description: Return Clock Generator M-Divider Numerator and Denominator

Input:  void          *Handle          (Handle pointer)
Output: __u64          *Numerator      (pointer to Numerator)
        __u32          *Denominator    (pointer to Denominator)
        long double    *Value          (pointer to Value)
Return: _ccurpmfc_lib_error_number_t
    # CCURPMFC_LIB_NO_ERROR              (successful)
    # CCURPMFC_LIB_BAD_HANDLE            (no/bad handler supplied)
    # CCURPMFC_LIB_NOT_OPEN              (device not open)
    # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
    # CCURPMFC_LIB_NO_LOCAL_REGION       (local region not present)
    # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE   (Clock is not active)
*****/

```

2.2.40 ccurPMFC_Clock_Get_Generator_N_Divider()

This call returns the N-Divider numerator, denominator and value for the selected divider.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Clock_Get_Generator_N_Divider (void          *Handle,
                                           _ccurpmfc_clock_generator_divider_t WhichDivider,
                                           __u64          *Numerator,
                                           __u32          *Denominator,
                                           long double    *Value)

Description: Return Clock Generator N-Divider Numerator and Denominator

Input:  void          *Handle          (Handle pointer)
        _ccurpmfc_clock_generator_divider_t WhichDivider (select divider)
    # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N0
    # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N1
    # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N2

```



```

        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N3
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N4
Output:  __u64                *Numerator    (pointer to Numerator)
        __u32                *Denominator  (pointer to Denominator)
        long double          *Value        (pointer to Value)
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR            (successful)
        # CCURPMFC_LIB_BAD_HANDLE         (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN           (device not open)
        # CCURPMFC_LIB_INVALID_ARG        (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.41 ccurPMFC_Clock_Get_Generator_Output_Config()

Return the clock generator output configuration for the selected output.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Clock_Get_Generator_Output_Config (void          *Handle,
                                                _ccurpmfc_clock_generator_output_t WhichOutput,
                                                ccurpmfc_clkgen_output_config_t *OutCfg)

Description: Return Clock Generator Output Configuration

Input:  void          *Handle    (Handle pointer)
        _ccurpmfc_clock_generator_output_t WhichOutput (select output)
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_9

Output: ccurpmfc_clkgen_output_config_t *OutCfg (pointer to output config)
        _ccurpmfc_cg_outcfg_force_rdiv2_t force_rdiv2
        # CCURPMFC_CG_OUTPUT_CONFIG_DONT_FORCE_RDIV2
        # CCURPMFC_CG_OUTPUT_CONFIG_FORCE_RDIV2
        _ccurpmfc_cg_outcfg_enable_t enable
        # CCURPMFC_CG_OUTPUT_CONFIG_DISABLE
        # CCURPMFC_CG_OUTPUT_CONFIG_ENABLE
        _ccurpmfc_cg_outcfg_shutdown_t shutdown
        # CCURPMFC_CG_OUTPUT_CONFIG_POWER_UP
        # CCURPMFC_CG_OUTPUT_CONFIG_SHUTDOWN

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR            (successful)
        # CCURPMFC_LIB_BAD_HANDLE         (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN           (device not open)
        # CCURPMFC_LIB_INVALID_ARG        (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.42 ccurPMFC_Clock_Get_Generator_Output_Format()

Return the clock generator output format for the selected output.

```

/*****
    _ccurpmfc_lib_error_number_t

```

```

ccurPMFC_Clock_Get_Generator_Output_Format (void *Handle,
                                             _ccurpmfc_clock_generator_output_t WhichOutput,
                                             ccurpmfc_clkgen_output_format_t *OutFmt)

```

Description: Return Clock Generator Output Format

```

Input: void *Handle (Handle pointer)
       _ccurpmfc_clock_generator_output_t WhichOutput (select output)
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_9

Output: ccurpmfc_clkgen_output_format_t *OutFmt (pointer to output format)
        _ccurpmfc_cg_outfmt_cmos_drive_t cmos_drive
        # CCURPMFC_CG_OUTPUT_FORMAT_CMOS_DRIVE_LVDS
        # CCURPMFC_CG_OUTPUT_FORMAT_CMOS_DRIVE_CMOS
        _ccurpmfc_cg_outfmt_disable_state_t disable_state
        # CCURPMFC_CG_OUTPUT_FORMAT_DISABLE_LOW
        # CCURPMFC_CG_OUTPUT_FORMAT_DISABLE_HIGH
        _ccurpmfc_cg_outfmt_sync_t sync
        # CCURPMFC_CG_OUTPUT_FORMAT_SYNC_DISABLE
        # CCURPMFC_CG_OUTPUT_FORMAT_SYNC_ENABLE
        _ccurpmfc_cg_outfmt_format_t format
        # CCURPMFC_CG_OUTPUT_FORMAT_FORMAT_LVDS
        # CCURPMFC_CG_OUTPUT_FORMAT_FORMAT_CMOS

Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)

```

2.2.43 ccurPMFC_Clock_Get_Generator_Output_Mode()

Return the clock generator output mode for the selected output.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Output_Mode (void *Handle,
                                             _ccurpmfc_clock_generator_output_t WhichOutput,
                                             ccurpmfc_clkgen_output_mode_t *OutMode)

```

Description: Return Clock Generator Output Mode

```

Input: void *Handle (Handle pointer)
       _ccurpmfc_clock_generator_output_t WhichOutput (select output)
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_8

```

```

    # CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
Output:  ccurpmfc_clkgen_output_mode_t      *OutMode (pointer to output
                                             amplitude/common mode)
        _ccurpmfc_cg_outmode_amplitude_t  amplitude
        # CCURPMFC_CG_OUTPUT_AMPLITUDE_CMOS
        # CCURPMFC_CG_OUTPUT_AMPLITUDE_LVDS
        _ccurpmfc_cg_outmode_common_t     common
        # CCURPMFC_CG_OUTPUT_COMMON_CMOS
        # CCURPMFC_CG_OUTPUT_COMMON_LVDS
        # CCURPMFC_CG_OUTPUT_COMMON_LVPECL
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.44 ccurPMFC_Clock_Get_Generator_Output_Mux()

Return the clock generator output mux for the selected output.

```

/*****
    _ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Output_Mux (void      *Handle,
                                           _ccurpmfc_clock_generator_output_t WhichOutput,
                                           ccurpmfc_clkgen_output_mux_t      *OutMux)

Description: Return Clock Generator Output Mux

Input:  void      *Handle      (Handle pointer)
        _ccurpmfc_clock_generator_output_t WhichOutput (select output)
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
Output:  ccurpmfc_clkgen_output_mux_t      *OutMux (pointer to output
                                             inversion/N-divider mux)
        _ccurpmfc_cg_outmux_inversion_t    inversion
        # CCURPMFC_CG_OUTPUT_MUX_COMPLEMENTARY
        # CCURPMFC_CG_OUTPUT_MUX_IN_PHASE
        # CCURPMFC_CG_OUTPUT_MUX_INVERTED
        # CCURPMFC_CG_OUTPUT_MUX_OUT_OF_PHASE
        _ccurpmfc_cg_outmux_ndiv_select_t  ndiv_mux
        # CCURPMFC_CG_OUTPUT_MUX_NDIV_0
        # CCURPMFC_CG_OUTPUT_MUX_NDIV_1
        # CCURPMFC_CG_OUTPUT_MUX_NDIV_2
        # CCURPMFC_CG_OUTPUT_MUX_NDIV_3
        # CCURPMFC_CG_OUTPUT_MUX_NDIV_4
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)

```

*****/

2.2.45 ccurPMFC_Clock_Get_Generator_P_Divider()

Return the clock generator P-Divider.

```
/*
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_P_Divider (void          *Handle,
                                         _ccurpmfc_clock_generator_divider_t WhichDivider,
                                         __u64          *Divider)

Description: Return Clock Generator P-Divider

Input:   void          *Handle      (Handle pointer)
         _ccurpmfc_clock_generator_divider_t WhichDivider (select divider)
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P0
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P1
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P2
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_PFB
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_PXAXB

Output:  __u64          *Divider    (pointer to
                                   Divider)

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR          (successful)
         # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN         (device not open)
         # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
         # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/
```

2.2.46 ccurPMFC_Clock_Get_Generator_P_Divider_Enable()

Return the clock generator P-Divider Enable state.

```
/*
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_P_Divider_Enable (void          *Handle,
                                                _ccurpmfc_clock_generator_divider_t WhichDivider,
                                                _ccurpmfc_cg_pdiv_enable_t      *Pdiv_Enable)

Description: Return Clock Generator P-Divider Enable

Input:   void          *Handle      (Handle pointer)
         _ccurpmfc_clock_generator_divider_t WhichDivider (select divider)
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P0
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P1
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P2
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_PXAXB

Output:  _ccurpmfc_cg_pdiv_enable_t *Pdiv_Enable (pointer to enable
                                                  flag)
         # CCURPMFC_CG_PDIV_DISABLE
         # CCURPMFC_CG_PDIV_ENABLE

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR          (successful)
         # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN         (device not open)
         # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
         # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/
```

2.2.47 ccurPMFC_Clock_Get_Generator_R_Divider()

Return the clock generator R-Divider for the selected divider.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Clock_Get_Generator_R_Divider (void                *Handle,
                                             _ccurpmfc_clock_generator_divider_t WhichDivider,
                                             __u32                *Divider)

Description: Return Clock Generator R-Divider

Input:   void                *Handle      (Handle pointer)
         _ccurpmfc_clock_generator_divider_t WhichDivider (select divider)
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R0
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R1
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R2
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R3
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R4
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R5
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R6
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R7
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R8
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R9

Output:  __u32                *Divider   (pointer to Divider)

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN         (device not open)
         # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
         # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.48 ccurPMFC_Clock_Get_Generator_Revision()

Return the clock generator revision information.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Clock_Get_Generator_Revision (void                *Handle,
                                             ccurpmfc_clock_revision_t *Revision)

Description: Return Clock Generator Revision

Input:   void                *Handle      (Handle pointer)
Output:  ccurpmfc_clock_revision_t *Revision (pointer to Divider)
         _ccurpmfc_cg_die_revision_t   DieRevision
         # CCURPMFC_CG_SILICON_REVISION_A0
         # CCURPMFC_CG_SILICON_REVISION_A1
         _convert_base_part_number_t   BasePartNumber;
         _convert_base_part_number_t
         u_short BPN
         u_char  NChar[2]
         _ccurpmfc_cg_clock_speed_grade_t ClockSpeedGrade;
         # CCURPMFC_CG_CLOCK_SPEED_GRADE_A
         # CCURPMFC_CG_CLOCK_SPEED_GRADE_B
         # CCURPMFC_CG_CLOCK_SPEED_GRADE_C
         # CCURPMFC_CG_CLOCK_SPEED_GRADE_D
         _ccurpmfc_cg_clock_revision_t  ClockRevision;
         # CCURPMFC_CG_CLOCK_REVISION_A
         # CCURPMFC_CG_CLOCK_REVISION_B
         # CCURPMFC_CG_CLOCK_REVISION_C
*****/

```

```

        # CCURPMFC_CG_CLOCK_REVISION_D
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.49 ccurPMFC_Clock_Get_Generator_Value()

This is a generic call that can return the value of a valid clock generator address.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Value (void      *Handle,
                                     int        address,
                                     u_char    *value)

```

Description: Return the value of the specified Clock Generator register.

```

Input:  void      *Handle      (Handle pointer)
        int        address     (clock gen address to display)
Output: u_char    *value;      (pointer to value)
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.50 ccurPMFC_Clock_Get_Generator_Voltage_Select()

Return the clock generator Voltage Selection.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Voltage_Select (void      *Handle,
                                              _ccurpmfc_cg_stat_ctrl_voltsel_t *VoltSel)

```

Description: Return the Clock Generator Voltage Selection

```

Input:  void      *Handle      (Handle pointer)
Output: _ccurpmfc_cg_stat_ctrl_voltsel_t *VoltSel (pointer to voltage select)
        # CCURPMFC_CG_VOLTAGE_SELECT_1_8V
        # CCURPMFC_CG_VOLTAGE_SELECT_3_3V
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.51 ccurPMFC_Clock_Get_Generator_Zero_Delay()

Return the clock generator Zero Delay status.

```

/*****

```

```

_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Get_Generator_Zero_Delay (void          *Handle,
                                          _ccurpmfc_cg_zero_delay_t *ZeroDelay)

Description: Return the Clock Generator Zero Delay setting.

Input:   void          *Handle      (Handle pointer)
Output:  _ccurpmfc_cg_zero_delay_t *ZeroDelay (pointer to zero delay)
        # CCURPMFC.CG_ZERO_DELAY_MODE
        # CCURPMFC.CG_NORMAL_MODE

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC.LIB_NO_ERROR          (successful)
        # CCURPMFC.LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC.LIB_NOT_OPEN        (device not open)
        # CCURPMFC.LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC.LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC.LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.52 ccurPMFC_Clock_ReturnOutputFrequency()

This call does not return the actual programmed frequency but instead returns the expected output frequency that would be generated if the specified user input parameters are supplied.

```

/*****
long double
ccurPMFC_Clock_ReturnOutputFrequency(double      InputClock,
                                       long double Mdiv_value,
                                       long double Ndiv_value,
                                       double      Pdiv_value,
                                       double      Rdiv_value)

Description: Return output frequency

Input:   double      InputClock (input clock frequency in Hz)
        long double Mdiv_value (M-Divider value)
        long double Ndiv_value (N-Divider value)
        double      Pdiv_value (P-Divider value)
        double      Rdiv_value (R-Divider value)

Output:  none
Return:  long double      returned frequency
*****/

```

2.2.53 ccurPMFC_Clock_Set_Generator_CSR()

This call sets the clock generator control and status register.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_CSR (void          *Handle,
                                   ccurpmfc_clkgen_csr_t *CgCsr)

Description: Set Clock Generator Control and Status information

Input:   void          *Handle      (Handle pointer)
        ccurpmfc_clkgen_csr_t *CgCsr (pointer to clock generator csr)
        _ccurpmfc_clkgen_output_t output
        # CCURPMFC.CLOCK_GENERATOR_OUTPUT_DISABLE
        # CCURPMFC.CLOCK_GENERATOR_OUTPUT_ENABLE
        # CCURPMFC.CLOCK_GENERATOR_OUTPUT_DO_NOT_CHANGE
        _ccurpmfc_clkgen_state_t state
        # CCURPMFC.CLOCK_GENERATOR_ACTIVE
        # CCURPMFC.CLOCK_GENERATOR_RESET

```

```

                                # CCURPMFC_CLOCK_GENERATOR_STATE_DO_NOT_CHANGE
Output: none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
         # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
*****/

```

2.2.54 ccurPMFC_Clock_Set_Generator_Input_Clock_Enable()

This call sets the input clock status for the input clocks.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Input_Clock_Enable (void      *Handle,
                                                  ccurpmfc_clkgen_input_clock_enable_t *InputClockEnable)

Description: Set Clock Generator Input Clock Enable

Input:      void *Handle (Handle pointer)
            ccurpmfc_clkgen_input_clock_enable_t *InputClockEnable (pointer to
                                                                    input clock enable)
            _ccurpmfc_cg_input_clock_enable_t   input_0_clock
            # CCURPMFC_CG_INPUT_CLOCK_DISABLE
            # CCURPMFC_CG_INPUT_CLOCK_ENABLE
            # CCURPMFC_CG_INPUT_CLOCK_DO_NOT_CHANGE
            _ccurpmfc_cg_input_clock_enable_t   input_1_clock
            # CCURPMFC_CG_INPUT_CLOCK_DISABLE
            # CCURPMFC_CG_INPUT_CLOCK_ENABLE
            # CCURPMFC_CG_INPUT_CLOCK_DO_NOT_CHANGE
            _ccurpmfc_cg_input_clock_enable_t   input_2_clock
            # CCURPMFC_CG_INPUT_CLOCK_DISABLE
            # CCURPMFC_CG_INPUT_CLOCK_ENABLE
            # CCURPMFC_CG_INPUT_CLOCK_DO_NOT_CHANGE
            _ccurpmfc_cg_input_clock_enable_t   input_fb_clock
            # CCURPMFC_CG_INPUT_CLOCK_DISABLE
            # CCURPMFC_CG_INPUT_CLOCK_ENABLE
            # CCURPMFC_CG_INPUT_CLOCK_DO_NOT_CHANGE

Output: none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
         # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
         # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.55 ccurPMFC_Clock_Set_Generator_Input_Clock_Select()

This call sets the input clock selection.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Input_Clock_Select (void      *Handle,
                                                  ccurpmfc_clkgen_input_clock_select_t *ClkSel)

Description: Set Clock Generator Input Clock Selection

Input:      void *Handle (Handle pointer)

```



```

ccurpmfc_clkgen_input_clock_select_t    *ClkSel (pointer to input
                                           clock select)
    _ccurpmfc_cg_input_clock_select_control_t    control;
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_PIN_CONTROL
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_REG_CONTROL
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_CONTROL_DO_NOT_CHANGE
    _ccurpmfc_cg_input_clock_select_register_t    select;
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN0
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN1
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN2
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_INXAXB
    # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN_DO_NOT_CHANGE
Output:  none
Return:  _ccurpmfc_lib_error_number_t
    # CCURPMFC_LIB_NO_ERROR                (successful)
    # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
    # CCURPMFC_LIB_NOT_OPEN                (device not open)
    # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
    # CCURPMFC_LIB_NO_LOCAL_REGION         (local region not present)
    # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE     (Clock is not active)
*****/

```

2.2.56 ccurPMFC_Clock_Set_Generator_M_Divider()

This call sets the clock generator M-Divider to the user specified Numerator and Denominator. If the Update flag is set, then the change will take place after the divider has been written to.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Clock_Set_Generator_M_Divider (void    *Handle,
                                           __u64    Numerator,
                                           __u32    Denominator,
                                           int      Update)

```

Description: Set Clock Generator M-Divider Numerator and Denominator

```

Input:  void          *Handle          (Handle pointer)
        __u64         Numerator        (Numerator)
        __u32         Denominator      (Denominator)
        int           Update           (True=Update)

```

```

Output:  none
Return:  _ccurpmfc_lib_error_number_t
    # CCURPMFC_LIB_NO_ERROR                (successful)
    # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
    # CCURPMFC_LIB_NOT_OPEN                (device not open)
    # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
    # CCURPMFC_LIB_NO_LOCAL_REGION         (local region not present)
    # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE     (Clock is not active)
*****/

```

2.2.57 ccurPMFC_Clock_Set_Generator_N_Divider()

This call sets the clock generator selected N-Divider to the user specified Numerator and Denominator. If the Update flag is set, then the change will take place after the divider has been written to.

```

/*****
    ccurPMFC_Clock_Set_Generator_N_Divider()
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Clock_Set_Generator_N_Divider (void          *Handle,
                                           __ccurpmfc_clock_generator_divider_t WhichDivider,
                                           __u64          Numerator,
                                           __u32          Denominator,
                                           int            Update)

```

Description: Set Clock Generator N-Divider Numerator and Denominator

```
Input:   void                                     *Handle           (Handle pointer)
         __ccurpmfc_clock_generator_divider_t WhichDivider     (select divider)
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N0
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N1
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N2
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N3
         # CCURPMFC_CLOCK_GENERATOR_DIVIDER_N4
         __u64                                     Numerator         (Numerator)
         __u32                                     Denominator       (Denominator)
         int                                       Update            (True=Update)

Output:  none
Return:  __ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR                 (successful)
         # CCURPMFC_LIB_BAD_HANDLE               (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN                 (device not open)
         # CCURPMFC_LIB_INVALID_ARG              (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION          (local region not present)
         # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE     (Clock is not active)
*****/
```

2.2.58 ccurPMFC_Clock_Set_Generator_Output_Config()

This call sets the clock generator Output Configuration for the selected output.

```
/******
__ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Output_Config (void           *Handle,
                                             __ccurpmfc_clock_generator_output_t WhichOutput,
                                             ccurpmfc_clkgen_output_config_t *OutCfg)
*****/
```

Description: Set Clock Generator Output Configuration

```
Input:   void                                     *Handle           (Handle pointer)
         __ccurpmfc_clock_generator_output_t WhichOutput     (select output)
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
         ccurpmfc_clkgen_output_config_t *OutCfg (pointer to output config)
         __ccurpmfc_cg_outcfg_force_rdiv2_t force_rdiv2
         # CCURPMFC_CG_OUTPUT_CONFIG_DONT_FORCE_RDIV2
         # CCURPMFC_CG_OUTPUT_CONFIG_FORCE_RDIV2
         # CCURPMFC_CG_OUTPUT_CONFIG_FORCE_DO_NOT_CHANGE
         __ccurpmfc_cg_outcfg_enable_t enable
         # CCURPMFC_CG_OUTPUT_CONFIG_DISABLE
         # CCURPMFC_CG_OUTPUT_CONFIG_ENABLE
         # CCURPMFC_CG_OUTPUT_CONFIG_ENABLE_DO_NOT_CHANGE
         __ccurpmfc_cg_outcfg_shutdown_t shutdown
         # CCURPMFC_CG_OUTPUT_CONFIG_POWER_UP
         # CCURPMFC_CG_OUTPUT_CONFIG_SHUTDOWN
         # CCURPMFC_CG_OUTPUT_CONFIG_SHUTDOWN_DO_NOT_CHANGE

Output:  none
Return:  __ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR                 (successful)
```

```

# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.59 ccurPMFC_Clock_Set_Generator_Output_Format()

This call sets the clock generator Output Format for the selected output.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Output_Format (void *Handle,
                                           _ccurpmfc_clock_generator_output_t WhichOutput,
                                           ccurpmfc_clkgen_output_format_t *OutFmt)

```

Description: Set Clock Generator Output Format

Input: void *Handle (Handle pointer)
_ccurpmfc_clock_generator_output_t WhichOutput (select output)

```

# CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
ccurpmfc_clkgen_output_format_t *OutFmt (pointer to
                                         output format)

```

```

_ccurpmfc_cg_outfmt_cmos_drive_t cmos_drive
# CCURPMFC_CG_OUTPUT_FORMAT_CMOS_DRIVE_LVDS
# CCURPMFC_CG_OUTPUT_FORMAT_CMOS_DRIVE_CMOS
# CCURPMFC_CG_OUTPUT_FORMAT_CMOS_DRIVE_DO_NOT_CHANGE
_ccurpmfc_cg_outfmt_disable_state_t disable_state
# CCURPMFC_CG_OUTPUT_FORMAT_DISABLE_LOW
# CCURPMFC_CG_OUTPUT_FORMAT_DISABLE_HIGH
# CCURPMFC_CG_OUTPUT_FORMAT_DISABLE_DO_NOT_CHANGE
_ccurpmfc_cg_outfmt_sync_t sync
# CCURPMFC_CG_OUTPUT_FORMAT_SYNC_DISABLE
# CCURPMFC_CG_OUTPUT_FORMAT_SYNC_ENABLE
# CCURPMFC_CG_OUTPUT_FORMAT_SYNC_DO_NOT_CHANGE
_ccurpmfc_cg_outfmt_format_t format
# CCURPMFC_CG_OUTPUT_FORMAT_FORMAT_LVDS
# CCURPMFC_CG_OUTPUT_FORMAT_FORMAT_CMOS
# CCURPMFC_CG_OUTPUT_FORMAT_FORMAT_DO_NOT_CHANGE

```

Output: none

```

Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.60 ccurPMFC_Clock_Set_Generator_Output_Mode()

This call sets the clock generator Output Mode for the selected output.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Output_Mode (void          *Handle,
      _ccurpmfc_clock_generator_output_t             WhichOutput,
      ccurpmfc_clkgen_output_mode_t                 *OutMode)

Description: Set Clock Generator Output Mode

Input:  void          *Handle      (Handle pointer)
        _ccurpmfc_clock_generator_output_t          WhichOutput (select output)
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
        ccurpmfc_clkgen_output_mode_t              *OutMode      (pointer to
                                                                output mode)
        _ccurpmfc_cg_outmode_amplitude_t          amplitude
        # CCURPMFC_CG_OUTPUT_AMPLITUDE_CMOS
        # CCURPMFC_CG_OUTPUT_AMPLITUDE_LVDS
        # CCURPMFC_CG_OUTPUT_AMPLITUDE_DO_NOT_CHANGE
        _ccurpmfc_cg_outmode_common_t             common
        # CCURPMFC_CG_OUTPUT_COMMON_CMOS
        # CCURPMFC_CG_OUTPUT_COMMON_LVDS
        # CCURPMFC_CG_OUTPUT_COMMON_LVPECL
        # CCURPMFC_CG_OUTPUT_COMMON_DO_NOT_CHANGE

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                    (successful)
        # CCURPMFC_LIB_BAD_HANDLE                  (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                    (device not open)
        # CCURPMFC_LIB_INVALID_ARG                 (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION             (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE         (Clock is not active)
*****/

```

2.2.61 ccurPMFC_Clock_Set_Generator_Output_Mux()

This call sets the clock generator Output Mux for the selected output.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Output_Mux (void          *Handle,
      _ccurpmfc_clock_generator_output_t             WhichOutput,
      ccurpmfc_clkgen_output_mux_t                 *OutMux)

Description: Set Clock Generator Output Mux

Input:  void          *Handle      (Handle pointer)
        _ccurpmfc_clock_generator_output_t          WhichOutput (select output)
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7

```

```

# CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
# CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
ccurpmfc_clkgen_output_mux_t      *OutMux    (pointer to output
                                           inversion/N-divider mux)
_ccurpmfc_cg_outmux_inversion_t    inversion
# CCURPMFC_CG_OUTPUT_MUX_COMPLEMENTARY
# CCURPMFC_CG_OUTPUT_MUX_IN_PHASE
# CCURPMFC_CG_OUTPUT_MUX_INVERTED
# CCURPMFC_CG_OUTPUT_MUX_OUT_OF_PHASE
# CCURPMFC_CG_OUTPUT_MUX_INVERSION_DO_NOT_CHANGE
_ccurpmfc_cg_outmux_ndiv_select_t  ndiv_mux
# CCURPMFC_CG_OUTPUT_MUX_NDIV_0
# CCURPMFC_CG_OUTPUT_MUX_NDIV_1
# CCURPMFC_CG_OUTPUT_MUX_NDIV_2
# CCURPMFC_CG_OUTPUT_MUX_NDIV_3
# CCURPMFC_CG_OUTPUT_MUX_NDIV_4
# CCURPMFC_CG_OUTPUT_MUX_NDIV_DO_NOT_CHANGE

Output:  none
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR                (successful)
# CCURPMFC_LIB_BAD_HANDLE               (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN                 (device not open)
# CCURPMFC_LIB_INVALID_ARG              (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION           (local region not present)
# CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE      (Clock is not active)
*****/

```

2.2.62 ccurPMFC_Clock_Set_Generator_P_Divider()

This call sets the clock generator selected P-Divider to the user specified value. If the Update flag is set, then the change will take place after the divider has been written to.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_P_Divider (void      *Handle,
                                           _ccurpmfc_clock_generator_divider_t WhichDivider,
                                           __u64      Divider,
                                           int        Update)

```

Description: Set Clock Generator R-Divider

```

Input:  void      *Handle      (Handle pointer)
         _ccurpmfc_clock_generator_divider_t WhichDivider (select divider)
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_P0
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_P1
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_P2
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_PFB
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_PXAXB
__u64      Divider      (Divider)
int        Update       (True=Update)

Output:  none
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR                (successful)
# CCURPMFC_LIB_BAD_HANDLE               (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN                 (device not open)
# CCURPMFC_LIB_INVALID_ARG              (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION           (local region not present)
# CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE      (Clock is not active)
*****/

```

2.2.63 ccurPMFC_Clock_Set_Generator_P_Divider_Enable()

This call sets the state of the clock generator P-Divider.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_P_Divider_Enable (void          *Handle,
        _ccurpmfc_clock_generator_divider_t WhichDivider,
        _ccurpmfc_cg_pdiv_enable_t          Pdiv_Enable)

Description: Set Clock Generator P-Divider Enable

Input:  void          *Handle          (Handle pointer)
        _ccurpmfc_clock_generator_divider_t WhichDivider (select divider)
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P0
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P1
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_P2
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_PXAXB
        _ccurpmfc_cg_pdiv_enable_t          Pdiv_Enable (enable flag)
        # CCURPMFC_CG_PDIV_DISABLE
        # CCURPMFC_CG_PDIV_ENABLE

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.64 ccurPMFC_Clock_Set_Generator_R_Divider()

This call sets the clock generator selected R-Divider to the user specified value. If the output clock is running, the new clock frequency will take affect immediately or on the next clock cycle depending on the output configuration.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_R_Divider (void          *Handle,
        _ccurpmfc_clock_generator_divider_t WhichDivider,
        __u32          Divider)

Description: Set Clock Generator R-Divider

Input:  void          *Handle          (Handle pointer)
        _ccurpmfc_clock_generator_divider_t WhichDivider (select divider)
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R0
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R1
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R2
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R3
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R4
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R5
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R6
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R7
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R8
        # CCURPMFC_CLOCK_GENERATOR_DIVIDER_R9
        __u32          Divider          (Divider)

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

*****/

2.2.65 ccurPMFC_Clock_Set_Generator_Value()

This is a generic call that can program a valid clock generator address to a desired value. User must be intimately familiar with the hardware before programming the values. In-correct programming could result in unpredictable results.

/*****

```
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Value (void      *Handle,
                                     int       address,
                                     u_char   value)
```

Description: Set the value of the specified Clock Generator register.

Input: void *Handle (Handle pointer)
int address (clock gen address to set)
u_char value; (value to write)

Output: none

Return: _ccurpmfc_lib_error_number_t
CCURPMFC_LIB_NO_ERROR (successful)
CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
CCURPMFC_LIB_NOT_OPEN (device not open)
CCURPMFC_LIB_INVALID_ARG (invalid argument)
CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)

*****/

2.2.66 ccurPMFC_Clock_Set_Generator_Voltage_Select()

Program the clock generator voltage selection.

/*****

```
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Voltage_Select (void      *Handle,
                                              _ccurpmfc_cg_stat_ctrl_voltsel_t VoltSel)
```

Description: Set Clock Generator voltage selection

Input: void *Handle (Handle pointer)
_ccurpmfc_cg_stat_ctrl_voltsel_t VoltSel (voltage selection)
CCURPMFC_CG_VOLTAGE_SELECT_1_8V
CCURPMFC_CG_VOLTAGE_SELECT_3_3V

Output: none

Return: _ccurpmfc_lib_error_number_t
CCURPMFC_LIB_NO_ERROR (successful)
CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
CCURPMFC_LIB_NOT_OPEN (device not open)
CCURPMFC_LIB_INVALID_ARG (invalid argument)
CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)

*****/

2.2.67 ccurPMFC_Clock_Set_Generator_Zero_Delay()

Program the clock generator zero delay.

/*****

```
_ccurpmfc_lib_error_number_t
ccurPMFC_Clock_Set_Generator_Zero_Delay (void      *Handle,
                                          _ccurpmfc_cg_zero_delay_t ZeroDelay)
```

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Description: Set Clock Generator Zero Delay selection

```
Input:   void                *Handle      (Handle pointer)
         _ccurpmfc_cg_zero_delay_t      ZeroDelay (zero delay selection)
         # CCURPMFC_CG_ZERO_DELAY_MODE
         # CCURPMFC_CG_NORMAL_MODE

Output:  none

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR          (successful)
         # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN         (device not open)
         # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
         # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
         # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/
```

2.2.68 ccurPMFC_Close()

This call is used to close an already opened device using the *ccurPMFC_Open()* call.

```
/*
   _ccurpmfc_lib_error_number_t ccurPMFC_Close(void *Handle)

Description: Close a previously opened device.

Input:   void *Handle          (Handle pointer)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR          (successful)
         # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN         (device not open)
*****/
```

2.2.69 ccurPMFC_Compute_All_Output_Clocks()

This call does not program the clock outputs but instead returns to the user whether the board can be programmed with the user selected output clock frequencies. Additionally, useful information is returned to the user in a structure for each clock that was computed.

```
/*
   ccurPMFC_Compute_All_Output_Clocks()

Description: Compute All Output Clocks

Input:   void                *Handle      (Handle pointer)
         double              InputClockFrequency (Input clock
                                                frequency)
         ccurpmfc_compute_all_output_clocks_t *AllClocks (Pointer to all
                                                output clocks info)
         ccurpmfc_compute_single_output_clock_t
         long double          *Clock      DesiredFrequency
         double               DesiredTolerancePPT
Output:  ccurpmfc_compute_all_output_clocks_t *AllClocks
         (Pointer to returned output clocks info)
         __u32                NumberOfNdividers
         ccurpmfc_compute_single_output_clock_t *Clock
         _ccurpmfc_clock_generator_output_t   OutputClock
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
         # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
*****/
```



```

        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
        # CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
double
long double
int
long double
double
__u64
__u32
__u64
__u32
_ccurpmfc_cg_outmux_ndiv_select_t
# CCURPMFC_CG_OUTPUT_MUX_NDIV_0
# CCURPMFC_CG_OUTPUT_MUX_NDIV_1
# CCURPMFC_CG_OUTPUT_MUX_NDIV_2
# CCURPMFC_CG_OUTPUT_MUX_NDIV_3
# CCURPMFC_CG_OUTPUT_MUX_NDIV_4
__u32
__u32
__u32
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR
        # CCURPMFC_LIB_BAD_HANDLE

        # CCURPMFC_LIB_NOT_OPEN
        # CCURPMFC_LIB_NO_LOCAL_REGION
        # CCURPMFC_LIB_IO_ERROR
        # CCURPMFC_LIB_N_DIVIDERS_EXCEEDED

        # CCURPMFC_LIB_CANNOT_COMPUTE_OUTPUT_FREQ

        # CCURPMFC_LIB_INVALID_ARG
*****

```

2.2.70 ccurPMFC_Convert_Physmem2avmm_Address()

This call is used to supply the user with an Avalon equivalent Address for the supplied Physical DMA memory. This Avalon equivalent address can then be supplied to the DMA engine to perform DMA operations.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Convert_Physmem2avmm_Address(void      *Handle,
                                         uint      *PhysDmaMemPtr,
                                         uint      *AvalonAddress)

```

Description: Get the converted value of Physical DMA memory to Avalon address to be supplied as address for DMA operations.

```

Input:  void      *Handle      (Handle pointer)
        uint      *PhysDmaMemPtr (pointer to physical DMA
                                memory)
Output: uint      *AvalonAddress (pointer to Avalon
                                Address).

Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN      (library not open)
        # CCURPMFC_LIB_INVALID_ARG   (invalid argument)

```

```

        # CCURPMFC_LIB_AVALON_TRANSLATION_TABLE (avalon translation table
        error)
        # CCURPMFC_LIB_ADDRESS_RANGE_ERROR (address range error)
        *****/

```

2.2.71 ccurPMFC_Create_UserDioCosInterruptHandler()

This call provides the ability for a user to get notification when a DIO change-of-state interrupt occurs. Prior to invoking this call, the user needs to create an *interrupt callback* function which is supplied to this call as one of its inputs. Additionally, the user selects a set of DIO COS wakeup masks to enter the user supplied callback when a corresponding interrupt occurs. On successful completion of this call, a real-time high priority thread is created and blocked waiting for DIO COS interrupts. When a DIO COS interrupt occurs, the driver will wake up this thread which in turn will execute the user supplied *interrupt callback* function. Various DIO COS statistics will be returned to the user as an argument *driver_dio_cos_int* supplied to the *interrupt callback* routine everytime a wakeup occurs. The user needs to ensure that the processing within this *interrupt callback* should be completed in as short a time as possible for the thread to be ready in time to accept the next DIO COS interrupt. Failure to do so will result in missed change-of-state interrupts.

If the interrupt handler has already been created for a device, then the user will be unable to create another one as only one interrupt handler is assigned to each device. User will need to destroy the interrupt handler with the *ccurPMFC_Destroy_UserDioCosInterruptHandler()* call prior to creating a new one.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Create_UserDioCosInterruptHandler(void      *Handle,
                                                void      CallBack(),
                                                u_int     DioCosWakeupInterruptMask)

Description: Create a User DIO COS Interrupt Handler

Input:   void      *Handle      (Handle pointer)
         void      CallBack()   (user callback function)
         u_int     DioCosWakeupInterruptMask (wakeup interrupt mask)
         # CCURPMFC_DIO_GROUP0_INTMASK
         # CCURPMFC_DIO_GROUP1_INTMASK
         # CCURPMFC_DIO_GROUP2_INTMASK

Output:  none

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR      (successful)
         # CCURPMFC_LIB_BAD_HANDLE   (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN     (device not open)
         # CCURPMFC_LIB_INTHDLR_CREATE_FAILURE (failed to create
         interrupt handler)
         # CCURPMFC_LIB_INTHDLR_ALREADY_RUNNING (interrupt hdlr already
         running)
         # CCURPMFC_LIB_IOCTL_FAILED (ioctl failed)
         # CCURPMFC_LIB_INVALID_ARG  (invalid argument)
        *****/

```

// User interrupt callback()

```

void DioCosUserCallback(void      *Handle,
                        ccurpmfc_driver_dio_cos_int_t *driver_dio_cos_int)
{
    // User supplied code for handling interrupt
}

// Interrupt Counters
typedef struct
{
    long long unsigned dio_interrupt_count;
}

```

```

    long long unsigned dma_count[CCURPMFC_DMA_MAX_ENGINES];
    long long unsigned DIO_COS_ChannelsCount[CCURPMFC_DIO_MAX_REGISTERS];
    long long unsigned
DIO_COS_ChannelsOverflowCount[CCURPMFC_DIO_MAX_REGISTERS];
} ccurpmfc_interrupt_dio_cos_counters_t;

typedef struct {
    u_int32_t chan_00_31;
    u_int32_t chan_32_63;
    u_int32_t chan_64_95;
} ccurpmfc_dio_channel_t;

typedef u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS];

// DIO COS Interrupt
typedef struct
{
    union {
        uint status; // Obsolete
        uint InterruptsOccurredMask; // use this name
    };
    union {
        uint mask; // Obsolete
        uint WakeupInterruptMask; // use this name
    };

    // DIO information
    union {
        ccurpmfc_dio_channels_t DIO_COS_ChannelsStatus;
        ccurpmfc_dio_channel_t DIO_COS_ChannelsStatusX;
    };
    union {
        ccurpmfc_dio_channels_t DIO_COS_ChannelsOverflow;
        ccurpmfc_dio_channel_t DIO_COS_ChannelsOverflowX;
    };

    ccurpmfc_interrupt_dio_cos_counters_t counters;
} ccurpmfc_driver_dio_cos_int_t;

```

2.2.72 ccurPMFC_Create_UserProcess()

Typically reads from h/w take a finite time to complete. If the user has a process that is time critical and needs to read the latest data faster, they may use a new approach called Hyper-Drive. In this case, the user defines a thread with this call, which continuously reads the data from the board and holds the latest values. The user process can then access this latest data at substantially faster rates. The two drawbacks to this approach is that the excessive bus access is made and dedicated CPUs are required.

This call is used to create this User Process looping thread which can be controlled by the user via the returned handle. (*This is an experimental API for debugging and testing*).

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Create_UserProcess(void *Handle,
                             _ccurpmfc_UserFunction_t *UFunc,
                             _ccurpmfc_UserFunction_t **UFuncHandle)

```

Description: Create a User Process for user defined processing

Input:	void	*Handle	(Handle pointer)
	_ccurpmfc_UserFunction_t	*UFunc	(pointer to user information structure)
Output:	_ccurpmfc_UserFunction_t	**UFuncHandle	(pointer to user function struct handle)

```

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_NO_RESOURCE             (cannot allocate memory)
        # CCURPMFC_LIB_INTERNAL_ERROR          (pthread attr failed)
        # CCURPMFC_LIB_THREAD_CREATE_FAILED    (failed to create thread)
*****/

```

```

typedef struct
{
    int Magic;
    void (*UserFunction) (void *hdl);
    pthread_t UserFunction_Thread_id;
    pid_t Pid;
    pthread_mutex_t lock; /* lock this structure */
    pthread_cond_t wait; /* wait for command */
    pthread_mutex_t cmd_lock; /* lock this structure */
    pthread_cond_t cmd_wait; /* wait for command */
    pthread_mutex_t user_lock; /* lock this structure */
    pthread_cond_t user_wait; /* wait for command */
    pthread_mutex_t user_mem_lock; /* lock this structure */
    pthread_cond_t user_mem_wait; /* wait for command */
    volatile int cpuAffinity; /* CPU on which Thread
                               will run */
    volatile int cpuCount; /* no. of cpus to run on
                            starting at base */

    volatile void *Handle;
    volatile void **Args;
    volatile int SchedulePolicy;
    volatile int SchedulePriority;
    volatile int ScheduleSelf; /* 1=(Use
                                SchedulePriority-
                                1),0=no change */

    volatile ccurpmfc_uf_action_t Action;
    volatile ccurpmfc_uf_state_t State;
    volatile int CommandPending;
    volatile void *Next_UserFunction;
    volatile unsigned int long long RunCount;
    volatile int Pause;
} _ccurpmfc_UserFunction_t;

```

2.2.73 ccurPMFC_DAC_Activate()

This call must be the first call to activate the DAC. Without activation, all other calls will fail. The user can also use this call to return the current state of the DAC without any change.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Activate (void *Handle,
                      _ccurpmfc_dac_all_enable_t activate,
                      _ccurpmfc_dac_all_enable_t *current_state)

```

Description: Activate/DeActivate DAC module

```

Input:  void *Handle (Handle pointer)
        _ccurpmfc_dac_all_enable_t activate (activate/deactivate)
        # CCURPMFC_DAC_ALL_DISABLE
        # CCURPMFC_DAC_ALL_ENABLE
        # CCURPMFC_DAC_ALL_ENABLE_DO_NOT_CHANGE
Output: _ccurpmfc_dac_all_enable_t *current_state (active/deactive)
        # CCURPMFC_DAC_ALL_DISABLE
        # CCURPMFC_DAC_ALL_ENABLE

```

```

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN               (device not open)
        # CCURPMFC_LIB_INVALID_ARG            (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
*****/

```

2.2.74 ccurPMFC_DAC_Get_CSR()

This call returns information from the DAC registers for the selected channel group.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Get_CSR (void          *Handle,
                      _ccurpmfc_dac_mask_t  dac_mask,
                      ccurpmfc_dac_csr_t    *dac_csr)

Description: Get DAC Control and Status information

Input:  void          *Handle (Handle pointer)
        _ccurpmfc_dac_mask_t  dac_mask (selected DAC mask)
        # CCURPMFC_DAC_MASK_0_3
        # CCURPMFC_DAC_MASK_4_7
        # CCURPMFC_DAC_MASK_8_11
        # CCURPMFC_DAC_MASK_12_15

Output: ccurpmfc_dac_csr_t    *dac_csr (pointer to DAC csr)
        _ccurpmfc_daccsr_busy_t  dac_interface_busy
        # CCURPMFC_DAC_IDLE
        # CCURPMFC_DAC_BUSY
        _ccurpmfc_daccsr_powerdown_t  dac_powerdown
        # CCURPMFC_DAC_OPERATIONAL
        # CCURPMFC_DAC_POWERDOWN
        _ccurpmfc_daccsr_updmode_t  dac_update_mode
        # CCURPMFC_DAC_MODE_IMMEDIATE
        # CCURPMFC_DAC_MODE_SYNCHRONIZED
        _ccurpmfc_daccsr_data_format_t  dac_data_format
        # CCURPMFC_DAC_OFFSET_BINARY
        # CCURPMFC_DAC_TWOS_COMPLEMENT
        _ccurpmfc_daccsr_output_select_t  dac_output_select
        # CCURPMFC_DAC_SINGLE_ENDED
        # CCURPMFC_DAC_DIFFERENTIAL
        _ccurpmfc_daccsr_output_range_t  dac_output_range
        # CCURPMFC_DAC_SINGLE_ENDED_UNIPOLAR_10V
        # CCURPMFC_DAC_SINGLE_ENDED_BIPOLAR_5V
        # CCURPMFC_DAC_SINGLE_ENDED_BIPOLAR_10V
        # CCURPMFC_DAC_SINGLE_ENDED_UNIPOLAR_20V

        # CCURPMFC_DAC_DIFFERENTIAL_UNIPOLAR_10V
        # CCURPMFC_DAC_DIFFERENTIAL_BIPOLAR_10V
        # CCURPMFC_DAC_DIFFERENTIAL_BIPOLAR_20V
        # CCURPMFC_DAC_DIFFERENTIAL_UNIPOLAR_20V

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN               (device not open)
        # CCURPMFC_LIB_INVALID_ARG            (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE      (DAC is not active)
*****/

```

2.2.75 ccurPMFC_DAC_Get_Driver_Write_Mode()

This call returns the current driver DAC write mode. When a *write(2)* system call is issued, it is this mode that determines the type of write being performed by the driver.

```
/*
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Get_Driver_Write_Mode (void *Handle,
                                     _ccurpmfc_driver_DAC_write_mode_t *mode)

Description: Get current DAC write mode that will be selected by the 'write()'
call

Input: void *Handle (Handle pointer)
Output: _ccurpmfc_driver_DAC_write_mode_t *mode (select DAC write mode)
        # CCURPMFC_DAC_PIO_CHANNEL
        # CCURPMFC_DAC_PIO_FIFO
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (library not open)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_IOCTL_FAILED (driver ioctl call failed)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
*/
```

2.2.76 ccurPMFC_DAC_Get_Fifo_Channel_Select()

This call returns the current Fifo Channel selection mask. Only samples for these selected channels are placed in the FIFO during sample generation. Unlike the ADC Fifo channel select option, this DAC FIFO channel select option also restricts DAC channel register writes to those selected by this option. The advantage for implementing this option for DAC channel registers in addition to DAC FIFO is that the user can perform DMA operations to generate samples on selected channels without affecting the output of those channels that have not been included in the channel selection.

```
/*
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Get_Fifo_Channel_Select(void *Handle,
                                     _ccurpmfc_dac_channel_mask_t
                                     *dac_fifo_channel_select_mask)

Description: DAC Get Fifo Channel Selection

Input: void *Handle (handle pointer)
Output: _ccurpmfc_dac_channel_mask_t *dac_fifo_channel_select_mask
        (channel select mask)
        # CCURPMFC_DAC_CHANNEL_MASK_0
        # CCURPMFC_DAC_CHANNEL_MASK_1
        # CCURPMFC_DAC_CHANNEL_MASK_2
        # CCURPMFC_DAC_CHANNEL_MASK_3
        # CCURPMFC_DAC_CHANNEL_MASK_4
        # CCURPMFC_DAC_CHANNEL_MASK_5
        # CCURPMFC_DAC_CHANNEL_MASK_6
        # CCURPMFC_DAC_CHANNEL_MASK_7
        # CCURPMFC_DAC_CHANNEL_MASK_8
        # CCURPMFC_DAC_CHANNEL_MASK_9
        # CCURPMFC_DAC_CHANNEL_MASK_10
        # CCURPMFC_DAC_CHANNEL_MASK_11
        # CCURPMFC_DAC_CHANNEL_MASK_12
        # CCURPMFC_DAC_CHANNEL_MASK_13
        # CCURPMFC_DAC_CHANNEL_MASK_14
        # CCURPMFC_DAC_CHANNEL_MASK_15
        # CCURPMFC_ALL_DAC_CHANNELS_MASK
*/
```

```

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.77 ccurPMFC_DAC_Get_Fifo_Info()

This call returns DAC FIFO information to the user.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Get_Fifo_Info (void *Handle,
                             ccurpmfc_dac_fifo_info_t *dac_fifo)

Description: Get DAC FIFO control and Status information

Input:  void *Handle (Handle pointer)
Output: ccurpmfc_dac_fifo_info_t *dac_fifo (pointer to DAC fifo
                                             struct)

        _ccurpmfc_dac_fifo_reset_t      reset;
        # CCURPMFC_DAC_FIFO_ACTIVE
        # CCURPMFC_DAC_FIFO_RESET
        _ccurpmfc_dac_fifo_overflow_t    overflow;
        # CCURPMFC_DAC_FIFO_NO_OVERFLOW
        # CCURPMFC_DAC_FIFO_OVERFLOW
        _ccurpmfc_dac_fifo_underflow_t   underflow;
        # CCURPMFC_DAC_FIFO_NO_UNDERFLOW
        # CCURPMFC_DAC_FIFO_UNDERFLOW
        _ccurpmfc_dac_fifo_full_t        full;
        # CCURPMFC_DAC_FIFO_NOT_FULL
        # CCURPMFC_DAC_FIFO_FULL
        _ccurpmfc_dac_fifo_threshold_t   threshold_exceeded;
        # CCURPMFC_DAC_FIFO_THRESHOLD_NOT_EXCEEDED
        # CCURPMFC_DAC_FIFO_THRESHOLD_EXCEEDED
        _ccurpmfc_dac_fifo_empty_t       empty;
        # CCURPMFC_DAC_FIFO_NOT_EMPTY
        # CCURPMFC_DAC_FIFO_EMPTY

        uint data_counter;
        uint threshold;
        uint max_threshold;
        uint driver_threshold;
        uint write_count;
        dac_fifo_channel_select_mask     channel_select_mask;
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.78 ccurPMFC_DAC_Get_Fifo_Threshold()

This call returns the DAC Fifo threshold information.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Get_Fifo_Threshold(void *Handle,

```

```
uint *dac_threshold)
```

Description: DAC Get Fifo Threshold

```
Input: void *Handle (handle pointer)
Output: uint *dac_threshold (DAC fifo threshold)
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/
```

2.2.79 ccurPMFC_DAC_Get_Fifo_Write_Count()

This call returns the count of the DAC FIFO. It is updated anytime the FIFO is written to. This is only used for debug.

```
/*
*_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Get_Fifo_Write_Count(void *Handle,
                                  uint *dac_write_count)
```

Description: DAC Get Fifo Write Count

```
Input: void *Handle (handle pointer)
Output: uint *dac_write_count (DAC fifo write count)
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/
```

2.2.80 ccurPMFC_DAC_Get_Gain_Cal()

This call returns the DAC calibration gain values.

```
/*
*_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Get_Gain_Cal(void *Handle,
                          _ccurpmfc_dac_channel_mask_t ChanMask,
                          ccurpmfc_dac_cal_t *cal)
```

Description: Get the DAC Gain Calibration data.

```
Input: void *Handle (handle pointer)
        _ccurpmfc_dac_channel_mask_t ChanMask (channel selection mask)
        # CCURPMFC_DAC_CHANNEL_MASK_0
        # CCURPMFC_DAC_CHANNEL_MASK_1
        # CCURPMFC_DAC_CHANNEL_MASK_2
        # CCURPMFC_DAC_CHANNEL_MASK_3
        # CCURPMFC_DAC_CHANNEL_MASK_4
        # CCURPMFC_DAC_CHANNEL_MASK_5
        # CCURPMFC_DAC_CHANNEL_MASK_6
        # CCURPMFC_DAC_CHANNEL_MASK_7
        # CCURPMFC_DAC_CHANNEL_MASK_8
        # CCURPMFC_DAC_CHANNEL_MASK_9
        # CCURPMFC_DAC_CHANNEL_MASK_10
```



```

# CCURPMFC_DAC_CHANNEL_MASK_11
# CCURPMFC_DAC_CHANNEL_MASK_12
# CCURPMFC_DAC_CHANNEL_MASK_13
# CCURPMFC_DAC_CHANNEL_MASK_14
# CCURPMFC_DAC_CHANNEL_MASK_15
# CCURPMFC_ALL_DAC_CHANNELS_MASK
Output: ccurpmfc_dac_cal_t          *cal      (pointer to board cal)
        uint      Raw[CCURPMFC_MAX_DAC_CHANNELS]
        double    Float[CCURPMFC_MAX_DAC_CHANNELS]
        double    CalibrationReferenceVoltage[CCURPMFC_MAX_DAC_CHANNELS]
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.81 ccurPMFC_DAC_Get_Offset_Cal()

This call returns the DAC calibration offset values.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Get_Offset_Cal(void          *Handle,
                                _ccurpmfc_dac_channel_mask_t ChanMask
                                ccurpmfc_dac_cal_t          *cal)

```

Description: Get the DAC Offset Calibration data.

```

Input:  void          *Handle (handle pointer)
        _ccurpmfc_dac_channel_mask_t ChanMask (channel selection mask)
        # CCURPMFC_DAC_CHANNEL_MASK_0
        # CCURPMFC_DAC_CHANNEL_MASK_1
        # CCURPMFC_DAC_CHANNEL_MASK_2
        # CCURPMFC_DAC_CHANNEL_MASK_3
        # CCURPMFC_DAC_CHANNEL_MASK_4
        # CCURPMFC_DAC_CHANNEL_MASK_5
        # CCURPMFC_DAC_CHANNEL_MASK_6
        # CCURPMFC_DAC_CHANNEL_MASK_7
        # CCURPMFC_DAC_CHANNEL_MASK_8
        # CCURPMFC_DAC_CHANNEL_MASK_9
        # CCURPMFC_DAC_CHANNEL_MASK_10
        # CCURPMFC_DAC_CHANNEL_MASK_11
        # CCURPMFC_DAC_CHANNEL_MASK_12
        # CCURPMFC_DAC_CHANNEL_MASK_13
        # CCURPMFC_DAC_CHANNEL_MASK_14
        # CCURPMFC_DAC_CHANNEL_MASK_15
        # CCURPMFC_ALL_DAC_CHANNELS_MASK
Output: ccurpmfc_dac_cal_t          *cal      (pointer to board cal)
        uint      Raw[CCURPMFC_MAX_DAC_CHANNELS]
        double    Float[CCURPMFC_MAX_DAC_CHANNELS]
        double    CalibrationReferenceVoltage[CCURPMFC_MAX_DAC_CHANNELS]
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.82 ccurPMFC_DAC_Get_Update_Source_Select()

This call allows the user to return the selected DAC update source.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_DAC_Get_Update_Source_Select (void          *Handle,
                                         _ccurpmfc_daccsr_update_source_t
                                         *update_source)

Description: Get DAC Update Source Select

Input:   void          *Handle      (Handle pointer)
Output:  _ccurpmfc_daccsr_update_source_t *update_source (pointer to update
                                         source)

      # CCURPMFC_DAC_UPDATE_SOFTWARE
      # CCURPMFC_DAC_UPDATE_CLOCK_0
      # CCURPMFC_DAC_UPDATE_CLOCK_1
      # CCURPMFC_DAC_UPDATE_CLOCK_2
      # CCURPMFC_DAC_UPDATE_CLOCK_3
      # CCURPMFC_DAC_UPDATE_CLOCK_4
      # CCURPMFC_DAC_UPDATE_CLOCK_5
      # CCURPMFC_DAC_UPDATE_CLOCK_6
Return:  _ccurpmfc_lib_error_number_t
      # CCURPMFC_LIB_NO_ERROR          (successful)
      # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
      # CCURPMFC_LIB_NOT_OPEN         (device not open)
      # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
      # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
      # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/
```

2.2.83 ccurPMFC_DAC_Perform_Auto_Calibration()

This single call performs a full DAC calibration of all the channels using the ADC. The ADC needs to be first calibrated prior to issuing this call.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_DAC_Perform_Auto_Calibration(void          *Handle,
                                         _ccurpmfc_dac_channel_mask_t  ChanMask)

Description: Perform DAC Auto Calibration for selected channels

Input:   void          *Handle      (handle pointer)
         _ccurpmfc_dac_channel_mask_t ChanMask (channel selection mask)
      # CCURPMFC_DAC_CHANNEL_MASK_0
      # CCURPMFC_DAC_CHANNEL_MASK_1
      # CCURPMFC_DAC_CHANNEL_MASK_2
      # CCURPMFC_DAC_CHANNEL_MASK_3
      # CCURPMFC_DAC_CHANNEL_MASK_4
      # CCURPMFC_DAC_CHANNEL_MASK_5
      # CCURPMFC_DAC_CHANNEL_MASK_6
      # CCURPMFC_DAC_CHANNEL_MASK_7
      # CCURPMFC_DAC_CHANNEL_MASK_8
      # CCURPMFC_DAC_CHANNEL_MASK_9
      # CCURPMFC_DAC_CHANNEL_MASK_10
      # CCURPMFC_DAC_CHANNEL_MASK_11
      # CCURPMFC_DAC_CHANNEL_MASK_12
      # CCURPMFC_DAC_CHANNEL_MASK_13
      # CCURPMFC_DAC_CHANNEL_MASK_14
      # CCURPMFC_DAC_CHANNEL_MASK_15
      # CCURPMFC_ALL_DAC_CHANNELS_MASK
*****/
```

```

Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (library not open)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.84 ccurPMFC_DAC_Perform_Gain_Calibration()

This call performs a *gain* calibration using the ADC. The ADC needs to be first calibrated prior to issuing this call.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_DAC_Perform_Gain_Calibration(void          *Handle,
                                           _ccurpmfc_dac_channel_mask_t  ChanMask)

```

Description: Perform DAC Gain Calibration for selected channels

```

Input:  void          *Handle (handle pointer)
        _ccurpmfc_dac_channel_mask_t  ChanMask (channel selection mask)
        # CCURPMFC_DAC_CHANNEL_MASK_0
        # CCURPMFC_DAC_CHANNEL_MASK_1
        # CCURPMFC_DAC_CHANNEL_MASK_2
        # CCURPMFC_DAC_CHANNEL_MASK_3
        # CCURPMFC_DAC_CHANNEL_MASK_4
        # CCURPMFC_DAC_CHANNEL_MASK_5
        # CCURPMFC_DAC_CHANNEL_MASK_6
        # CCURPMFC_DAC_CHANNEL_MASK_7
        # CCURPMFC_DAC_CHANNEL_MASK_8
        # CCURPMFC_DAC_CHANNEL_MASK_9
        # CCURPMFC_DAC_CHANNEL_MASK_10
        # CCURPMFC_DAC_CHANNEL_MASK_11
        # CCURPMFC_DAC_CHANNEL_MASK_12
        # CCURPMFC_DAC_CHANNEL_MASK_13
        # CCURPMFC_DAC_CHANNEL_MASK_14
        # CCURPMFC_DAC_CHANNEL_MASK_15
        # CCURPMFC_ALL_DAC_CHANNELS_MASK

```

```

Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (library not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.85 ccurPMFC_DAC_Perform_Offset_Calibration()

This call performs a *offset* calibration using the ADC. The ADC needs to be first calibrated prior to issuing this call.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_DAC_Perform_Offset_Calibration(void          *Handle,
                                           _ccurpmfc_dac_channel_mask_t  ChanMask)

```

Description: Perform DAC Offset Calibration for selected channels

```
Input:   void          *Handle (handle pointer)
        _ccurpmfc_dac_channel_mask_t ChanMask (channel selection mask)
        # CCURPMFC_DAC_CHANNEL_MASK_0
        # CCURPMFC_DAC_CHANNEL_MASK_1
        # CCURPMFC_DAC_CHANNEL_MASK_2
        # CCURPMFC_DAC_CHANNEL_MASK_3
        # CCURPMFC_DAC_CHANNEL_MASK_4
        # CCURPMFC_DAC_CHANNEL_MASK_5
        # CCURPMFC_DAC_CHANNEL_MASK_6
        # CCURPMFC_DAC_CHANNEL_MASK_7
        # CCURPMFC_DAC_CHANNEL_MASK_8
        # CCURPMFC_DAC_CHANNEL_MASK_9
        # CCURPMFC_DAC_CHANNEL_MASK_10
        # CCURPMFC_DAC_CHANNEL_MASK_11
        # CCURPMFC_DAC_CHANNEL_MASK_12
        # CCURPMFC_DAC_CHANNEL_MASK_13
        # CCURPMFC_DAC_CHANNEL_MASK_14
        # CCURPMFC_DAC_CHANNEL_MASK_15
        # CCURPMFC_ALL_DAC_CHANNELS_MASK

Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (library not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/
```

2.2.86 ccurPMFC_DAC_Read_Channels_Calibration()

This routine reads the DAC channel calibration registers and dumps them to the user specified file. If the file name specified is NULL, then information is written to *stdout*.

```
/*
   _ccurpmfc_lib_error_number_t
   ccurPMFC_DAC_Read_Channels_Calibration(void *Handle,
                                           char *filename)

Description: Read DAC Channels Calibration

Input:   void *Handle (handle pointer)
Output:  char *filename (pointer to filename)
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (library not open)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_CANNOT_OPEN_FILE (cannot open calib. file)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (ADC is not active)
*****/
```

2.2.87 ccurPMFC_DAC_ReadBack_Channels()

This call is more of debug purpose. It causes the DAC channels output to be connected to a user specified ADC channel and then returns the current reading of the ADC channel. Hence, we have read back the DAC channels selected.

If the ADC configuration *adc_csr* is *NULL*, then the call reads the current ADC configuration for the selected ADC channel *ADCChan*, however, the user can instead supply a pointer to the ADC configuration *adc_csr* where they have already configured the ADC as the following:

```
adc_data_format = CCURPMFC_ADC_TWOS_COMPLEMENT
adc_input_range = CCURPMFC_ADC_BIPOLAR_10V
adc_input_signal = CCURPMFC_ADC_CALIBRATION_BUS
adc_update_clock = CCURPMFC_ADC_UPDATE_CLOCK_0
```

Note that the *adc_update_clock* should be set to the currently active clock. Failure to set the above values will result in the call failing with invalid argument *CCURPMFC_LIB_INVALID_ARG*.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_ReadBack_Channels(void                *Handle,
                                _ccurpmfc_dac_channel_mask_t DACChanMask,
                                _ccurpmfc_adc_channel_t     ADCChan,
                                _ccurpmfc_adc_csr_t          *adc_csr,
                                ccurpmfc_dac_volts_t         *dac_volts)

```

Description: Read Back DAC Channels using ADC

Input: void mask)	void _ccurpmfc_dac_channel_mask_t # CCURPMFC_DAC_CHANNEL_MASK_0 # CCURPMFC_DAC_CHANNEL_MASK_1 # CCURPMFC_DAC_CHANNEL_MASK_2 # CCURPMFC_DAC_CHANNEL_MASK_3 # CCURPMFC_DAC_CHANNEL_MASK_4 # CCURPMFC_DAC_CHANNEL_MASK_5 # CCURPMFC_DAC_CHANNEL_MASK_6 # CCURPMFC_DAC_CHANNEL_MASK_7 # CCURPMFC_DAC_CHANNEL_MASK_8 # CCURPMFC_DAC_CHANNEL_MASK_9 # CCURPMFC_DAC_CHANNEL_MASK_10 # CCURPMFC_DAC_CHANNEL_MASK_11 # CCURPMFC_DAC_CHANNEL_MASK_12 # CCURPMFC_DAC_CHANNEL_MASK_13 # CCURPMFC_DAC_CHANNEL_MASK_14 # CCURPMFC_DAC_CHANNEL_MASK_15 # CCURPMFC_ALL_DAC_CHANNELS_MASK _ccurpmfc_adc_channel_t _ccurpmfc_adc_csr_t _ccurpmfc_adccsr_update_clock_t # CCURPMFC_ADC_UPDATE_CLOCK_NONE # CCURPMFC_ADC_UPDATE_CLOCK_0 # CCURPMFC_ADC_UPDATE_CLOCK_1 # CCURPMFC_ADC_UPDATE_CLOCK_2 # CCURPMFC_ADC_UPDATE_CLOCK_3 # CCURPMFC_ADC_UPDATE_CLOCK_4 # CCURPMFC_ADC_UPDATE_CLOCK_5 # CCURPMFC_ADC_UPDATE_CLOCK_6 _ccurpmfc_adccsr_input_signal_t # CCURPMFC_ADC_EXTERNAL_SIGNAL # CCURPMFC_ADC_CALIBRATION_BUS _ccurpmfc_adccsr_data_format_t # CCURPMFC_ADC_OFFSET_BINARY # CCURPMFC_ADC_TWOS_COMPLEMENT _ccurpmfc_adccsr_input_range_t # CCURPMFC_ADC_BIPOLAR_10V	*Handle (Handle pointer) DACChanMask (specify DAC channel ADCChan (ADC channel to read) *adc_csr (pointer to ADC csr) adc_update_clock adc_input_signal adc_data_format adc_input_range
----------------------	---	---

```

        # CCURPMFC_ADC_BIPOLAR_5V
Output:  ccurpmfc_dac_volts_t          *dac_volts (pointer to DAC
                                         volts)
        uint    Raw[CCURPMFC_MAX_DAC_CHANNELS];
        double  Float[CCURPMFC_MAX_DAC_CHANNELS];
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (no error)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (library not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
        # CCURPMFC_LIB_ADC_IS_NOT_ACTIVE (ADC is not active)
        # CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.88 ccurPMFC_DAC_Read_Channels()

This call provides the user an easy method of reading the DAC channels. User can supply a channel mask. If pointer to *dac_csr* is NULL, then the routine itself computes the current DAC configuration. For performance, the user should get the current DAC configuration using the *ccurPMFC_DAC_CSR()* call to get the current settings and pass it to this routine. Hence, if the configuration is not changed, the user can continuously invoke *ccurPMFC_DAC_Read_Channels()* routine without incurring the additional overhead of routine calling the *ccurPMFC_DAC_CSR()* call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Read_Channels(void          *Handle,
                                     _ccurpmfc_dac_channel_mask_t ChanMask,
                                     _ccurpmfc_dac_csr_t          *dac_csr,
                                     ccurpmfc_dac_volts_t          *dac_volts)

```

Description: Read DAC Channels

```

Input:  void          *Handle          (Handle pointer)
        _ccurpmfc_dac_channel_mask_t ChanMask      (specify channel mask)
        # CCURPMFC_DAC_CHANNEL_MASK_0
        # CCURPMFC_DAC_CHANNEL_MASK_1
        # CCURPMFC_DAC_CHANNEL_MASK_2
        # CCURPMFC_DAC_CHANNEL_MASK_3
        # CCURPMFC_DAC_CHANNEL_MASK_4
        # CCURPMFC_DAC_CHANNEL_MASK_5
        # CCURPMFC_DAC_CHANNEL_MASK_6
        # CCURPMFC_DAC_CHANNEL_MASK_7
        # CCURPMFC_DAC_CHANNEL_MASK_8
        # CCURPMFC_DAC_CHANNEL_MASK_9
        # CCURPMFC_DAC_CHANNEL_MASK_10
        # CCURPMFC_DAC_CHANNEL_MASK_11
        # CCURPMFC_DAC_CHANNEL_MASK_12
        # CCURPMFC_DAC_CHANNEL_MASK_13
        # CCURPMFC_DAC_CHANNEL_MASK_14
        # CCURPMFC_DAC_CHANNEL_MASK_15
        # CCURPMFC_ALL_DAC_CHANNELS_MASK
        _ccurpmfc_dac_csr_t          *dac_csr (pointer to DAC csr)
        _ccurpmfc_daccsr_busy_t      dac_interface_busy
        # CCURPMFC_DAC_IDLE
        # CCURPMFC_DAC_BUSY
        _ccurpmfc_daccsr_powerdown_t dac_powerdown
        # CCURPMFC_DAC_OPERATIONAL
        # CCURPMFC_DAC_POWERDOWN
        _ccurpmfc_daccsr_updmode_t   dac_update_mode
        # CCURPMFC_DAC_MODE_IMMEDIATE
        # CCURPMFC_DAC_MODE_SYNCHRONIZED

```

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```

    _ccurpmfc_daccsr_data_format_t      dac_data_format
    # CCURPMFC_DAC_OFFSET_BINARY
    # CCURPMFC_DAC_TWOS_COMPLEMENT
    _ccurpmfc_daccsr_output_select_t    dac_output_select
    # CCURPMFC_DAC_SINGLE_ENDED
    # CCURPMFC_DAC_DIFFERENTIAL
    _ccurpmfc_daccsr_output_range_t     dac_output_range
    # CCURPMFC_DAC_SINGLE_ENDED_UNIPOLAR_10V
    # CCURPMFC_DAC_SINGLE_ENDED_BIPOLAR_5V
    # CCURPMFC_DAC_SINGLE_ENDED_BIPOLAR_10V
    # CCURPMFC_DAC_SINGLE_ENDED_UNIPOLAR_20V

    # CCURPMFC_DAC_DIFFERENTIAL_UNIPOLAR_10V
    # CCURPMFC_DAC_DIFFERENTIAL_BIPOLAR_10V
    # CCURPMFC_DAC_DIFFERENTIAL_BIPOLAR_20V
    # CCURPMFC_DAC_DIFFERENTIAL_UNIPOLAR_20V
Output:  ccurpmfc_dac_volts_t            *dac_volts (pointer to DAC volts)
        uint      Raw[CCURPMFC_MAX_DAC_CHANNELS];
        double    Float[CCURPMFC_MAX_DAC_CHANNELS];
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (no error)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (library not open)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.89 ccurPMFC_DAC_Reset_Fifo()

This call resets the DAC fifo to the power-on state. User can elect to activate the FIFO after a reset.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_DAC_Reset_Fifo(void          *Handle,
                               _ccurpmfc_dac_fifo_reset_t activate)

Description: DAC Reset Fifo

Input:  void          *Handle (handle pointer)
        _ccurpmfc_dac_fifo_reset_t activate (activate converter)
        # CCURPMFC_DAC_FIFO_ACTIVATE
        # CCURPMFC_DAC_FIFO_RESET

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.90 ccurPMFC_DAC_Set_CSR()

This call sets the DAC control registers for the selected channel group.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_DAC_Set_CSR (void          *Handle,
                          _ccurpmfc_dac_mask_t dac_mask,
                          ccurpmfc_dac_csr_t *dac_csr)

```

Description: Set DAC Control and Status information

```
Input:  void                                *Handle (Handle pointer)
        _ccurpmfc_dac_mask_t                dac_mask (selected DAC mask)
        # CCURPMFC_DAC_MASK_0_3
        # CCURPMFC_DAC_MASK_4_7
        # CCURPMFC_DAC_MASK_8_11
        # CCURPMFC_DAC_MASK_12_15
        ccurpmfc_dac_csr_t                  *dac_csr (pointer to DAC csr)
        _ccurpmfc_daccsr_powerdown_t       dac_powerdown
        # CCURPMFC_DAC_OPERATIONAL
        # CCURPMFC_DAC_POWERDOWN
        # CCURPMFC_DAC_POWERDOWN_DO_NOT_CHANGE
        _ccurpmfc_daccsr_updmode_t         dac_update_mode
        # CCURPMFC_DAC_MODE_IMMEDIATE
        # CCURPMFC_DAC_MODE_SYNCHRONIZED
        # CCURPMFC_DAC_MODE_DO_NOT_CHANGE
        _ccurpmfc_daccsr_data_format_t     dac_data_format
        # CCURPMFC_DAC_OFFSET_BINARY
        # CCURPMFC_DAC_TWOS_COMPLEMENT
        # CCURPMFC_DAC_DATA_FORMAT_DO_NOT_CHANGE
        _ccurpmfc_daccsr_output_select_t   dac_output_select
        # CCURPMFC_DAC_SINGLE_ENDED
        # CCURPMFC_DAC_DIFFERENTIAL
        # CCURPMFC_DAC_OUTPUT_SELECT_DO_NOT_CHANGE
        _ccurpmfc_daccsr_output_range_t    dac_output_range
        # CCURPMFC_DAC_SINGLE_ENDED_UNIPOLAR_10V
        # CCURPMFC_DAC_SINGLE_ENDED_BIPOLAR_5V
        # CCURPMFC_DAC_SINGLE_ENDED_BIPOLAR_10V
        # CCURPMFC_DAC_SINGLE_ENDED_UNIPOLAR_20V

        # CCURPMFC_DAC_DIFFERENTIAL_UNIPOLAR_10V
        # CCURPMFC_DAC_DIFFERENTIAL_BIPOLAR_10V
        # CCURPMFC_DAC_DIFFERENTIAL_BIPOLAR_20V
        # CCURPMFC_DAC_DIFFERENTIAL_UNIPOLAR_20V

        # CCURPMFC_DAC_OUTPUT_RANGE_DO_NOT_CHANGE
Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR              (successful)
        # CCURPMFC_LIB_BAD_HANDLE            (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN              (device not open)
        # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION       (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE     (DAC is not active)
*****/
```

2.2.91 ccurPMFC_DAC_Set_Driver_Write_Mode()

This call sets the current driver write mode. When a *write(2)* system call is issued, it is this mode that determines the type of DAC write being performed by the driver. Refer to the *write(2)* system call under *Direct Driver Access* section for more information on the various modes.

```
/******
ccurPMFC_DAC_Set_Driver_Write_Mode()
_ccurpmfc_lib_error_number_t
ccurPMFC_Select_Driver_DAC_Write_Mode (void                                *Handle,
                                       _ccurpmfc_driver_DAC_write_mode_t  mode)

Description: Select Driver DAC_Write Mode

Input:  void                                *Handle (Handle pointer)
        _ccurpmfc_driver_DAC_write_mode_t mode (select write mode)
```



```

        # CCURPMFC_DAC_PIO_CHANNEL
        # CCURPMFC_DAC_PIO_FIFO
Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
*****/

```

2.2.92 ccurPMFC_DAC_Set_Fifo_Channel_Select()

This call allows the user to select a set of channels that need to be provided in the DAC FIFO or the DAC channel registers. Only samples for these selected channels are placed in the FIFO during sample generation. Unlike the ADC Fifo channel select option, this DAC FIFO channel select option also restricts DAC channel register writes to those selected by this option. The advantage for implementing this option for DAC channel registers in addition to DAC FIFO is that the user can perform DMA operations to generate samples on selected channels without affecting the output of those channels that have not been included in the channel selection.

```

/*****
 _ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Set_Fifo_Channel_Select(void      *Handle,
                                       _ccurpmfc_dac_channel_mask_t
                                       dac_fifo_channel_select_mask)

Description: DAC Set Fifo Channel Selection

Input:   void      *Handle      (handle pointer)
         _ccurpmfc_dac_channel_mask_t
         dac_fifo_channel_select_mask (channel select mask)
        # CCURPMFC_DAC_CHANNEL_MASK_0
        # CCURPMFC_DAC_CHANNEL_MASK_1
        # CCURPMFC_DAC_CHANNEL_MASK_2
        # CCURPMFC_DAC_CHANNEL_MASK_3
        # CCURPMFC_DAC_CHANNEL_MASK_4
        # CCURPMFC_DAC_CHANNEL_MASK_5
        # CCURPMFC_DAC_CHANNEL_MASK_6
        # CCURPMFC_DAC_CHANNEL_MASK_7
        # CCURPMFC_DAC_CHANNEL_MASK_8
        # CCURPMFC_DAC_CHANNEL_MASK_9
        # CCURPMFC_DAC_CHANNEL_MASK_10
        # CCURPMFC_DAC_CHANNEL_MASK_11
        # CCURPMFC_DAC_CHANNEL_MASK_12
        # CCURPMFC_DAC_CHANNEL_MASK_13
        # CCURPMFC_DAC_CHANNEL_MASK_14
        # CCURPMFC_DAC_CHANNEL_MASK_15
        # CCURPMFC_ALL_DAC_CHANNELS_MASK

Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.93 ccurPMFC_DAC_Set_Fifo_Threshold()

This call allows the user to set the DAC FIFO threshold.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_DAC_Set_Fifo_Threshold(void *Handle,
                                  uint dac_threshold)

  Description: DAC Set Fifo Threshold

  Input:   void          *Handle      (handle pointer)
           uint          dac_threshold (DAC fifo threshold)

  Output:  none

  Return:  _ccurpmfc_lib_error_number_t
           # CCURPMFC_LIB_NO_ERROR      (successful)
           # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
           # CCURPMFC_LIB_NOT_OPEN      (device not open)
           # CCURPMFC_LIB_INVALID_ARG   (invalid argument)
           # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
           # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/
```

2.2.94 ccurPMFC_DAC_Set_Fifo_Write_Count()

This call allows the user to set the DAC FIFO write count. This is only used for debug.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_DAC_Set_Fifo_Write_Count(void *Handle,
                                     uint dac_write_count)

  Description: DAC Set Fifo Write Count

  Input:   void          *Handle      (handle pointer)
           uint          dac_write_count (DAC fifo write count)

  Output:  none

  Return:  _ccurpmfc_lib_error_number_t
           # CCURPMFC_LIB_NO_ERROR      (successful)
           # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
           # CCURPMFC_LIB_NOT_OPEN      (device not open)
           # CCURPMFC_LIB_INVALID_ARG   (invalid argument)
           # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
           # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/
```

2.2.95 ccurPMFC_DAC_Set_Gain_Cal()

This call is used to set the DAC gain calibration for all the channels.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_DAC_Set_Gain_Cal(void          *Handle,
                             _ccurpmfc_dac_channel_mask_t ChanMask,
                             ccurpmfc_dac_cal_t *cal)

  Description: Set the DAC Offset Calibration data.

  Input:   void          *Handle      (handle pointer)
           _ccurpmfc_dac_channel_mask_t ChanMask (channel selection mask)
           # CCURPMFC_DAC_CHANNEL_MASK_0
           # CCURPMFC_DAC_CHANNEL_MASK_1
           # CCURPMFC_DAC_CHANNEL_MASK_2
*****/
```

```

# CCURPMFC_DAC_CHANNEL_MASK_3
# CCURPMFC_DAC_CHANNEL_MASK_4
# CCURPMFC_DAC_CHANNEL_MASK_5
# CCURPMFC_DAC_CHANNEL_MASK_6
# CCURPMFC_DAC_CHANNEL_MASK_7
# CCURPMFC_DAC_CHANNEL_MASK_8
# CCURPMFC_DAC_CHANNEL_MASK_9
# CCURPMFC_DAC_CHANNEL_MASK_10
# CCURPMFC_DAC_CHANNEL_MASK_11
# CCURPMFC_DAC_CHANNEL_MASK_12
# CCURPMFC_DAC_CHANNEL_MASK_13
# CCURPMFC_DAC_CHANNEL_MASK_14
# CCURPMFC_DAC_CHANNEL_MASK_15
# CCURPMFC_ALL_DAC_CHANNELS_MASK
ccurpmfc_dac_cal_t *cal (pointer to board cal)
uint Raw[CCURPMFC_MAX_DAC_CHANNELS]
double Float[CCURPMFC_MAX_DAC_CHANNELS]
double CalibrationReferenceVoltage[CCURPMFC_MAX_DAC_CHANNELS]
Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.96 ccurPMFC_DAC_Set_Offset_Cal()

This call is used to set the DAC offset calibration for all the channels.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Set_Offset_Cal(void *Handle,
_ccurpmfc_dac_channel_mask_t ChanMask,
ccurpmfc_dac_cal_t *cal)

```

Description: Set the DAC Offset Calibration data.

```

Input: void *Handle (handle pointer)
_ccurpmfc_dac_channel_mask_t ChanMask (channel selection mask)
# CCURPMFC_DAC_CHANNEL_MASK_0
# CCURPMFC_DAC_CHANNEL_MASK_1
# CCURPMFC_DAC_CHANNEL_MASK_2
# CCURPMFC_DAC_CHANNEL_MASK_3
# CCURPMFC_DAC_CHANNEL_MASK_4
# CCURPMFC_DAC_CHANNEL_MASK_5
# CCURPMFC_DAC_CHANNEL_MASK_6
# CCURPMFC_DAC_CHANNEL_MASK_7
# CCURPMFC_DAC_CHANNEL_MASK_8
# CCURPMFC_DAC_CHANNEL_MASK_9
# CCURPMFC_DAC_CHANNEL_MASK_10
# CCURPMFC_DAC_CHANNEL_MASK_11
# CCURPMFC_DAC_CHANNEL_MASK_12
# CCURPMFC_DAC_CHANNEL_MASK_13
# CCURPMFC_DAC_CHANNEL_MASK_14
# CCURPMFC_DAC_CHANNEL_MASK_15
# CCURPMFC_ALL_DAC_CHANNELS_MASK
ccurpmfc_dac_cal_t *cal (pointer to board cal)
uint Raw[CCURPMFC_MAX_DAC_CHANNELS]
double Float[CCURPMFC_MAX_DAC_CHANNELS]
double CalibrationReferenceVoltage[CCURPMFC_MAX_DAC_CHANNELS]

```

```

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.97 ccurPMFC_DAC_Set_Update_Source_Select()

This call allows the user to set the DAC update source. Users can select either one of the defined clock generators or software update to cause the samples in the FIFO to be sent out.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Set_Update_Source_Select (void                *Handle,
                                       _ccurpmfc_daccsr_update_source_t
                                       update_source)

Description: Set DAC Update Source Select

Input:   void                *Handle      (Handle pointer)
         _ccurpmfc_daccsr_update_source_t update_source (pointer to update
                                                         source)

         # CCURPMFC_DAC_UPDATE_SOFTWARE
         # CCURPMFC_DAC_UPDATE_CLOCK_0
         # CCURPMFC_DAC_UPDATE_CLOCK_1
         # CCURPMFC_DAC_UPDATE_CLOCK_2
         # CCURPMFC_DAC_UPDATE_CLOCK_3
         # CCURPMFC_DAC_UPDATE_CLOCK_4
         # CCURPMFC_DAC_UPDATE_CLOCK_5
         # CCURPMFC_DAC_UPDATE_CLOCK_6

Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.98 ccurPMFC_DAC_Wait_For_Channel_Idle()

This call is used when writing to channel registers to ensure that we are not writing too fast. The DAC must be idle prior to the corresponding channel write, otherwise, the data would not be sent out.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Wait_For_Channel_Idle (void                *Handle,
                                       _ccurpmfc_dac_channel_t dac_channel)

Description: Wait for DAC Channel to go idle

Input:   void                *Handle      (Handle pointer)
         _ccurpmfc_dac_channel_t dac_channel (dac channel number)

         # CCURPMFC_DAC_CHANNEL_0
         # CCURPMFC_DAC_CHANNEL_1
         # CCURPMFC_DAC_CHANNEL_2
         # CCURPMFC_DAC_CHANNEL_3
         # CCURPMFC_DAC_CHANNEL_4

```

```

# CCURPMFC_DAC_CHANNEL_5
# CCURPMFC_DAC_CHANNEL_6
# CCURPMFC_DAC_CHANNEL_7
# CCURPMFC_DAC_CHANNEL_8
# CCURPMFC_DAC_CHANNEL_9
# CCURPMFC_DAC_CHANNEL_10
# CCURPMFC_DAC_CHANNEL_11
# CCURPMFC_DAC_CHANNEL_12
# CCURPMFC_DAC_CHANNEL_13
# CCURPMFC_DAC_CHANNEL_14
# CCURPMFC_DAC_CHANNEL_15
Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_IOCTL_FAILED (driver ioctl call
failed)
# CCURPMFC_LIB_INVALID_ARG (Invalid argument)
# CCURPMFC_LIB_DAC_FIFO_UNDERFLOW (DAC Fifo underflow)
# CCURPMFC_LIB_DAC_IS_BUSY (DAC is busy)
*****/

```

2.2.99 ccurPMFC_DAC_Wait_For_Fifo_To_Drain()

This call is used prior to writing to the DAC fifo to ensure that there is enough sample space available to complete the write without getting an overflow condition. User needs to specify the threshold level to wait for the FIFO to reach, before returning to the caller. Note that if the threshold is too low, it is possible that the FIFO could experience an underflow condition prior to adding more samples to the FIFO.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Wait_For_Fifo_To_Drain (void *Handle,
uint fifo_threshold)

Description: Wait for DAC Fifo to drain

Input: void *Handle (Handle pointer)
uint fifo_threshold (fifo threshold)
Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_IOCTL_FAILED (driver ioctl call
failed)
# CCURPMFC_LIB_INVALID_ARG (Invalid argument)
# CCURPMFC_LIB_DAC_FIFO_UNDERFLOW (DAC Fifo underflow)
*****/

```

2.2.100 ccurPMFC_DAC_Write_Channels()

This call provides the user an easy method of writing the DAC channels. User can supply a channel mask. If pointer to *dac_csr* is NULL, then the routine itself computes the current DAC configuration. For performance, the user should get the current DAC configuration using the *ccurPMFC_DAC_CSR()* call to get the current settings and pass it to this routine. Hence, if the configuration is not changed, the user can continuously invoke *ccurPMFC_DAC_Write_Channels()* routine without incurring the additional overhead of routine calling the *ccurPMFC_DAC_CSR()* call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DAC_Write_Channels(void *Handle,

```

```

        _ccurpmfc_dac_channel_mask_t ChanMask,
        _ccurpmfc_dac_csr_t          *dac_csr,
        ccurpmfc_dac_volts_t        *dac_volts)

```

Description: Read DAC Channels

```

Input:  void          *Handle          (Handle pointer)
        _ccurpmfc_dac_channel_mask_t ChanMask      (specify channel mask)
        # CCURPMFC_DAC_CHANNEL_MASK_0
        # CCURPMFC_DAC_CHANNEL_MASK_1
        # CCURPMFC_DAC_CHANNEL_MASK_2
        # CCURPMFC_DAC_CHANNEL_MASK_3
        # CCURPMFC_DAC_CHANNEL_MASK_4
        # CCURPMFC_DAC_CHANNEL_MASK_5
        # CCURPMFC_DAC_CHANNEL_MASK_6
        # CCURPMFC_DAC_CHANNEL_MASK_7
        # CCURPMFC_DAC_CHANNEL_MASK_8
        # CCURPMFC_DAC_CHANNEL_MASK_9
        # CCURPMFC_DAC_CHANNEL_MASK_10
        # CCURPMFC_DAC_CHANNEL_MASK_11
        # CCURPMFC_DAC_CHANNEL_MASK_12
        # CCURPMFC_DAC_CHANNEL_MASK_13
        # CCURPMFC_DAC_CHANNEL_MASK_14
        # CCURPMFC_DAC_CHANNEL_MASK_15
        # CCURPMFC_ALL_DAC_CHANNELS_MASK
        _ccurpmfc_dac_csr_t          *dac_csr (pointer to DAC csr)
        _ccurpmfc_daccsr_busy_t      dac_interface_busy
        # CCURPMFC_DAC_IDLE
        # CCURPMFC_DAC_BUSY
        _ccurpmfc_daccsr_powerdown_t dac_powerdown
        # CCURPMFC_DAC_OPERATIONAL
        # CCURPMFC_DAC_POWERDOWN
        _ccurpmfc_daccsr_updmode_t   dac_update_mode
        # CCURPMFC_DAC_MODE_IMMEDIATE
        # CCURPMFC_DAC_MODE_SYNCHRONIZED
        _ccurpmfc_daccsr_data_format_t dac_data_format
        # CCURPMFC_DAC_OFFSET_BINARY
        # CCURPMFC_DAC_TWOS_COMPLEMENT
        _ccurpmfc_daccsr_output_select_t dac_output_select
        # CCURPMFC_DAC_SINGLE_ENDED
        # CCURPMFC_DAC_DIFFERENTIAL
        _ccurpmfc_daccsr_output_range_t dac_output_range
        # CCURPMFC_DAC_SINGLE_ENDED_UNIPOLAR_10V
        # CCURPMFC_DAC_SINGLE_ENDED_BIPOLAR_5V
        # CCURPMFC_DAC_SINGLE_ENDED_BIPOLAR_10V
        # CCURPMFC_DAC_SINGLE_ENDED_UNIPOLAR_20V

        # CCURPMFC_DAC_DIFFERENTIAL_UNIPOLAR_10V
        # CCURPMFC_DAC_DIFFERENTIAL_BIPOLAR_10V
        # CCURPMFC_DAC_DIFFERENTIAL_BIPOLAR_20V
        # CCURPMFC_DAC_DIFFERENTIAL_UNIPOLAR_20V
        ccurpmfc_dac_volts_t          *dac_volts (pointer to DAC volts)
        uint      Raw[CCURPMFC_MAX_DAC_CHANNELS];
        double    Float[CCURPMFC_MAX_DAC_CHANNELS];

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (no error)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (library not open)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_VOLTAGE_NOT_IN_RANGE (voltage not in range)
        # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)

```

*****/

2.2.101 ccurPMFC_DAC_Write_Channels_Calibration()

This call allows the user to write the calibration registers from a user supplied calibration file.

```

/*****
  ccurPMFC_DAC_Write_Channels_Calibration()

  Description: Write Channels Calibration

  Input:   void   *Handle           (handle pointer)
  Output:  char   *filename         (pointer to filename)
  Return:  _ccurpmfc_lib_error_number_t
          # CCURPMFC_LIB_NO_ERROR      (successful)
          # CCURPMFC_LIB_BAD_HANDLE   (no/bad handler supplied)
          # CCURPMFC_LIB_NOT_OPEN     (library not open)
          # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
          # CCURPMFC_LIB_CANNOT_OPEN_FILE (cannot open calib. file)
          # CCURPMFC_LIB_INVALID_ARG  (invalid argument)
          # CCURPMFC_LIB_DAC_IS_NOT_ACTIVE (DAC is not active)
*****/

```

2.2.102 ccurPMFC_DataToVolts()

This routine takes a raw analog input data value and converts it to a floating point voltage based on the supplied format. Format can be *CCURPMFC_TWOS_COMPLEMENT* or *CCURPMFC_OFFSET_BINARY*. The data supplied in *us_data* must not be greater than the hardware resolution bits *CCURPMFC_ADC_RESOLUTION_BITS* supported by the board. Data greater than this will be masked out.

```

/*****
  double ccurPMFC_DataToVolts(int us_data, ccurpmfc_volt_convert_t *conv)

  Description: Convert Data to volts

  Input:   int           us_data      (data to convert)
          ccurpmfc_volt_convert_t *conv (pointer to conversion struct)
          double         VoltageRange (maximum voltage range)
          _ccurpmfc_csr_dataformat_t Format (format)
          # CCURPMFC_OFFSET_BINARY
          # CCURPMFC_TWOS_COMPLEMENT
          ccurpmfc_bool  BiPolar     (bi-polar)
          # CCURPMFC_TRUE
          # CCURPMFC_FALSE
          int            ResolutionBits (Number of resolution bits)

  Output:  none
  Return:  double         volts      (returned volts)
*****/

```

2.2.103 ccurPMFC_Destroy_AllUserProcess()

The purpose of this call is to destroy all User Processes that have been previously created by the *ccurPMFC_Create_UserProcess()* command. (*This is an experimental API for debugging and testing.*)

```

/*****
  _ccurpmfc_lib_error_number_t ccurPMFC_Destroy_AllUserProcess(void *Handle)

  Description: Destroy all created user processes

  Input:   void           *Handle     (Handle pointer)

```

```

Output: none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
*****/

```

2.2.104 ccurPMFC_Destroy_UserDioCosInterruptHandler()

The purpose of this call is to destroy the User DIO COS Interrupt handler that was created earlier with the *ccurPMFC_Create_UserDioCosInterruptHandler()* call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Destroy_UserDioCosInterruptHandler(void *Handle)

Description: Destroy a previously created User DIO COS Interrupt Handler

Input:   void          *Handle          (Handle pointer)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
         # CCURPMFC_LIB_IOCTL_FAILED      (ioctl failed)
         # CCURPMFC_LIB_IO_ERROR          (failed to terminate
                                         handler)
*****/

```

2.2.105 ccurPMFC_Destroy_UserProcess()

The purpose of this call is to destroy the User Process that have been previously created by the *ccurPMFC_Create_UserProcess()* call. *(This is an experimental API for debugging and testing).*

```

/*****
_ccurpmfc_lib_error_number_t ccurPMFC_Destroy_UserProcess(void *Handle,
                                                           _ccurpmfc_UserFunction_t **UFuncHandle)

Description: Destroy an already created user process

Input:   void          *Handle          (Handle pointer)
         _ccurpmfc_UserFunction_t **UFuncHandle (pointer to user handle)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
*****/

```

2.2.106 ccurPMFC_DIO_Activate()

This call must be the first call to activate the DIO. Without activation, all other calls will fail. The user can also use this call to return the current state of the DIO without any change.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Activate (void          *Handle,
                      _ccurpmfc_dio_all_enable_t activate,
                      _ccurpmfc_dio_all_enable_t *current_state)

Description: Activate/DeActivate DIO module

Input:   void          *Handle          (Handle pointer)
         _ccurpmfc_dio_all_enable_t activate (activate/deactivate)
         # CCURPMFC_DIO_ALL_DISABLE

```



```

# CCURPMFC_DIO_ALL_ENABLE
# CCURPMFC_DIO_ALL_ENABLE_DO_NOT_CHANGE
Output:  _ccurpmfc_dio_all_enable_t      *current_state  (active/deactive)
# CCURPMFC_DIO_ALL_DISABLE
# CCURPMFC_DIO_ALL_ENABLE
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR                (successful)
# CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN                (device not open)
# CCURPMFC_LIB_INVALID_ARG            (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION         (local region not present)
*****/

```

2.2.107 ccurPMFC_DIO_Get_Channels_Polarity()

This call allows the user to get the polarity for the DIO channels. The *ChannelSelectMask* is used to retrieve polarity settings for selected channels.

For input channels, a value of *CCURPMFC_DIO_INPUT_LOW_TRUE* or '0' for polarity indicates low true, while a value of *CCURPMFC_DIO_INPUT_HIGH_TRUE* or '1' for polarity indicates high true.

For output channels, a value of *CCURPMFC_DIO_OUTPUT_LOW* or '0' for polarity indicates low or 0 volts, while a value of *CCURPMFC_DIO_OUTPUT_HIGH* or '1' for polarity indicates high or +5 volts.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_Channels_Polarity(void          *Handle,
                                             ccurpmfc_dio_channels_t  DIO_ChannelsPolarity,
                                             ccurpmfc_dio_channels_t  ChannelSelectMask)

```

Description: Get Channels Polarity

```

Input:  void          *Handle          (handle pointer)
        ccurpmfc_dio_channels_t  ChannelSelectMask (channel selection)
        # NULL                          (select all channels)
        # u_int32_t   ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12
        # CCURPMFC_DIO_CHANNEL_MASK_13
        # CCURPMFC_DIO_CHANNEL_MASK_14
        # CCURPMFC_DIO_CHANNEL_MASK_15
        # CCURPMFC_DIO_CHANNEL_MASK_16
        # CCURPMFC_DIO_CHANNEL_MASK_17
        # CCURPMFC_DIO_CHANNEL_MASK_18
        # CCURPMFC_DIO_CHANNEL_MASK_19
        # CCURPMFC_DIO_CHANNEL_MASK_20
        # CCURPMFC_DIO_CHANNEL_MASK_21
        # CCURPMFC_DIO_CHANNEL_MASK_22
        # CCURPMFC_DIO_CHANNEL_MASK_23
        # CCURPMFC_DIO_CHANNEL_MASK_24
        # CCURPMFC_DIO_CHANNEL_MASK_25

```

```

# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Output: ccurpmfc_dio_channels_t DIO_ChannelsPolarity (channels polarity
                                               registers)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.108 ccurPMFC_DIO_Get_COS_Channels_Edge_Sense()

This call returns to the user the settings for the change-of-state to sense the rising or falling edge of the signal on input for all the channels. The *ChannelSelectMask* is used to retrieve edge sense settings for selected channels. A value of *CCURPMFC_DIO_COS_FALLING_EDGE* or '0' represents sensing of falling edge of input signal while a value of *CCURPMFC_DIO_COS_RISING_EDGE* or '1' represents sensing of rising edge of input signal.

```
/******  
_ccurpmfc_lib_error_number_t  
ccurPMFC_DIO_Get_COS_Channels_Edge_Sense(void      *Handle,  
                                           ccurpmfc_dio_channels_t  DIO_COS_ChannelsEdgeSense,  
                                           ccurpmfc_dio_channels_t  ChannelSelectMask)
```

Description: Get COS Channels Edge Sense

```
Input:  void      *Handle      (handle pointer)  
        ccurpmfc_dio_channels_t ChannelSelectMask (channel selection)  
        # NULL      (select all channels)  
        # u_int32_t  ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]  
          # CCURPMFC_DIO_CHANNEL_MASK_0  
          # CCURPMFC_DIO_CHANNEL_MASK_1  
          # CCURPMFC_DIO_CHANNEL_MASK_2  
          # CCURPMFC_DIO_CHANNEL_MASK_3  
          # CCURPMFC_DIO_CHANNEL_MASK_4  
          # CCURPMFC_DIO_CHANNEL_MASK_5  
          # CCURPMFC_DIO_CHANNEL_MASK_6  
          # CCURPMFC_DIO_CHANNEL_MASK_7  
          # CCURPMFC_DIO_CHANNEL_MASK_8  
          # CCURPMFC_DIO_CHANNEL_MASK_9  
          # CCURPMFC_DIO_CHANNEL_MASK_10  
          # CCURPMFC_DIO_CHANNEL_MASK_11  
          # CCURPMFC_DIO_CHANNEL_MASK_12  
          # CCURPMFC_DIO_CHANNEL_MASK_13  
          # CCURPMFC_DIO_CHANNEL_MASK_14  
          # CCURPMFC_DIO_CHANNEL_MASK_15  
          # CCURPMFC_DIO_CHANNEL_MASK_16  
          # CCURPMFC_DIO_CHANNEL_MASK_17  
          # CCURPMFC_DIO_CHANNEL_MASK_18  
          # CCURPMFC_DIO_CHANNEL_MASK_19  
          # CCURPMFC_DIO_CHANNEL_MASK_20  
          # CCURPMFC_DIO_CHANNEL_MASK_21  
          # CCURPMFC_DIO_CHANNEL_MASK_22  
          # CCURPMFC_DIO_CHANNEL_MASK_23  
          # CCURPMFC_DIO_CHANNEL_MASK_24  
          # CCURPMFC_DIO_CHANNEL_MASK_25  
          # CCURPMFC_DIO_CHANNEL_MASK_26  
          # CCURPMFC_DIO_CHANNEL_MASK_27  
          # CCURPMFC_DIO_CHANNEL_MASK_28  
          # CCURPMFC_DIO_CHANNEL_MASK_29  
          # CCURPMFC_DIO_CHANNEL_MASK_30  
          # CCURPMFC_DIO_CHANNEL_MASK_31  
          # CCURPMFC_DIO_ALL_CHANNELS_MASK  
        CCURPMFC_DIO_MAX_REGISTERS can be one of:  
          # CCURPMFC_DIO_CHAN_00_31  
          # CCURPMFC_DIO_CHAN_32_63  
          # CCURPMFC_DIO_CHAN_64_95  
Output: ccurpmfc_dio_channels_t  DIO_COS_ChannelsEdgeSense (COS channels  
                                                             edge sense registers)  
        # u_int32_t  ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]  
          # CCURPMFC_DIO_CHANNEL_MASK_0  
          # CCURPMFC_DIO_CHANNEL_MASK_1  
          # CCURPMFC_DIO_CHANNEL_MASK_2
```

```

# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR           (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.109 ccurPMFC_DIO_Get_COS_Channels_Enable()

This call returns to the user the settings for the change-of-state enable registers all the channels. The *ChannelSelectMask* is used to retrieve enable settings for selected channels. A value of *CCURPMFC_DIO_COS_IGNORE* or '0' ignores change-of-state while a value of *CCURPMFC_DIO_COS_ENABLE* or '1' represents enabling change-of-state for the selected channels.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_COS_Channels_Enable(void          *Handle,
                                         ccurpmfc_dio_channels_t DIO_COS_ChannelsEnable,
                                         ccurpmfc_dio_channels_t ChannelSelectMask)

```

Description: Get COS Channels Enable Setting

```

Input:  void          *Handle          (handle pointer)
        ccurpmfc_dio_channels_t ChannelSelectMask (channel selection)
        # NULL              (select all channels)
        # u_int32_t  ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0

```

```

# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Output: ccurpmfc_dio_channels_t    DIO_COS_ChannelsEnable (COS channels
                                     enable registers)
# u_int32_t    ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23

```

```

# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR                (successful)
# CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN                (device not open)
# CCURPMFC_LIB_INVALID_ARG            (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE      (DIO is not active)
*****/

```

2.2.110 ccurPMFC_DIO_Get_COS_Channels_Mode()

This call returns to the user the settings for the change-of-state mode registers all the channels. The *ChannelSelectMask* is used to retrieve mode settings for selected channels. A value of *CCURPMFC_DIO_COS_ANY_TRANSITION* or '0' detects change-of-state on any edge transition while a value of *CCURPMFC_DIO_COS_RISING_OR_FALLING_TRANSITION* or '1' represents enabling change-of-state for either rising edge or falling edge depending on the channel edge sense setting for the selected channels.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_COS_Channels_Mode(void          *Handle,
                                     ccurpmfc_dio_channels_t  DIO_COS_ChannelsMode,
                                     ccurpmfc_dio_channels_t  ChannelSelectMask)

```

Description: Get COS Channels Mode Setting

```

Input:  void          *Handle          (handle pointer)
        ccurpmfc_dio_channels_t ChannelSelectMask (channel selection)
        # NULL              (select all channels)
        # u_int32_t  ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12
        # CCURPMFC_DIO_CHANNEL_MASK_13
        # CCURPMFC_DIO_CHANNEL_MASK_14
        # CCURPMFC_DIO_CHANNEL_MASK_15
        # CCURPMFC_DIO_CHANNEL_MASK_16
        # CCURPMFC_DIO_CHANNEL_MASK_17
        # CCURPMFC_DIO_CHANNEL_MASK_18
        # CCURPMFC_DIO_CHANNEL_MASK_19

```

```

# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Output: ccurpmfc_dio_channels_t    DIO_COS_ChannelsMode (COS channels
                                                Mode registers)
# u_int32_t    ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR                (successful)
# CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN                (device not open)
# CCURPMFC_LIB_INVALID_ARG            (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION         (local region not present)

```

```
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/
```

2.2.111 ccurPMFC_DIO_Get_COS_Channels_Overflow()

This call returns to the user the state of the change-of-state overflow registers for all the channels. The *ChannelSelectMask* is used to retrieve overflow settings for selected channels. A value of *CCURPMFC_DIO_COS_OVERFLOW_DID_NOT_OCCUR* or '0' indicates that no overflow occurred while a value of *CCURPMFC_DIO_COS_OVERFLOW_OCCURRED* or '1' indicates that an overflow condition occurred for the selected channels. An overflow condition is set when a change-of-state condition is detected on a channel that previously detected a change-of-state condition without its status being cleared.

```
/******
```

```
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_COS_Channels_Overflow(void          *Handle,
                                         ccurpmfc_dio_channels_t  DIO_COS_ChannelsOverflow,
                                         ccurpmfc_dio_channels_t  ChannelSelectMask)
```

Description: Get COS Channels Overflow State

```
Input:  void          *Handle          (handle pointer)
        ccurpmfc_dio_channels_t ChannelSelectMask (channel selection)
        # NULL          (select all channels)
        # u_int32_t    ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12
        # CCURPMFC_DIO_CHANNEL_MASK_13
        # CCURPMFC_DIO_CHANNEL_MASK_14
        # CCURPMFC_DIO_CHANNEL_MASK_15
        # CCURPMFC_DIO_CHANNEL_MASK_16
        # CCURPMFC_DIO_CHANNEL_MASK_17
        # CCURPMFC_DIO_CHANNEL_MASK_18
        # CCURPMFC_DIO_CHANNEL_MASK_19
        # CCURPMFC_DIO_CHANNEL_MASK_20
        # CCURPMFC_DIO_CHANNEL_MASK_21
        # CCURPMFC_DIO_CHANNEL_MASK_22
        # CCURPMFC_DIO_CHANNEL_MASK_23
        # CCURPMFC_DIO_CHANNEL_MASK_24
        # CCURPMFC_DIO_CHANNEL_MASK_25
        # CCURPMFC_DIO_CHANNEL_MASK_26
        # CCURPMFC_DIO_CHANNEL_MASK_27
        # CCURPMFC_DIO_CHANNEL_MASK_28
        # CCURPMFC_DIO_CHANNEL_MASK_29
        # CCURPMFC_DIO_CHANNEL_MASK_30
        # CCURPMFC_DIO_CHANNEL_MASK_31
        # CCURPMFC_DIO_ALL_CHANNELS_MASK
        CCURPMFC_DIO_MAX_REGISTERS can be one of:
        # CCURPMFC_DIO_CHAN_00_31
        # CCURPMFC_DIO_CHAN_32_63
        # CCURPMFC_DIO_CHAN_64_95
```

```
Output: ccurpmfc_dio_channels_t  DIO_COS_ChannelsOverflow (COS channels
                                                             Overflow registers)
```

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```

# u_int32_t    ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR           (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.112 ccurPMFC_DIO_Get_COS_Channels_Status()

This call returns to the user the state of the change-of-state status registers for all the channels. The *ChannelSelectMask* is used to retrieve status settings for selected channels. A value of *CCURPMFC_DIO_COS_DID_NOT_OCCUR* or '0' indicates that no change-of-state occurred while a value of *CCURPMFC_DIO_COS_OCCURRED* or '1' indicates that a change-of-state condition occurred for the selected channels. A change-of-state status is set when the hardware is enabled to detect a change of input signal transition and an input signal is received with the monitored transition.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_COS_Channels_Status(void          *Handle,
ccurpmfc_dio_channels_t    DIO_COS_ChannelsOStatus,
ccurpmfc_dio_channels_t    ChannelSelectMask)

```

Description: Get COS Channels Status

```

Input: void *Handle (handle pointer)
        ccurpmfc_dio_channels_t ChannelSelectMask (channel selection)
        # NULL (select all channels)
        # u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
          # CCURPMFC_DIO_CHANNEL_MASK_0
          # CCURPMFC_DIO_CHANNEL_MASK_1
          # CCURPMFC_DIO_CHANNEL_MASK_2
          # CCURPMFC_DIO_CHANNEL_MASK_3
          # CCURPMFC_DIO_CHANNEL_MASK_4
          # CCURPMFC_DIO_CHANNEL_MASK_5
          # CCURPMFC_DIO_CHANNEL_MASK_6
          # CCURPMFC_DIO_CHANNEL_MASK_7
          # CCURPMFC_DIO_CHANNEL_MASK_8
          # CCURPMFC_DIO_CHANNEL_MASK_9
          # CCURPMFC_DIO_CHANNEL_MASK_10
          # CCURPMFC_DIO_CHANNEL_MASK_11
          # CCURPMFC_DIO_CHANNEL_MASK_12
          # CCURPMFC_DIO_CHANNEL_MASK_13
          # CCURPMFC_DIO_CHANNEL_MASK_14
          # CCURPMFC_DIO_CHANNEL_MASK_15
          # CCURPMFC_DIO_CHANNEL_MASK_16
          # CCURPMFC_DIO_CHANNEL_MASK_17
          # CCURPMFC_DIO_CHANNEL_MASK_18
          # CCURPMFC_DIO_CHANNEL_MASK_19
          # CCURPMFC_DIO_CHANNEL_MASK_20
          # CCURPMFC_DIO_CHANNEL_MASK_21
          # CCURPMFC_DIO_CHANNEL_MASK_22
          # CCURPMFC_DIO_CHANNEL_MASK_23
          # CCURPMFC_DIO_CHANNEL_MASK_24
          # CCURPMFC_DIO_CHANNEL_MASK_25
          # CCURPMFC_DIO_CHANNEL_MASK_26
          # CCURPMFC_DIO_CHANNEL_MASK_27
          # CCURPMFC_DIO_CHANNEL_MASK_28
          # CCURPMFC_DIO_CHANNEL_MASK_29
          # CCURPMFC_DIO_CHANNEL_MASK_30
          # CCURPMFC_DIO_CHANNEL_MASK_31
          # CCURPMFC_DIO_ALL_CHANNELS_MASK
        CCURPMFC_DIO_MAX_REGISTERS can be one of:
          # CCURPMFC_DIO_CHAN_00_31
          # CCURPMFC_DIO_CHAN_32_63
          # CCURPMFC_DIO_CHAN_64_95
Output: ccurpmfc_dio_channels_t DIO_COS_ChannelsStatus (COS channels
                                                Status registers)
        # u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
          # CCURPMFC_DIO_CHANNEL_MASK_0
          # CCURPMFC_DIO_CHANNEL_MASK_1
          # CCURPMFC_DIO_CHANNEL_MASK_2
          # CCURPMFC_DIO_CHANNEL_MASK_3
          # CCURPMFC_DIO_CHANNEL_MASK_4
          # CCURPMFC_DIO_CHANNEL_MASK_5
          # CCURPMFC_DIO_CHANNEL_MASK_6
          # CCURPMFC_DIO_CHANNEL_MASK_7
          # CCURPMFC_DIO_CHANNEL_MASK_8
          # CCURPMFC_DIO_CHANNEL_MASK_9
          # CCURPMFC_DIO_CHANNEL_MASK_10
          # CCURPMFC_DIO_CHANNEL_MASK_11
          # CCURPMFC_DIO_CHANNEL_MASK_12
          # CCURPMFC_DIO_CHANNEL_MASK_13
          # CCURPMFC_DIO_CHANNEL_MASK_14
          # CCURPMFC_DIO_CHANNEL_MASK_15
          # CCURPMFC_DIO_CHANNEL_MASK_16
          # CCURPMFC_DIO_CHANNEL_MASK_17

```

```

# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR           (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.113 ccurPMFC_DIO_Get_Input_Channels_Filter()

This call allows the user to get the settings for the DIO channels input filters. The *ChannelSelectMask* is used to retrieve filter settings for selected channels. A value of *CCURPMFC_DIO_INPUT_FILTER_ENABLED* or '0' for filter indicates that the 100 nanosecond filter is enabled for the selected channel, while a value of *CCURPMFC_DIO_INPUT_FILTER_DISABLED* or '1' indicates that the filter is disabled. On powerup, filter for all channels are enabled.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_Input_Channels_Filter(void          *Handle,
                                         ccurpmfc_dio_channels_t  DIO_InputChannels,
                                         ccurpmfc_dio_channels_t  ChannelSelectMask)

```

Description: Get Input Channel Filters

```

Input:  void          *Handle          (handle pointer)
        ccurpmfc_dio_channels_t  ChannelSelectMask (channel selection)
        # NULL              (select all channels)
        # u_int32_t  ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12
        # CCURPMFC_DIO_CHANNEL_MASK_13
        # CCURPMFC_DIO_CHANNEL_MASK_14

```

```

# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Output: ccurpmfc_dio_channels_t DIO_InputChannels (input channel registers)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Return: _ccurpmfc_lib_error_number_t (successful)
# CCURPMFC_LIB_NO_ERROR

```

```

# CCURPMFC_LIB_BAD_HANDLE          (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN           (device not open)
# CCURPMFC_LIB_INVALID_ARG        (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE  (DIO is not active)
*****/

```

2.2.114 ccurPMFC_DIO_Get_Input_Snapshot()

This call returns the Input Snapshot state to the user. The purpose of this snapshot feature is to allow the user to read the input channels without the firmware updating them in the middle of the reads. In this way, then can ensure that all channels data are in sync.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_Input_Snapshot(void          *Handle,
                                _ccurpmfc_dio_input_snapshot_t *dio_snapshot)

Description: Get DIO Input Snapshot

Input:   void          *Handle          (handle pointer)
Output:  _ccurpmfc_dio_input_snapshot_t *dio_snapshot      (dio snapshot)
        # CCURPMFC_DIO_INPUT_OPERATION_CONTINUOUS
        # CCURPMFC_DIO_INPUT_OPERATION_SNAPSHOT

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.115 ccurPMFC_DIO_Get_Mode()

This call returns the current DIO mode.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_Mode(void          *Handle,
                          _ccurpmfc_dio_mode_t *dio_mode)

Description: Get DIO Mode

Input:   void          *Handle          (handle pointer)
Output:  _ccurpmfc_dio_mode_t          *dio_mode      (dio mode)
        # CCURPMFC_DIO_MODE_CUSTOM
        # CCURPMFC_DIO_MODE_NORMAL

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.116 ccurPMFC_DIO_Get_Output_Sync()

This call returns the current state of the output sync flag. The purpose of the output sync feature is to ensure that the user can safely program all the output channels prior to directing the firmware to send them out simultaneously.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_Output_Sync(void          *Handle,
                                _ccurpmfc_dio_output_sync_t  *dio_sync)

Description: Get DIO Output Sync

Input:   void          *Handle          (handle pointer)
Output:  _ccurpmfc_dio_output_sync_t  *dio_sync      (dio sync)
        # CCURPMFC_DIO_OUTPUT_OPERATION_CONTINUOUS
        # CCURPMFC_DIO_OUTPUT_OPERATION_SYNC

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.117 ccurPMFC_DIO_Get_Ports_Direction()

This call allows the user to get the direction of the digital channels. There are 24 ports with grouping of 4 channels per port. Direction control is on a port level or a group of 4 channels.

When the direction for channels are set to output, then reading the channels input registers will result in acquiring what was written to the output (loopback). When the direction for the channels are set as inputs, then reading the channels input registers will result in acquiring signals coming into the board from the external digital lines.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Get_Ports_Direction(void          *Handle,
                                _ccurpmfc_dio_port_mask_t *dio_direction)

Description: Get DIO Ports Direction Mask

Input:   void          *Handle          (handle pointer)
Output:  _ccurpmfc_dio_port_mask_t  *dio_direction      (port mask)
        # CCURPMFC_DIO_PORT_MASK_P0
        # CCURPMFC_DIO_PORT_MASK_P1
        # CCURPMFC_DIO_PORT_MASK_P2
        # CCURPMFC_DIO_PORT_MASK_P3
        # CCURPMFC_DIO_PORT_MASK_P4
        # CCURPMFC_DIO_PORT_MASK_P5
        # CCURPMFC_DIO_PORT_MASK_P6
        # CCURPMFC_DIO_PORT_MASK_P7
        # CCURPMFC_DIO_PORT_MASK_P8
        # CCURPMFC_DIO_PORT_MASK_P9
        # CCURPMFC_DIO_PORT_MASK_P10
        # CCURPMFC_DIO_PORT_MASK_P11
        # CCURPMFC_DIO_PORT_MASK_P12
        # CCURPMFC_DIO_PORT_MASK_P13
        # CCURPMFC_DIO_PORT_MASK_P14
        # CCURPMFC_DIO_PORT_MASK_P15
        # CCURPMFC_DIO_PORT_MASK_P16
        # CCURPMFC_DIO_PORT_MASK_P17
        # CCURPMFC_DIO_PORT_MASK_P18
        # CCURPMFC_DIO_PORT_MASK_P19
        # CCURPMFC_DIO_PORT_MASK_P20
        # CCURPMFC_DIO_PORT_MASK_P21
        # CCURPMFC_DIO_PORT_MASK_P22
        # CCURPMFC_DIO_PORT_MASK_P23

```

```

# CCURPMFC_DIO_ALL_PORTS_MASK
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR           (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.118 ccurPMFC_DIO_Read_Custom_Channel_Registers()

This call allows the user to display any DIO channels that have been reserved for custom usage. This is specifically dependant of the firmware being loaded. The user must enable the custom mode for DIO operation before reviewing these reserved channels. If no channels are listed, then no custom DIO channels exist. Any custom DIO channel will not operate in the normal DIO functionality but will behave differently based on the firmware loaded.

```

/*****
ccurPMFC_DIO_Read_Custom_Channel_Registers()
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Read_Custom_Channel_Registers(void          *Handle,
                                                    ccurpmfc_dio_channels_t  DIO_CustomChannels,
                                                    ccurpmfc_dio_channels_t  ChannelSelectMask)

```

Description: Read DIO Custom Channel Registers

```

Input:  void          *Handle          (handle pointer)
        ccurpmfc_dio_channels_t  ChannelSelectMask (custom channel selection)
        # NULL                          (select all channels)
        # u_int32_t   ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12
        # CCURPMFC_DIO_CHANNEL_MASK_13
        # CCURPMFC_DIO_CHANNEL_MASK_14
        # CCURPMFC_DIO_CHANNEL_MASK_15
        # CCURPMFC_DIO_CHANNEL_MASK_16
        # CCURPMFC_DIO_CHANNEL_MASK_17
        # CCURPMFC_DIO_CHANNEL_MASK_18
        # CCURPMFC_DIO_CHANNEL_MASK_19
        # CCURPMFC_DIO_CHANNEL_MASK_20
        # CCURPMFC_DIO_CHANNEL_MASK_21
        # CCURPMFC_DIO_CHANNEL_MASK_22
        # CCURPMFC_DIO_CHANNEL_MASK_23
        # CCURPMFC_DIO_CHANNEL_MASK_24
        # CCURPMFC_DIO_CHANNEL_MASK_25
        # CCURPMFC_DIO_CHANNEL_MASK_26
        # CCURPMFC_DIO_CHANNEL_MASK_27
        # CCURPMFC_DIO_CHANNEL_MASK_28
        # CCURPMFC_DIO_CHANNEL_MASK_29
        # CCURPMFC_DIO_CHANNEL_MASK_30
        # CCURPMFC_DIO_CHANNEL_MASK_31

```

```

        # CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
        # CCURPMFC_DIO_CHAN_00_31
        # CCURPMFC_DIO_CHAN_32_63
        # CCURPMFC_DIO_CHAN_64_95
Output:  ccurpmfc_dio_channels_t DIO_CustomChannels (custom channel registers)
        # u_int32_t    ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12
        # CCURPMFC_DIO_CHANNEL_MASK_13
        # CCURPMFC_DIO_CHANNEL_MASK_14
        # CCURPMFC_DIO_CHANNEL_MASK_15
        # CCURPMFC_DIO_CHANNEL_MASK_16
        # CCURPMFC_DIO_CHANNEL_MASK_17
        # CCURPMFC_DIO_CHANNEL_MASK_18
        # CCURPMFC_DIO_CHANNEL_MASK_19
        # CCURPMFC_DIO_CHANNEL_MASK_20
        # CCURPMFC_DIO_CHANNEL_MASK_21
        # CCURPMFC_DIO_CHANNEL_MASK_22
        # CCURPMFC_DIO_CHANNEL_MASK_23
        # CCURPMFC_DIO_CHANNEL_MASK_24
        # CCURPMFC_DIO_CHANNEL_MASK_25
        # CCURPMFC_DIO_CHANNEL_MASK_26
        # CCURPMFC_DIO_CHANNEL_MASK_27
        # CCURPMFC_DIO_CHANNEL_MASK_28
        # CCURPMFC_DIO_CHANNEL_MASK_29
        # CCURPMFC_DIO_CHANNEL_MASK_30
        # CCURPMFC_DIO_CHANNEL_MASK_31
        # CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
        # CCURPMFC_DIO_CHAN_00_31
        # CCURPMFC_DIO_CHAN_32_63
        # CCURPMFC_DIO_CHAN_64_95
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.119 ccurPMFC_DIO_Read_Input_Channel_Registers()

This call reads the contents of the input channel registers and returns to the user. There are two modes of operation for this call. (1) Continuous (2) Snapshot.

When the user selects the *continuous* operation, this call immediately returns to the user whatever is available on the input registers as they are being received by the hardware. There is therefore no synchronizing occurring between the three input channel registers (32 channels/register). For performance improvements with this operational mode, it is recommended that the user sets the continuous option using the *ccurPMFC_DIO_Set_Input_Snapshot()* call once and then supply

CCURPMFC_DIO_INPUT_OPERATION_DO_NOT_CHANGE to this call for more reads. In this way, an additional register access will not occur everytime this call is issued.

When the user selects the *snapshot* operation, there is no need to issue the *ccurPMFC_DIO_Set_Input_Snapshot()*. All that is required is to supply the *CCURPMFC_DIO_INPUT_OPERATION_SNAPSHOT* option when issuing this call. The result is that all the three input registers will be captured instantaneously (in sync) by the firmware and returned to the user.

Obviously, the *snapshot* option is only meaningful if the user selects channels (*using the channel selection mask*) that reside in at least two different input channel registers.

Input channel register 0: Channels 0 to 31
 Input channel register 1: Channels 32 to 63
 Input channel register 2: Channels 64 to 95

The *skip_dio_disable_check* (when set to *CCURPMFC_FALSE*) causes the call to test for DIO being enabled prior to proceeding. If this option is set to *CCURPMFC_TRUE*, then no test is. If the DIO has not been enabled, input reads will be invalid. The only reason for providing the option to disable the check is to improve the performance of the call. If the user can ensure that the DIO is enabled prior to issuing this call, they can set this option to *CCURPMFC_TRUE* so that no test is performed and hence, improve performance.

When the direction for channels are set to output, then reading the channels input registers will result in acquiring what was written to the output (loopback). When the direction for the channels are set as inputs, then reading the channels input registers will result in acquiring signals coming into the board from the external digital lines.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Read_Input_Channel_Registers(void          *Handle,
        _ccurpmfc_dio_input_snapshot_t          dio_snapshot,
        ccurpmfc_bool                          skip_dio_disabled_check,
        ccurpmfc_dio_channels_t                DIO_InputChannels,
        ccurpmfc_dio_channels_t                ChannelSelectMask)

Description: Read DIO Input Channel Registers

Input:  void          *Handle          (handle pointer)
        _ccurpmfc_dio_input_snapshot_t dio_snapshot (dio_snapshot operation)
        # CCURPMFC_DIO_INPUT_OPERATION_CONTINUOUS
        # CCURPMFC_DIO_INPUT_OPERATION_SNAPSHOT
        # CCURPMFC_DIO_INPUT_OPERATION_DO_NOT_CHANGE
        ccurpmfc_bool skip_dio_disabled_check (skip dio disabled check)
        # CCURPMFC_TRUE
        # CCURPMFC_FALSE
        ccurpmfc_dio_channels_t ChannelSelectMask (input channel selection)
        # NULL (select all channels)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12

```

```

# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Output: ccurpmfc_dio_channels_t DIO_InputChannels (input channel registers)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95

```

```

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.120 ccurPMFC_DIO_Read_Output_Channel_Registers()

This call reads the contents of the output channel registers and returns to the user. This simply represents the contents of the last write to the output registers.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Read_Output_Channel_Registers(void          *Handle,
                                              ccurpmfc_dio_channels_t DIO_OutputChannels,
                                              ccurpmfc_dio_channels_t ChannelSelectMask)

```

Description: Read DIO Output Channel Registers

```

Input:  void          *Handle          (handle pointer)
        ccurpmfc_dio_channels_t ChannelSelectMask (output channel selection)
        # NULL                                           (select all channels)
        # u_int32_t   ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12
        # CCURPMFC_DIO_CHANNEL_MASK_13
        # CCURPMFC_DIO_CHANNEL_MASK_14
        # CCURPMFC_DIO_CHANNEL_MASK_15
        # CCURPMFC_DIO_CHANNEL_MASK_16
        # CCURPMFC_DIO_CHANNEL_MASK_17
        # CCURPMFC_DIO_CHANNEL_MASK_18
        # CCURPMFC_DIO_CHANNEL_MASK_19
        # CCURPMFC_DIO_CHANNEL_MASK_20
        # CCURPMFC_DIO_CHANNEL_MASK_21
        # CCURPMFC_DIO_CHANNEL_MASK_22
        # CCURPMFC_DIO_CHANNEL_MASK_23
        # CCURPMFC_DIO_CHANNEL_MASK_24
        # CCURPMFC_DIO_CHANNEL_MASK_25
        # CCURPMFC_DIO_CHANNEL_MASK_26
        # CCURPMFC_DIO_CHANNEL_MASK_27
        # CCURPMFC_DIO_CHANNEL_MASK_28
        # CCURPMFC_DIO_CHANNEL_MASK_29
        # CCURPMFC_DIO_CHANNEL_MASK_30
        # CCURPMFC_DIO_CHANNEL_MASK_31
        # CCURPMFC_DIO_ALL_CHANNELS_MASK
        CCURPMFC_DIO_MAX_REGISTERS can be one of:
        # CCURPMFC_DIO_CHAN_00_31
        # CCURPMFC_DIO_CHAN_32_63
        # CCURPMFC_DIO_CHAN_64_95

```

```

Output:  ccurpmfc_dio_channels_t DIO_OutputChannels (output channel registers)
        # u_int32_t    ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
        # CCURPMFC_DIO_CHANNEL_MASK_0
        # CCURPMFC_DIO_CHANNEL_MASK_1
        # CCURPMFC_DIO_CHANNEL_MASK_2
        # CCURPMFC_DIO_CHANNEL_MASK_3
        # CCURPMFC_DIO_CHANNEL_MASK_4
        # CCURPMFC_DIO_CHANNEL_MASK_5
        # CCURPMFC_DIO_CHANNEL_MASK_6
        # CCURPMFC_DIO_CHANNEL_MASK_7
        # CCURPMFC_DIO_CHANNEL_MASK_8
        # CCURPMFC_DIO_CHANNEL_MASK_9
        # CCURPMFC_DIO_CHANNEL_MASK_10
        # CCURPMFC_DIO_CHANNEL_MASK_11
        # CCURPMFC_DIO_CHANNEL_MASK_12
        # CCURPMFC_DIO_CHANNEL_MASK_13
        # CCURPMFC_DIO_CHANNEL_MASK_14
        # CCURPMFC_DIO_CHANNEL_MASK_15
        # CCURPMFC_DIO_CHANNEL_MASK_16
        # CCURPMFC_DIO_CHANNEL_MASK_17
        # CCURPMFC_DIO_CHANNEL_MASK_18
        # CCURPMFC_DIO_CHANNEL_MASK_19
        # CCURPMFC_DIO_CHANNEL_MASK_20
        # CCURPMFC_DIO_CHANNEL_MASK_21
        # CCURPMFC_DIO_CHANNEL_MASK_22
        # CCURPMFC_DIO_CHANNEL_MASK_23
        # CCURPMFC_DIO_CHANNEL_MASK_24
        # CCURPMFC_DIO_CHANNEL_MASK_25
        # CCURPMFC_DIO_CHANNEL_MASK_26
        # CCURPMFC_DIO_CHANNEL_MASK_27
        # CCURPMFC_DIO_CHANNEL_MASK_28
        # CCURPMFC_DIO_CHANNEL_MASK_29
        # CCURPMFC_DIO_CHANNEL_MASK_30
        # CCURPMFC_DIO_CHANNEL_MASK_31
        # CCURPMFC_DIO_ALL_CHANNELS_MASK
        CCURPMFC_DIO_MAX_REGISTERS can be one of:
        # CCURPMFC_DIO_CHAN_00_31
        # CCURPMFC_DIO_CHAN_32_63
        # CCURPMFC_DIO_CHAN_64_95
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.121 ccurPMFC_DIO_Set_Channels_Polarity()

This call allows the user to set the polarity for the DIO channels. The *ChannelSelectMask* is used to retrieve polarity settings for selected channels.

For input channels, a value of *CCURPMFC_DIO_INPUT_LOW_TRUE* or '0' for polarity indicates low true, while a value of *CCURPMFC_DIO_INPUT_HIGH_TRUE* or '1' for polarity indicates high true.

For output channels, a value of *CCURPMFC_DIO_OUTPUT_LOW* or '0' for polarity indicates low or 0 volts, while a value of *CCURPMFC_DIO_OUTPUT_HIGH* or '1' for polarity indicates high or +5 volts.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Set_Channels_Polarity(void          *Handle,

```

```
ccurpmfc_dio_channels_t DIO_ChannelsPolarity,  
ccurpmfc_dio_channels_t ChannelSelectMask)
```

Description: Set Input Channel Filters

```
Input: void *Handle (handle pointer)  
ccurpmfc_dio_channels_t DIO_ChannelsPolarity(channels polarity regs)  
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]  
# CCURPMFC_DIO_CHANNEL_MASK_0  
# CCURPMFC_DIO_CHANNEL_MASK_1  
# CCURPMFC_DIO_CHANNEL_MASK_2  
# CCURPMFC_DIO_CHANNEL_MASK_3  
# CCURPMFC_DIO_CHANNEL_MASK_4  
# CCURPMFC_DIO_CHANNEL_MASK_5  
# CCURPMFC_DIO_CHANNEL_MASK_6  
# CCURPMFC_DIO_CHANNEL_MASK_7  
# CCURPMFC_DIO_CHANNEL_MASK_8  
# CCURPMFC_DIO_CHANNEL_MASK_9  
# CCURPMFC_DIO_CHANNEL_MASK_10  
# CCURPMFC_DIO_CHANNEL_MASK_11  
# CCURPMFC_DIO_CHANNEL_MASK_12  
# CCURPMFC_DIO_CHANNEL_MASK_13  
# CCURPMFC_DIO_CHANNEL_MASK_14  
# CCURPMFC_DIO_CHANNEL_MASK_15  
# CCURPMFC_DIO_CHANNEL_MASK_16  
# CCURPMFC_DIO_CHANNEL_MASK_17  
# CCURPMFC_DIO_CHANNEL_MASK_18  
# CCURPMFC_DIO_CHANNEL_MASK_19  
# CCURPMFC_DIO_CHANNEL_MASK_20  
# CCURPMFC_DIO_CHANNEL_MASK_21  
# CCURPMFC_DIO_CHANNEL_MASK_22  
# CCURPMFC_DIO_CHANNEL_MASK_23  
# CCURPMFC_DIO_CHANNEL_MASK_24  
# CCURPMFC_DIO_CHANNEL_MASK_25  
# CCURPMFC_DIO_CHANNEL_MASK_26  
# CCURPMFC_DIO_CHANNEL_MASK_27  
# CCURPMFC_DIO_CHANNEL_MASK_28  
# CCURPMFC_DIO_CHANNEL_MASK_29  
# CCURPMFC_DIO_CHANNEL_MASK_30  
# CCURPMFC_DIO_CHANNEL_MASK_31  
# CCURPMFC_DIO_ALL_CHANNELS_MASK  
CCURPMFC_DIO_MAX_REGISTERS can be one of:  
# CCURPMFC_DIO_CHAN_00_31  
# CCURPMFC_DIO_CHAN_32_63  
# CCURPMFC_DIO_CHAN_64_95  
ccurpmfc_dio_channels_t ChannelSelectMask (polarity channel  
selection)  
# NULL (select all channels)  
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]  
# CCURPMFC_DIO_CHANNEL_MASK_0  
# CCURPMFC_DIO_CHANNEL_MASK_1  
# CCURPMFC_DIO_CHANNEL_MASK_2  
# CCURPMFC_DIO_CHANNEL_MASK_3  
# CCURPMFC_DIO_CHANNEL_MASK_4  
# CCURPMFC_DIO_CHANNEL_MASK_5  
# CCURPMFC_DIO_CHANNEL_MASK_6  
# CCURPMFC_DIO_CHANNEL_MASK_7  
# CCURPMFC_DIO_CHANNEL_MASK_8  
# CCURPMFC_DIO_CHANNEL_MASK_9  
# CCURPMFC_DIO_CHANNEL_MASK_10  
# CCURPMFC_DIO_CHANNEL_MASK_11  
# CCURPMFC_DIO_CHANNEL_MASK_12  
# CCURPMFC_DIO_CHANNEL_MASK_13
```

```

# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95

Output: none
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR           (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.122 ccurPMFC_DIO_Set_COS_Channels_Edge_Sense()

This call sets the change-of-state to sense the rising or falling edge of the signal on input for the channels. The *ChannelSelectMask* is used to set the edge sense settings for selected channels. A value of *CCURPMFC_DIO_COS_FALLING_EDGE* or '0' represents sensing of falling edge of input signal while a value of *CCURPMFC_DIO_COS_RISING_EDGE* or '1' represents sensing of rising edge of input signal.

For edge sensing to occur, the *CCURPMFC_DIO_COS_RISING_OR_FALLING_TRANSITION* bit needs to be set for the corresponding channels using the *ccurPMFC_DIO_Set_COS_Channels_Mode()* call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Set_COS_Channels_Edge_Sense(void *Handle,
                                           ccurpmfc_dio_channels_t DIO_COS_ChannelsEdgeSense,
                                           ccurpmfc_dio_channels_t ChannelSelectMask)

Description: Set COS Channels Edge Sense

Input: void *Handle (handle pointer)
       ccurpmfc_dio_channels_t DIO_COS_ChannelsEdgeSense
                               (COS channels edge sense registers)
       # u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
       # CCURPMFC_DIO_CHANNEL_MASK_0
       # CCURPMFC_DIO_CHANNEL_MASK_1
       # CCURPMFC_DIO_CHANNEL_MASK_2
       # CCURPMFC_DIO_CHANNEL_MASK_3
       # CCURPMFC_DIO_CHANNEL_MASK_4
       # CCURPMFC_DIO_CHANNEL_MASK_5
       # CCURPMFC_DIO_CHANNEL_MASK_6
       # CCURPMFC_DIO_CHANNEL_MASK_7

```

```

# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
ccurpmfc_dio_channels_t ChannelSelectMask    (channel selection)
# NULL                                       (select all channels)
# u_int32_t  ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30

```

```

# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95

Output: none
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR           (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN         (device not open)
# CCURPMFC_LIB_INVALID_ARG      (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.123 ccurPMFC_DIO_Set_COS_Channels_Enable()

If the user wishes to monitor change-of-state for a channel, then need to enable the change-of-state detection for the respective channels using this call. Without the channel being enabled, no change-of-state detection will occur. The *ChannelSelectMask* is used to set enable settings for selected channels. A value of *CCURPMFC_DIO_COS_IGNORE* or '0' ignores change-of-state while a value of *CCURPMFC_DIO_COS_ENABLE* or '1' represents enabling change-of-state for the selected channels.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Set_COS_Channels_Enable(void          *Handle,
                                       ccurpmfc_dio_channels_t DIO_COS_ChannelsEnable,
                                       ccurpmfc_dio_channels_t ChannelSelectMask)

```

Description: Set COS Channels Enable

```

Input:  void          *Handle          (handle pointer)
        ccurpmfc_dio_channels_t DIO_COS_ChannelsEnable
                                       (COS channels enable registers)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26

```



```

# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
ccurpmfc_dio_channels_t ChannelSelectMask (channel selection)
# NULL (select all channels)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95

Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.124 ccurPMFC_DIO_Set_COS_Channels_Mode()

This call sets the change-of-state mode registers all the channels. The *ChannelSelectMask* is used to set the mode settings for selected channels. A value of *CCURPMFC_DIO_COS_ANY_TRANSITION* or '0' sets change-of-state on any edge transition while a value of *CCURPMFC_DIO_COS_RISING_OR_FALLING_TRANSITION* or '1' represents enabling change-of-state for either rising edge or falling edge depending on the channel edge sense setting for the selected channels.

```

/*****
   _ccurpmfc_lib_error_number_t
   ccurPMFC_DIO_Set_COS_Channels_Mode(void           *Handle,
                                     ccurpmfc_dio_channels_t  DIO_COS_ChannelsMode,
                                     ccurpmfc_dio_channels_t  ChannelSelectMask)

```

Description: Set COS Channels Mode

```

Input:  void           *Handle           (handle pointer)
        ccurpmfc_dio_channels_t  DIO_COS_ChannelsMode
                                               (COS channels mode registers)
        # u_int32_t   ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
            # CCURPMFC_DIO_CHANNEL_MASK_0
            # CCURPMFC_DIO_CHANNEL_MASK_1
            # CCURPMFC_DIO_CHANNEL_MASK_2
            # CCURPMFC_DIO_CHANNEL_MASK_3
            # CCURPMFC_DIO_CHANNEL_MASK_4
            # CCURPMFC_DIO_CHANNEL_MASK_5
            # CCURPMFC_DIO_CHANNEL_MASK_6
            # CCURPMFC_DIO_CHANNEL_MASK_7
            # CCURPMFC_DIO_CHANNEL_MASK_8
            # CCURPMFC_DIO_CHANNEL_MASK_9
            # CCURPMFC_DIO_CHANNEL_MASK_10
            # CCURPMFC_DIO_CHANNEL_MASK_11
            # CCURPMFC_DIO_CHANNEL_MASK_12
            # CCURPMFC_DIO_CHANNEL_MASK_13
            # CCURPMFC_DIO_CHANNEL_MASK_14
            # CCURPMFC_DIO_CHANNEL_MASK_15
            # CCURPMFC_DIO_CHANNEL_MASK_16
            # CCURPMFC_DIO_CHANNEL_MASK_17
            # CCURPMFC_DIO_CHANNEL_MASK_18
            # CCURPMFC_DIO_CHANNEL_MASK_19
            # CCURPMFC_DIO_CHANNEL_MASK_20
            # CCURPMFC_DIO_CHANNEL_MASK_21
            # CCURPMFC_DIO_CHANNEL_MASK_22
            # CCURPMFC_DIO_CHANNEL_MASK_23
            # CCURPMFC_DIO_CHANNEL_MASK_24
            # CCURPMFC_DIO_CHANNEL_MASK_25
            # CCURPMFC_DIO_CHANNEL_MASK_26
            # CCURPMFC_DIO_CHANNEL_MASK_27
            # CCURPMFC_DIO_CHANNEL_MASK_28
            # CCURPMFC_DIO_CHANNEL_MASK_29
            # CCURPMFC_DIO_CHANNEL_MASK_30
            # CCURPMFC_DIO_CHANNEL_MASK_31
            # CCURPMFC_DIO_ALL_CHANNELS_MASK
        CCURPMFC_DIO_MAX_REGISTERS can be one of:
            # CCURPMFC_DIO_CHAN_00_31
            # CCURPMFC_DIO_CHAN_32_63
            # CCURPMFC_DIO_CHAN_64_95
        ccurpmfc_dio_channels_t  ChannelSelectMask   (channel selection)
            # NULL                                       (select all channels)
            # u_int32_t   ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
                # CCURPMFC_DIO_CHANNEL_MASK_0
                # CCURPMFC_DIO_CHANNEL_MASK_1
                # CCURPMFC_DIO_CHANNEL_MASK_2

```

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```

# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95

```

Output: none

```

Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)

```

*****/

2.2.125 ccurPMFC_DIO_Set_Input_Channels_Filter()

This call allows the user to set or reset filters for a selected set of input channels. The *ChannelSelectMask* is used to select channels for filter settings. A value of *CCURPMFC_DIO_INPUT_FILTER_ENABLED* or '0' for filter indicates that the 100 nanosecond filter is enabled for the selected channel, while a value of *CCURPMFC_DIO_INPUT_FILTER_DISABLED* or '1' indicates that the filter is disabled. On powerup, filter for all channels are enabled.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Set_Input_Channels_Filter(void *Handle,
                                         ccurpmfc_dio_channels_t DIO_InputChannels,
                                         ccurpmfc_dio_channels_t ChannelSelectMask)

```

Description: Set Input Channel Filters

```

Input: void *Handle (handle pointer)
       ccurpmfc_dio_channels_t DIO_InputChannels (input channel registers)
       # u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]

```

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```

# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
ccurpmfc_dio_channels_t ChannelSelectMask (filter channel selection)
# NULL (select all channels)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22

```

```

# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95

Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.126 ccurPMFC_DIO_Set_Input_Snapshot()

This call allows the user to set the board in snapshot mode where all three input registers are acquired simultaneously (in sync) by the hardware and presented to the user. Mainly, this particular call is only useful for setting the operation to continuous mode. There is no need to set to snapshot mode as the read input registers call *ccurPMFC_DIO_Read_Input_Channel_Registers()* an option to set it call.

If the user wants to collect data in the continuous mode, then they should issue this call once with the *CCURPMFC_DIO_INPUT_OPERATION_CONTINUOUS* option and then call the read of the input channels with the *CCURPMF_DO_NOT_CHANGE* option. In this way, there is no un-necessary overhead in setting the board into continuous mode once it has already been set.

Recommended procedure for continuous mode is to issue this call only once with the *CCURPMFC_DIO_INPUT_OPERATION_CONTINUOUS* option and then followup with continuous input channel reads using the *ccurPMFC_DIO_Read_Input_Channel_Register()* call with the *CCURPMFC_DIO_INPUT_OPERATION_DO_NOT_CHANGE* option for *dio_snapshot*.

Recommended procedure for snapshot mode is to issue continuous input channel reads using the *ccurPMFC_DIO_Read_Input_Channel_Register()* call with the *CCURPMFC_DIO_INPUT_OPERATION_SYNC* option for *dio_snapshot*. There is really no need to issue this call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Set_Input_Snapshot(void *Handle,
_ccurpmfc_dio_input_snapshot_t dio_snapshot)

```

Description: Set DIO Input Snapshot

```

Input: void *Handle (handle pointer)
Output: _ccurpmfc_dio_input_snapshot_t dio_snapshot (dio snapshot)
# CCURPMFC_DIO_INPUT_OPERATION_CONTINUOUS
# CCURPMFC_DIO_INPUT_OPERATION_SNAPSHOT
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)

```

```

# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.127 ccurPMFC_DIO_Set_Mode()

This call allows the user to select a custom or a normal mode of DIO operation. In the normal mode, all 96 channels are available for DIO operation, while, in the custom mode, the custom channels supplied in the custom input registers may not operate as normal DIO channels. These custom channels behavior will depend entirely on the firmware loaded into the board.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Set_Mode(void          *Handle,
                        _ccurpmfc_dio_mode_t dio_mode)

Description: Set DIO Mode

Input:   void          *Handle          (handle pointer)
Output:  _ccurpmfc_dio_mode_t dio_mode  (dio mode)
        # CCURPMFC_DIO_MODE_CUSTOM
        # CCURPMFC_DIO_MODE_NORMAL

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.128 ccurPMFC_DIO_Set_Output_Sync()

This call allows the user to set the digital output channels to either *continuous* mode or *sync* mode. When the board is in continuous mode, any update to one of the three output registers will be immediately sent to the output lines. There will be no synchronization between the three output registers. When the sync mode is selected, no output is sent while updating the output registers. Once the output sync flag is set, the contents of all three output registers will be sent simultaneously to the output lines.

Recommended procedure for continuous mode is to issue this call only once with the *CCURPMFC_DIO_OUTPUT_OPERATION_CONTINUOUS* option and then followup with continuous output channel writes using the *ccurPMFC_DIO_Write_Output_Channel_Register()* call with the *CCURPMFC_DIO_INPUT_OPERATION_DO_NOT_CHANGE* option for *dio_sync*.

Recommended procedure for sync mode is to issue this call only once with the *CCURPMFC_DIO_OUTPUT_OPERATION_SYNC* option and then followed up with continuous output channel writes using the *ccurPMFC_DIO_Write_Output_Channel_Register()* call with the *CCURPMFC_DIO_OUTPUT_OPERATION_SYNC* option for *dio_sync*.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Set_Output_Sync(void *Handle,
                               _ccurpmfc_dio_output_sync_t dio_sync)

Description: Set DIO Output Sync

Input:   void          *Handle          (handle pointer)
        _ccurpmfc_dio_output_sync_t dio_sync  (dio sync)
        # CCURPMFC_DIO_OUTPUT_OPERATION_CONTINUOUS

```

```

        # CCURPMFC_DIO_OUTPUT_OPERATION_SYNC
Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.129 ccurPMFC_DIO_Set_Ports_Direction()

This call allows the user to set the direction of the digital channels. There are 24 ports with grouping of 4 channels per port. Direction control is on a port level or a group of 4 channels.

When the direction for channels are set to output, then reading the channels input registers will result in acquiring what was written to the output (readback). When the direction for the channels are set as inputs, then reading the channels input registers will result in acquiring signals coming into the board from the external digital lines.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Set_Ports_Direction(void          *Handle,
                                     _ccurpmfc_dio_port_mask_t dio_direction)

```

Description: Set DIO Port Direction Mask

```

Input:  void          *Handle          (handle pointer)
        _ccurpmfc_dio_port_mask_t    dio_direction    (port mask)
        # CCURPMFC_DIO_PORT_MASK_P0
        # CCURPMFC_DIO_PORT_MASK_P1
        # CCURPMFC_DIO_PORT_MASK_P2
        # CCURPMFC_DIO_PORT_MASK_P3
        # CCURPMFC_DIO_PORT_MASK_P4
        # CCURPMFC_DIO_PORT_MASK_P5
        # CCURPMFC_DIO_PORT_MASK_P6
        # CCURPMFC_DIO_PORT_MASK_P7
        # CCURPMFC_DIO_PORT_MASK_P8
        # CCURPMFC_DIO_PORT_MASK_P9
        # CCURPMFC_DIO_PORT_MASK_P10
        # CCURPMFC_DIO_PORT_MASK_P11
        # CCURPMFC_DIO_PORT_MASK_P12
        # CCURPMFC_DIO_PORT_MASK_P13
        # CCURPMFC_DIO_PORT_MASK_P14
        # CCURPMFC_DIO_PORT_MASK_P15
        # CCURPMFC_DIO_PORT_MASK_P16
        # CCURPMFC_DIO_PORT_MASK_P17
        # CCURPMFC_DIO_PORT_MASK_P18
        # CCURPMFC_DIO_PORT_MASK_P19
        # CCURPMFC_DIO_PORT_MASK_P20
        # CCURPMFC_DIO_PORT_MASK_P21
        # CCURPMFC_DIO_PORT_MASK_P22
        # CCURPMFC_DIO_PORT_MASK_P23
        # CCURPMFC_DIO_ALL_PORTS_MASK
Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_INVALID_ARG      (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)

```

*****/

2.2.130 ccurPMFC_DIO_Set_Ports_Direction_To_Input()

This call allows the user to set the direction of a selected set of digital channels to Inputs. Other channels are unchanged. There are 24 ports with grouping of 4 channels per port. Direction Input control is on a port level or a group of 4 channels.

When the direction for the channels are set as inputs, then reading the channels input registers will result in acquiring signals coming into the board from the external digital lines.

```
/*  
_ccurpmfc_lib_error_number_t  
    ccurPMFC_DIO_Set_Ports_Direction_To_Input(void      *Handle,  
                                                _ccurpmfc_dio_port_mask_t dio_input_direction)
```

Description: Set DIO Port Direction Input Mask

Input: void *Handle (handle pointer)
_ccurpmfc_dio_port_mask_t dio_input_direction (port mask)

```
# CCURPMFC_DIO_PORT_MASK_P0  
# CCURPMFC_DIO_PORT_MASK_P1  
# CCURPMFC_DIO_PORT_MASK_P2  
# CCURPMFC_DIO_PORT_MASK_P3  
# CCURPMFC_DIO_PORT_MASK_P4  
# CCURPMFC_DIO_PORT_MASK_P5  
# CCURPMFC_DIO_PORT_MASK_P6  
# CCURPMFC_DIO_PORT_MASK_P7  
# CCURPMFC_DIO_PORT_MASK_P8  
# CCURPMFC_DIO_PORT_MASK_P9  
# CCURPMFC_DIO_PORT_MASK_P10  
# CCURPMFC_DIO_PORT_MASK_P11  
# CCURPMFC_DIO_PORT_MASK_P12  
# CCURPMFC_DIO_PORT_MASK_P13  
# CCURPMFC_DIO_PORT_MASK_P14  
# CCURPMFC_DIO_PORT_MASK_P15  
# CCURPMFC_DIO_PORT_MASK_P16  
# CCURPMFC_DIO_PORT_MASK_P17  
# CCURPMFC_DIO_PORT_MASK_P18  
# CCURPMFC_DIO_PORT_MASK_P19  
# CCURPMFC_DIO_PORT_MASK_P20  
# CCURPMFC_DIO_PORT_MASK_P21  
# CCURPMFC_DIO_PORT_MASK_P22  
# CCURPMFC_DIO_PORT_MASK_P23  
# CCURPMFC_DIO_ALL_PORTS_MASK
```

Output: none

Return: _ccurpmfc_lib_error_number_t
CCURPMFC_LIB_NO_ERROR (successful)
CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
CCURPMFC_LIB_NOT_OPEN (device not open)
CCURPMFC_LIB_INVALID_ARG (invalid argument)
CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)

*****/

2.2.131 ccurPMFC_DIO_Set_Ports_Direction_To_Output()

This call allows the user to set the direction of a selected set of digital channels to Outputs. Other channels are unchanged. There are 24 ports with grouping of 4 channels per port. Direction Output control is on a port level or a group of 4 channels.

When the direction for channels are set to output, then reading the channels input registers will result in acquiring what was written to the output (readback).

```

/*****
_ccurpmfc_lib_error_number_t
    ccurPMFC_DIO_Set_Ports_Direction_To_Output(void      *Handle,
                                                _ccurpmfc_dio_port_mask_t dio_output_direction)

Description: Set DIO Port Direction Input Mask

Input:  void      *Handle      (handle pointer)
        _ccurpmfc_dio_port_mask_t dio_outputt_direction (port mask)
        # CCURPMFC_DIO_PORT_MASK_P0
        # CCURPMFC_DIO_PORT_MASK_P1
        # CCURPMFC_DIO_PORT_MASK_P2
        # CCURPMFC_DIO_PORT_MASK_P3
        # CCURPMFC_DIO_PORT_MASK_P4
        # CCURPMFC_DIO_PORT_MASK_P5
        # CCURPMFC_DIO_PORT_MASK_P6
        # CCURPMFC_DIO_PORT_MASK_P7
        # CCURPMFC_DIO_PORT_MASK_P8
        # CCURPMFC_DIO_PORT_MASK_P9
        # CCURPMFC_DIO_PORT_MASK_P10
        # CCURPMFC_DIO_PORT_MASK_P11
        # CCURPMFC_DIO_PORT_MASK_P12
        # CCURPMFC_DIO_PORT_MASK_P13
        # CCURPMFC_DIO_PORT_MASK_P14
        # CCURPMFC_DIO_PORT_MASK_P15
        # CCURPMFC_DIO_PORT_MASK_P16
        # CCURPMFC_DIO_PORT_MASK_P17
        # CCURPMFC_DIO_PORT_MASK_P18
        # CCURPMFC_DIO_PORT_MASK_P19
        # CCURPMFC_DIO_PORT_MASK_P20
        # CCURPMFC_DIO_PORT_MASK_P21
        # CCURPMFC_DIO_PORT_MASK_P22
        # CCURPMFC_DIO_PORT_MASK_P23
        # CCURPMFC_DIO_ALL_PORTS_MASK

Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN      (device not open)
        # CCURPMFC_LIB_INVALID_ARG   (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.132 ccurPMFC_DIO_Write_Output_Channel_Registers()

This call writes the user supplied channel settings to the output channel registers. There are two modes of operation for this call. (1) Continuous (2) Sync.

When the user selects the *continuous* operation, this call immediately sends out the channel data to the output lines as they are written to the output registers. There is therefore no synchronizing occurring between the three output channel registers (32 channels/register). For performance improvements with this operational mode, it is recommended that the user sets the continuous option using the *ccurPMFC_DIO_Set_Output_Sync()* call once and then supply *CCURPMFC_DIO_INPUT_OPERATION_DO_NOT_CHANGE* to this call for more writes. In this way, an additional register access will not occur everytime this call is issued.

When the user selects the *sync* operation, they need to issue the `ccurPMFC_DIO_Set_Output_Sync()` call once with the `CCURPMFC_DIO_OUTPUT_OPERATION_SYNC` option, followed by issuing this call with the `CCURPMFC_DIO_OUTPUT_OPERATION_SYNC` option in *dio_sync*.

Obviously, the *sync* option is only meaningful if the user selects channels (*using the channel selection mask*) that reside in at least two different output channel registers.

Output channel register 0: Channels 0 to 31
 Output channel register 1: Channels 32 to 63
 Output channel register 2: Channels 64 to 95

The *skip_dio_disable_check* (when set to `CCURPMFC_FALSE`) causes the call to test for DIO being enabled prior to proceeding. If this option is set to `CCURPMFC_TRUE`, then no test is. If the DIO has not been enabled, output writes will not take place. The only reason for providing the option to disable the check is to improve the performance of the call. If the user can ensure that the DIO is enabled prior to issuing this call, they can set this option to `CCURPMFC_TRUE` so that no test is performed and hence, improve performance.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Write_Output_Channel_Registers(void      *Handle,
      _ccurpmfc_dio_output_sync_t dio_sync,
      ccurpmfc_bool skip_dio_disabled_check,
      ccurpmfc_dio_channels_t DIO_OutputChannels,
      ccurpmfc_dio_channels_t ChannelSelectMask)
  
```

Description: Write DIO Output Channel Registers

```

Input: void *Handle (handle pointer)
      _ccurpmfc_dio_output_sync_t dio_sync (dio_sync operation)
      # CCURPMFC_DIO_OUTPUT_OPERATION_CONTINUOUS
      # CCURPMFC_DIO_OUTPUT_OPERATION_SYNC
      # CCURPMFC_DIO_OUTPUT_OPERATION_DO_NOT_CHANGE
      ccurpmfc_bool skip_dio_disabled_check (skip dio disabled check)
      # CCURPMFC_TRUE
      # CCURPMFC_FALSE
      ccurpmfc_dio_channels_t DIO_OutputChannels (output channel registers)
      # u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
      # CCURPMFC_DIO_CHANNEL_MASK_0
      # CCURPMFC_DIO_CHANNEL_MASK_1
      # CCURPMFC_DIO_CHANNEL_MASK_2
      # CCURPMFC_DIO_CHANNEL_MASK_3
      # CCURPMFC_DIO_CHANNEL_MASK_4
      # CCURPMFC_DIO_CHANNEL_MASK_5
      # CCURPMFC_DIO_CHANNEL_MASK_6
      # CCURPMFC_DIO_CHANNEL_MASK_7
      # CCURPMFC_DIO_CHANNEL_MASK_8
      # CCURPMFC_DIO_CHANNEL_MASK_9
      # CCURPMFC_DIO_CHANNEL_MASK_10
      # CCURPMFC_DIO_CHANNEL_MASK_11
      # CCURPMFC_DIO_CHANNEL_MASK_12
      # CCURPMFC_DIO_CHANNEL_MASK_13
      # CCURPMFC_DIO_CHANNEL_MASK_14
      # CCURPMFC_DIO_CHANNEL_MASK_15
      # CCURPMFC_DIO_CHANNEL_MASK_16
      # CCURPMFC_DIO_CHANNEL_MASK_17
      # CCURPMFC_DIO_CHANNEL_MASK_18
      # CCURPMFC_DIO_CHANNEL_MASK_19
      # CCURPMFC_DIO_CHANNEL_MASK_20
      # CCURPMFC_DIO_CHANNEL_MASK_21
      # CCURPMFC_DIO_CHANNEL_MASK_22
      # CCURPMFC_DIO_CHANNEL_MASK_23
  
```

```

# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
ccurpmfc_dio_channels_t ChannelSelectMask (output channel selection)
# NULL (select all channels)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95

Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****

```

2.2.133 ccurPMFC_DIO_Write_Output_Channel_High_Registers()

This call writes a selected set of channels to high outputs. Rest of the channels is not affected. There are two modes of operation for this call. (1) Continuous (2) Sync.

When the user selects the *continuous* operation, this call immediately sends out the channel high data to the output lines as they are written to the output registers. There is therefore no synchronizing occurring between the three output channel registers (32 channels/register). For performance improvements with this operational mode, it is recommended that the user sets the continuous option using the *ccurPMFC_DIO_Set_Output_Sync()* call once and then supply *CCURPMFC_DIO_INPUT_OPERATION_DO_NOT_CHANGE* to this call for more writes. In this way, an additional register access will not occur everytime this call is issued.

When the user selects the *sync* operation, they need to issue the *ccurPMFC_DIO_Set_Output_Sync()* call once with the *CCURPMFC_DIO_OUTPUT_OPERATION_SYNC* option, followed by issuing this call with the *CCURPMFC_DIO_OUTPUT_OPERATION_SYNC* option in *dio_sync*.

Obviously, the *sync* option is only meaningful if the user selects channels (*sets channels for high*) that reside in at least two different output channel registers.

Output channel register 0: Channels 0 to 31
Output channel register 1: Channels 32 to 63
Output channel register 2: Channels 64 to 95

The *skip_dio_disable_check* (when set to *CCURPMFC_FALSE*) causes the call to test for DIO being enabled prior to proceeding. If this option is set to *CCURPMFC_TRUE*, then no test is. If the DIO has not been enabled, output writes will not take place. The only reason for providing the option to disable the check is to improve the performance of the call. If the user can ensure that the DIO is enabled prior to issuing this call, they can set this option to *CCURPMFC_TRUE* so that no test is performed and hence, improve performance.

```
/*  
_ccurpmfc_lib_error_number_t  
ccurPMFC_DIO_Write_Output_Channel_High_Registers(void *Handle,  
_ccurpmfc_dio_output_sync_t dio_sync,  
ccurpmfc_bool skip_dio_disabled_check,  
ccurpmfc_dio_channels_t DIO_OutputChannels)
```

Description: Write DIO Output Channel High Registers

```
Input: void *Handle (handle pointer)  
_ccurpmfc_dio_output_sync_t dio_sync (dio_sync operation)  
# CCURPMFC_DIO_OUTPUT_OPERATION_CONTINUOUS  
# CCURPMFC_DIO_OUTPUT_OPERATION_SYNC  
# CCURPMFC_DIO_OUTPUT_OPERATION_DO_NOT_CHANGE  
ccurpmfc_bool skip_dio_disabled_check (skip dio disabled check)  
# CCURPMFC_TRUE  
# CCURPMFC_FALSE  
ccurpmfc_dio_channels_t DIO_OutputChannels (output channel registers)  
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]  
# CCURPMFC_DIO_CHANNEL_MASK_0  
# CCURPMFC_DIO_CHANNEL_MASK_1  
# CCURPMFC_DIO_CHANNEL_MASK_2  
# CCURPMFC_DIO_CHANNEL_MASK_3  
# CCURPMFC_DIO_CHANNEL_MASK_4  
# CCURPMFC_DIO_CHANNEL_MASK_5  
# CCURPMFC_DIO_CHANNEL_MASK_6  
# CCURPMFC_DIO_CHANNEL_MASK_7  
# CCURPMFC_DIO_CHANNEL_MASK_8  
# CCURPMFC_DIO_CHANNEL_MASK_9  
# CCURPMFC_DIO_CHANNEL_MASK_10
```

```

# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95
Output: none
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR                (successful)
# CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN                (device not open)
# CCURPMFC_LIB_INVALID_ARG             (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION         (local region not present)
# CCURPMFC_LIB_DIO_IS_NOT_ACTIVE       (DIO is not active)
*****/

```

2.2.134 ccurPMFC_DIO_Write_Output_Channel_Low_Registers()

This call writes a selected set of channels to low outputs. Rest of the channels is not affected. There are two modes of operation for this call. (1) Continuous (2) Sync.

When the user selects the *continuous* operation, this call immediately sends out the channel low data to the output lines as they are written to the output registers. There is therefore no synchronizing occurring between the three output channel registers (32 channels/register). For performance improvements with this operational mode, it is recommended that the user sets the continuous option using the *ccurPMFC_DIO_Set_Output_Sync()* call once and then supply *CCURPMFC_DIO_INPUT_OPERATION_DO_NOT_CHANGE* to this call for more writes. In this way, an additional register access will not occur everytime this call is issued.

When the user selects the *sync* operation, they need to issue the *ccurPMFC_DIO_Set_Output_Sync()* call once with the *CCURPMFC_DIO_OUTPUT_OPERATION_SYNC* option, followed by issuing this call with the *CCURPMFC_DIO_OUTPUT_OPERATION_SYNC* option in *dio_sync*.

Obviously, the *sync* option is only meaningful if the user selects channels (*sets channels for low*) that reside in at least two different output channel registers.

```

Output channel register 0: Channels 0 to 31
Output channel register 1: Channels 32 to 63
Output channel register 2: Channels 64 to 95

```

The *skip_dio_disable_check* (when set to *CCURPMFC_FALSE*) causes the call to test for DIO being enabled prior to proceeding. If this option is set to *CCURPMFC_TRUE*, then no test is. If the DIO has not been enabled, output writes will not take place. The only reason for providing the option to disable the check is to improve the performance of the call. If the user can ensure that the DIO is enabled prior to issuing this call, they can set this option to *CCURPMFC_TRUE* so that no test is performed and hence, improve performance.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DIO_Write_Output_Channel_Low_Registers(void *Handle,
_ccurpmfc_dio_output_sync_t dio_sync,
ccurpmfc_bool skip_dio_disabled_check,
ccurpmfc_dio_channels_t DIO_OutputChannels)

```

Description: Write DIO Output Channel Low Registers

```

Input: void *Handle (handle pointer)
_ccurpmfc_dio_output_sync_t dio_sync (dio_sync operation)
# CCURPMFC_DIO_OUTPUT_OPERATION_CONTINUOUS
# CCURPMFC_DIO_OUTPUT_OPERATION_SYNC
# CCURPMFC_DIO_OUTPUT_OPERATION_DO_NOT_CHANGE
ccurpmfc_bool skip_dio_disabled_check (skip dio disabled check)
# CCURPMFC_TRUE
# CCURPMFC_FALSE
ccurpmfc_dio_channels_t DIO_OutputChannels (output channel registers)
# u_int32_t ccurpmfc_dio_channels_t[CCURPMFC_DIO_MAX_REGISTERS]
# CCURPMFC_DIO_CHANNEL_MASK_0
# CCURPMFC_DIO_CHANNEL_MASK_1
# CCURPMFC_DIO_CHANNEL_MASK_2
# CCURPMFC_DIO_CHANNEL_MASK_3
# CCURPMFC_DIO_CHANNEL_MASK_4
# CCURPMFC_DIO_CHANNEL_MASK_5
# CCURPMFC_DIO_CHANNEL_MASK_6
# CCURPMFC_DIO_CHANNEL_MASK_7
# CCURPMFC_DIO_CHANNEL_MASK_8
# CCURPMFC_DIO_CHANNEL_MASK_9
# CCURPMFC_DIO_CHANNEL_MASK_10
# CCURPMFC_DIO_CHANNEL_MASK_11
# CCURPMFC_DIO_CHANNEL_MASK_12
# CCURPMFC_DIO_CHANNEL_MASK_13
# CCURPMFC_DIO_CHANNEL_MASK_14
# CCURPMFC_DIO_CHANNEL_MASK_15
# CCURPMFC_DIO_CHANNEL_MASK_16
# CCURPMFC_DIO_CHANNEL_MASK_17
# CCURPMFC_DIO_CHANNEL_MASK_18
# CCURPMFC_DIO_CHANNEL_MASK_19
# CCURPMFC_DIO_CHANNEL_MASK_20
# CCURPMFC_DIO_CHANNEL_MASK_21
# CCURPMFC_DIO_CHANNEL_MASK_22
# CCURPMFC_DIO_CHANNEL_MASK_23
# CCURPMFC_DIO_CHANNEL_MASK_24
# CCURPMFC_DIO_CHANNEL_MASK_25
# CCURPMFC_DIO_CHANNEL_MASK_26
# CCURPMFC_DIO_CHANNEL_MASK_27
# CCURPMFC_DIO_CHANNEL_MASK_28
# CCURPMFC_DIO_CHANNEL_MASK_29
# CCURPMFC_DIO_CHANNEL_MASK_30
# CCURPMFC_DIO_CHANNEL_MASK_31
# CCURPMFC_DIO_ALL_CHANNELS_MASK
CCURPMFC_DIO_MAX_REGISTERS can be one of:
# CCURPMFC_DIO_CHAN_00_31
# CCURPMFC_DIO_CHAN_32_63
# CCURPMFC_DIO_CHAN_64_95

```

Output: none

```

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_DIO_IS_NOT_ACTIVE (DIO is not active)
*****/

```

2.2.135 ccurPMFC_Disable_Pci_Interrupts()

The purpose of this call is to disable PCI interrupts. This call shouldn't be used during normal reads as calls could time out. The driver handles enabling and disabling interrupts during its normal course of operation.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Disable_Pci_Interrupts(void *Handle,
                                uint interrupt_mask)

Description: Disable interrupts being generated by the board.

Input:   void          *Handle          (Handle pointer)
         uint          interrupt_mask   (interrupt mask)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_IOCTL_FAILED      (driver ioctl call
                                         failed)
*****/

```

2.2.136 ccurPMFC_DMA_Configure()

The purpose of this call is configure a DMA engine to be ready for commencing DMA.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DMA_Configure(void          *Handle,
                        ccurpmfc_dma_engine_t DMAEngineNo,
                        uint          AvMM_FromAddr,
                        uint          AvMM_ToAddr,
                        uint          DMASize)

Description: Configure DMA Engine

Input:   void          *Handle          (Handle pointer)
         ccurpmfc_dma_engine_t DMAEngineNo (select DMA engine)
         # CCURPMFC_DMA0
         # CCURPMFC_DMA1
         uint          AvMM_FromAddr (Avalon Memory Converted Source
                                     Address)
         uint          AvMM_ToAddr  (Avalon Memory Converted
                                     Destination Address)
         uint          DMASize      (DMA transfer size in bytes)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (library not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
*****/

```

2.2.137 ccurPMFC_DMA_Fire()

The purpose of this call is to initiate an already configured DMA engine.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_DMA_Fire(void                *Handle,
                  ccurpmfc_dma_engine_t DMAEngineNo,
                  ccurpmfc_bool        UseInterrupts,
                  ccurpmfc_bool        WaitForCompletion,
                  int                   DmaControl)

Description: Start DMA Engine

Input:  void                *Handle                (Handle pointer)
        ccurpmfc_dma_engine_t DMAEngineNo        (select DMA engine)
        # CCURPMFC_DMA0
        # CCURPMFC_DMA1
        ccurpmfc_bool        UseInterrupts        (Enable Interrupt flag)
        # CCURPMFC_TRUE
        # CCURPMFC_FALSE
        ccurpmfc_bool        WaitForCompletion    (Wait for Completion Flag)
        # CCURPMFC_TRUE
        # CCURPMFC_FALSE
        int                   DmaControl          (DMA control flags)
        # CCURPMFC_DMA_CONTROL_RCON            (read constant)
        # CCURPMFC_DMA_CONTROL_WCON            (write constant)
        # CCURPMFC_DMA_CONTROL_INCREMENT       (increment)

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (no error)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (library not open)
        # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
        # CCURPMFC_LIB_IOCTL_FAILED            (ioctl failed)
        # CCURPMFC_LIB_DMA_FAILED              (DMA failed)
*****/

```

2.2.138 ccurPMFC_Enable_Pci_Interrupts()

The purpose of this call is to enable PCI interrupts. This call shouldn't be used during normal reads as calls could time out. The driver handles enabling and disabling interrupts during its normal course of operation.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Enable_Pci_Interrupts (void *Handle,
                                uint interrupt_mask)

Description: Enable interrupts being generated by the board.

Input:  void                *Handle                (Handle pointer)
        uint                 interrupt_mask        (interrupt mask)

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_IOCTL_FAILED            (driver ioctl call failed)
*****/

```


2.2.139 ccurPMFC_Fast_Memcpy()

The purpose of this call is to provide a fast mechanism to copy between hardware and memory using programmed I/O. The library performs appropriate locking while the copying is taking place.

```

/*****
ccurPMFC_Fast_Memcpy(void          *Handle,
                    volatile void *Destination,
                    volatile void *Source,
                    int            SizeInBytes)

Description: Perform fast copy to/from buffer using Programmed I/O
            (WITH LOCKING)

Input:   void          *Handle          (Handle pointer)
         volatile void *Source         (pointer to source buffer)
         int           SizeInBytes     (transfer size in bytes)
Output:  volatile void *Destination   (pointer to destination buffer)
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR      (successful)
         # CCURPMFC_LIB_BAD_HANDLE   (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN     (device not open)
*****/
```

2.2.140 ccurPMFC_Fast_Memcpy_Unlocked()

The purpose of this call is to provide a fast mechanism to copy between hardware and memory using programmed I/O. The library does not perform any locking. User needs to provide external locking instead.

```

/*****
void
ccurPMFC_Fast_Memcpy_Unlocked(volatile void *Destination,
                              volatile void *Source,
                              int           SizeInBytes
                              int           DoubleWordSupport)

Description: Perform fast copy to/from buffer using Programmed I/O
            (WITHOUT LOCKING)

Input:   volatile void *Source         (pointer to source buffer)
         int           SizeInBytes     (transfer size in bytes)
         int           DoubleWordSupport (double word support flag)
Output:  volatile void *Destination   (pointer to destination buffer)
Return:  none
*****/
```

2.2.141 ccurPMFC_Fast_Memcpy_Unlocked_FIFO()

The purpose of this call is to provide a simple mechanism to copy between hardware FIFO and memory using programmed I/O. The library does not perform any locking. User needs to provide external locking instead.

```

/*****
void
ccurPMFC_Fast_Memcpy_Unlocked_FIFO(volatile void *Destination,
                                    volatile void *Source,
                                    int           SizeInWords,
                                    int           PioControl,
                                    int           DoubleWordSupport)

Description: Perform fast copy to/from FIFO buffer using Programmed I/O
            (WITHOUT LOCKING)

Input:   volatile void *Source         (pointer to source buffer)
*****/
```

```

        int          SizeInWords          (transfer size in words)
        int          PioControl           (PIO Control)
        # CCURPMFC_PIO_CONTROL_RCON      (read constant)
        # CCURPMFC_PIO_CONTROL_WCON      (write constant)
        # CCURPMFC_PIO_CONTROL_INCREMENT (read/write increment)
    Output: volatile void *Destination    (pointer to destination buffer)
    Return: none
    *****/

```

2.2.142 ccurPMFC_Fraction_To_Hex()

This converts a fractional decimal to a hexadecimal value.

```

/*****
    int
    ccurPMFC_Fraction_To_Hex (double Fraction,
                             uint   *value)

    Description: Convert Fractional Decimal to Hexadecimal

    Input:      double   Fraction      (fraction to convert)
    Output:     uint     *value;       (converted hexadecimal value)
    Return:     1        (call failed)
               0        (good return)
    *****/

```

2.2.143 ccurPMFC_Get_All_Boards_Driver_Info()

This call returns driver information for all the *ccurpmfc* cards that have been found in the system.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Get_All_Boards_Driver_Info(void          *Handle,
                                             ccurpmfc_all_boards_driver_info *all_boards_info)

    Description: Get device information from driver for all boards.

    Input:      void          *Handle      (Handle pointer)
    Output:     ccurpmfc_driver_info_t    *all_boards_info (info struct pointer)
               char          version[12]
               char          built[32]
               char          module_name[16]
               int           board_index
               int           table_index
               char          board_desc[32]
               int           bus
               int           slot
               int           func
               int           vendor_id
               int           sub_vendor_id
               int           sub_device_id
               union {
                   u_int      BoardInfo
                   ccurpmfc_boardinfo_t BInfo
               }
               union {
                   u_int      FirmwareDate
                   ccurpmfc_firmware_date_t FmDate
               }
               union {
                   u_int      FirmwareRevision
                   ccurpmfc_firmware_revision_t FmRev
               }
    *****/

```

```

int                                 msi_support
int                                 irqlevel
double                              calibration_reference_voltage

int                                 driver_dma_size

// DMA
ccurpmfc_driver_dma_info_t         dma_info
- short   num_trans_tbl_entries
- int     avalon_page_bits
- int     avalon_page_size
- int     tx_interface_base
- int     dma_max_engines
- int     dma_max_burst_size
- int     dma_max_transactions
- int     dma_max_size
  - int     dma_width_in_bytes
  - int     dma_fire_command

// Interrupt
ccurpmfc_driver_int_t              interrupt
- union {
-   uint           status
-   uint           InterruptsOccurredMask
- }
- union {
-   uint           mask
-   uint           WakeupInterruptMask
- }
- int             timeout_seconds
- int             DmaControl
- long long unsigned   count
- long long unsigned   dma_count[CCURPMFC_DMA_MAX_ENGINES]
- long long unsigned   MsgDma_count
// DIO COS Interrupt
ccurpmfc_driver_dio_cos_int_t      dio_cos_interrupt
- union {
-   uint           status
-   uint           InterruptsOccurredMask
- }
- union {
-   uint           mask
-   uint           WakeupInterruptMask
- }

- // DIO information
- union {
-   ccurpmfc_dio_channels_t DIO_COS_ChannelsStatus
-   ccurpmfc_dio_channel_t  DIO_COS_ChannelsStatusX
- }
- union {
-   ccurpmfc_dio_channels_t DIO_COS_ChannelsOverflow
-   ccurpmfc_dio_channel_t  DIO_COS_ChannelsOverflowX
- }

ccurpmfc_interrupt_dio_cos_counters_t  counters
- long long unsigned   dio_interrupt_count
- long long unsigned   dma_count[CCURPMFC_DMA_MAX_ENGINES]
- long long unsigned   DIO_COS_ChannelsCount[CCURPMFC_DIO_MAX_REGISTERS]
- long long unsigned   DIO_COS_ChannelsOverflowCount[CCURPMFC_DIO_MAX_REGISTERS]

int                                 Ccurpmfc_Max_Region

```

```

// Memory Region
ccurpmfc_dev_region_t          mem_region[CCURPMFC_MAX_REGION]
- uint physical_address
- uint size
- uint flags
- uint *virtual_address

// ADC
ccurpmfc_driver_adc_info_t     adc_info
- double adc_max_voltage_range
- int    number_of_adcs
- int    number_of_adc_channels
- int    number_of_adc_resolutionbits
- int    all_adc_channels_mask
- int    max_adc_fifo_threshold
- int    max_adc_frequency

// DAC
ccurpmfc_driver_dac_info_t     dac_info
- double dac_max_voltage_range
- int    number_of_dacs
- int    number_of_dac_channels
- int    number_of_dac_resolutionbits
- int    all_dac_channels_mask
- int    max_dac_fifo_threshold
- int    max_dac_frequency

// DIO
ccurpmfc_driver_dio_info_t     dio_info
- int    number_of_dio_channels
- int    number_of_dio_ports
- int    number_of_dio_channels_per_port
- int    number_of_dio_registers
- int    number_of_dio_channels_per_register

// SDRAM
ccurpmfc_driver_sdram_info_t   sdram_info
- int    sdram_max_size_in_words
- _ccurpmfc_clock_generator_output_t sdram_output_clock
- double sdram_output_clock_frequency

// CLOCK
ccurpmfc_driver_clock_info_t   clock_info
- _ccurpmfc_cg_input_clock_select_register_t default_input_clock
- double default_input_clock_frequency
- double default_clock_tolerance_ppt

ccurpmfc_sprom_header_t        sprom_header
- u_int32_t board_serial_number
- u_short   sprom_revision

// Chip Temperature
char                            fpga_chip_temperature

char                            double_word_support

union {
    u_int                            FirmwareTime
    ccurpmfc_firmware_time_t         FmTime
}

union {
    u_int                            FirmwareFlavorCode
    ccurpmfc_firmware_option_code_t FmOptionCode
}

```

```

    }
    u_int                                     NumberAdvancedIPCores

    u_short                                   RunLevelSectorNumber
    char                                       FirmwareReloadFailed
    char                                       MultiFirmwareSupport

    _ccurpmfc_ipcore_t                       IpCore[CCURPMFC_MAX_IO_CORES]
    - u_int32_t   IpCoreCode
    - union {
    -   u_int32_t   IpCoreRevision
    -   ccurpmfc_ipcore_revision_t   IpCRev
    - }
    - u_int32_t   IpCoreOffset
    - union {
    -   u_int32_t   IpCoreInformation
    -   ccurpmfc_ipcore_information_t   IpCInf
    - }

    union {
        u_int                                     Dummy_time_t[2]
        time_t                                     DriverLoadCurrentTime
    }

    u_int32_t                                   FirmwareBoardSerialNumber

    u_int32_t                                   MaxMsgDmaDescriptors
    u_int32_t                                   MaxMsgDmaSize
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
        # CCURPMFC_LIB_IOCTL_FAILED            (driver ioctl call failed)
    *****/

```

2.2.144 ccurPMFC_Get_Board_CSR()

This call returns information from the board status register.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Board_CSR (void *Handle,
                        ccurpmfc_board_csr_t *bcsr)

Description: Get Board Control and Status information

Input:  void *Handle (Handle pointer)
Output: ccurpmfc_board_csr_t *bcsr (pointer to board csr)
        _ccurpmfc_bcsr_identify_board_t identify_board
        # CCURPMFC_BCSR_IDENTIFY_BOARD_DISABLE
        # CCURPMFC_BCSR_IDENTIFY_BOARD_ENABLE

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION         (local region not present)
    *****/

```

2.2.145 ccurPMFC_Get_Board_Info()

This call returns the board id, the board type and the firmware revision level for the selected board. This board id is 0x9277 and board type is 0x1 or 0x9278 with a board type of 0x2.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Board_Info (void *Handle,
                        ccurpmfc_board_info_t *binfo)
Description: Get Board Information

Input:  void *Handle (Handle pointer)
Output: ccurpmfc_board_info_t *binfo (pointer to board info)
        int vendor_id
        int sub_vendor_id
        int sub_device_id
        ccurpmfc_boardinfo_t BInfo
        u_char Function
        u_char Type
        u_short Id
        ccurpmfc_firmware_date_t FmDate
        u_short Year
        u_char Day
        u_char Month
        ccurpmfc_firmware_revision_t FmRev
        u_short Minor
        u_short Major
        ccurpmfc_sprom_header_t sprom_header
        u_int32_t board_serial_number
        u_short sprom_revision
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
*****/
```

2.2.146 ccurPMFC_Get_Calibration_CSR()

This call returns the current calibration control and status register.

```

/*****
ccurPMFC_Get_Calibration_CSR()

Description: Get Calibration Control and Status Register

Input:  void *Handle (Handle pointer)
Output: ccurpmfc_calibration_csr_t *CalCSR (pointer to calibration CSR)
        _ccurpmfc_calbus_control_t BusControl (bus control)
        # CCURPMFC_CB_GROUND
        # CCURPMFC_CB_POSITIVE_REFERENCE
        # CCURPMFC_CB_NEGATIVE_REFERENCE
        # CCURPMFC_CB_BUS_OPEN
        # CCURPMFC_CB_2_5V_REFERENCE
        # CCURPMFC_CB_5V_REFERENCE
        # CCURPMFC_CB_DAC_CHANNEL_0
        # CCURPMFC_CB_DAC_CHANNEL_1
        # CCURPMFC_CB_DAC_CHANNEL_2
        # CCURPMFC_CB_DAC_CHANNEL_3
        # CCURPMFC_CB_DAC_CHANNEL_4
        # CCURPMFC_CB_DAC_CHANNEL_5
        # CCURPMFC_CB_DAC_CHANNEL_6
*****/
```

```

# CCURPMFC_CB_DAC_CHANNEL_7
# CCURPMFC_CB_DAC_CHANNEL_8
# CCURPMFC_CB_DAC_CHANNEL_9
# CCURPMFC_CB_DAC_CHANNEL_10
# CCURPMFC_CB_DAC_CHANNEL_11
# CCURPMFC_CB_DAC_CHANNEL_12
# CCURPMFC_CB_DAC_CHANNEL_13
# CCURPMFC_CB_DAC_CHANNEL_14
# CCURPMFC_CB_DAC_CHANNEL_15
Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR           (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
*****/

```

2.2.147 ccurPMFC_Get_Driver_Error()

This call returns the last error generated by the driver.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Driver_Error (void          *Handle,
                           ccurpmfc_user_error_t *ret_err)

Description: Get the last error generated by the driver.

Input:  void          *Handle          (Handle pointer)
Output: ccurpmfc_user_error_t *ret_err (error struct pointer)
        uint error;                    (error number)
        char name[CCURPMFC_ERROR_NAME_SIZE] (error name used in driver)
        char desc[CCURPMFC_ERROR_DESC_SIZE] (error description)

Return:  _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR           (successful)
# CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
# CCURPMFC_LIB_IOCTL_FAILED      (driver ioctl call failed)
*****/

```

```

#define CCURPMFC_ERROR_NAME_SIZE    64
#define CCURPMFC_ERROR_DESC_SIZE    128

```

```

typedef struct _ccurpmfc_user_error_t
{
    uint error;                    /* error number */
    char name[CCURPMFC_ERROR_NAME_SIZE]; /* error name used in driver */
    char desc[CCURPMFC_ERROR_DESC_SIZE]; /* error description */
} ccurpmfc_user_error_t;

```

```

enum
{
    CCURPMFC_SUCCESS = 0,
    CCURPMFC_INVALID_PARAMETER,
    CCURPMFC_DMA_TIMEOUT,
    CCURPMFC_OPERATION_CANCELLED,
    CCURPMFC_RESOURCE_ALLOCATION_ERROR,
    CCURPMFC_INVALID_REQUEST,
    CCURPMFC_FAULT_ERROR,
    CCURPMFC_BUSY,
    CCURPMFC_ADDRESS_IN_USE,
    CCURPMFC_USER_INTERRUPT_TIMEOUT,

```

```

    CCURPMFC_DMA_INCOMPLETE,
    CCURPMFC_DATA_UNDERFLOW,
    CCURPMFC_DATA_OVERFLOW,
    CCURPMFC_IO_FAILURE,
    CCURPMFC_OPERATION_NOT_SUPPORTED,
    CCURPMFC_ADC_FIFO_THRESHOLD_TIMEOUT,
    CCURPMFC_DAC_FIFO_THRESHOLD_TIMEOUT,
    CCURPMFC_INTERRUPT_HANDLER_NOT_ENABLED,
    CCURPMFC_FIRMWARE_RELOAD_FAILED,
};

```

2.2.148 ccurPMFC_Get_Driver_Info()

This call returns internal information that is maintained by the driver.

```

/*****

```

```

    _ccurpmfc_lib_error_number_t
    ccurPMFC_Get_Driver_Info (void          *Handle,
                             ccurpmfc_driver_info_t *info)

```

Description: Get device information from driver.

```

Input:  void          *Handle      (Handle pointer)
Output: ccurpmfc_driver_info_t   *info      (info struct pointer)
    char          version[12]
    char          built[32]
    char          module_name[16]
    int           board_index
    int           table_index
    char          board_desc[32]
    int           bus
    int           slot
    int           func
    int           vendor_id
    int           sub_vendor_id
    int           sub_device_id
    union {
        u_int          BoardInfo
        ccurpmfc_boardinfo_t BInfo
    }
    union {
        u_int          FirmwareDate
        ccurpmfc_firmware_date_t FmDate
    }
    union {
        u_int          FirmwareRevision
        ccurpmfc_firmware_revision_t FmRev
    }
    int           msi_support
    int           irqlevel
    double        calibration_reference_voltage

    int           driver_dma_size

    // DMA
    ccurpmfc_driver_dma_info_t dma_info
    - short       num_trans_tbl_entries
    - int         avalon_page_bits
    - int         avalon_page_size
    - int         tx_interface_base
    - int         dma_max_engines
    - int         dma_max_burst_size
    - int         dma_max_transactions

```



```

- int      dma_max_size
- int      dma_width_in_bytes
- int      dma_fire_command

// Interrupt
ccurpmfc_driver_int_t          interrupt
- union {
-   uint          status
-   uint          InterruptsOccurredMask
- }
- union {
-   uint          mask
-   uint          WakeupInterruptMask
- }
- int             timeout_seconds
- int             DmaControl
- long long unsigned count
- long long unsigned dma_count[CCURPMFC_DMA_MAX_ENGINES]
- long long unsigned MsgDma_count
// DIO COS Interrupt
ccurpmfc_driver_dio_cos_int_t  dio_cos_interrupt
- union {
-   uint          status
-   uint          InterruptsOccurredMask
- }
- union {
-   uint          mask
-   uint          WakeupInterruptMask
- }

- // DIO information
- union {
-   ccurpmfc_dio_channels_t DIO_COS_ChannelsStatus
-   ccurpmfc_dio_channel_t  DIO_COS_ChannelsStatusX
- }
- union {
-   ccurpmfc_dio_channels_t DIO_COS_ChannelsOverflow
-   ccurpmfc_dio_channel_t  DIO_COS_ChannelsOverflowX
- }

ccurpmfc_interrupt_dio_cos_counters_t counters
- long long unsigned dio_interrupt_count
- long long unsigned dma_count[CCURPMFC_DMA_MAX_ENGINES]
- long long unsigned DIO_COS_ChannelsCount[CCURPMFC_DIO_MAX_REGISTERS]
- long long unsigned
    DIO_COS_ChannelsOverflowCount[CCURPMFC_DIO_MAX_REGISTERS]

int                                     Ccurpmfc_Max_Region

// Memory Region
ccurpmfc_dev_region_t                mem_region[CCURPMFC_MAX_REGION]
- uint physical_address
- uint size
- uint flags
- uint *virtual_address

// ADC
ccurpmfc_driver_adc_info_t           adc_info
- double adc_max_voltage_range
- int    number_of_adcs
- int    number_of_adc_channels
- int    number_of_adc_resolutionbits
- int    all_adc_channels_mask

```

```

- int    max_adc_fifo_threshold
- int    max_adc_frequency

// DAC
ccurpmfc_driver_dac_info_t      dac_info
- double dac_max_voltage_range
- int    number_of_dacs
- int    number_of_dac_channels
- int    number_of_dac_resolutionbits
- int    all_dac_channels_mask
- int    max_dac_fifo_threshold
- int    max_dac_frequency

// DIO
ccurpmfc_driver_dio_info_t      dio_info
- int    number_of_dio_channels
- int    number_of_dio_ports
- int    number_of_dio_channels_per_port
- int    number_of_dio_registers
- int    number_of_dio_channels_per_register

// SDRAM
ccurpmfc_driver_sdram_info_t    sdram_info
- int    sdram_max_size_in_words
- _ccurpmfc_clock_generator_output_t sdram_output_clock
- double sdram_output_clock_frequency

// CLOCK
ccurpmfc_driver_clock_info_t    clock_info
- _ccurpmfc_cg_input_clock_select_register_t default_input_clock
- double default_input_clock_frequency
- double default_clock_tolerance_ppt

ccurpmfc_sprom_header_t         sprom_header
- u_int32_t board_serial_number
- u_short   sprom_revision

// Chip Temperature
char                             fpga_chip_temperature

char                             double_word_support

union {
    u_int                             FirmwareTime
    ccurpmfc_firmware_time_t          FmTime
}

union {
    u_int                             FirmwareFlavorCode
    ccurpmfc_firmware_option_code_t   FmOptionCode
}
u_int                             NumberAdvancedIPCores

u_short                           RunLevelSectorNumber
char                               FirmwareReloadFailed
char                               MultiFirmwareSupport

_ccurpmfc_ipcore_t                IpCore[CCURPMFC_MAX_IO_CORES]
- u_int32_t IpCoreCode
- union {
-     u_int32_t IpCoreRevision
-     ccurpmfc_ipcore_revision_t IpCRev
- }
- u_int32_t IpCoreOffset
- union {

```

```

-     u_int32_t                IpCoreInformation
-     ccurpmfc_ipcore_information_t  IpCInf
- }

union {
    u_int                Dummy_time_t[2]
    time_t                DriverLoadCurrentTime
}

u_int32_t                FirmwareBoardSerialNumber

u_int32_t                MaxMsgDmaDescriptors
u_int32_t                MaxMsgDmaSize

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR            (successful)
        # CCURPMFC_LIB_BAD_HANDLE         (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN           (device not open)
        # CCURPMFC_LIB_INVALID_ARG        (invalid argument)
        # CCURPMFC_LIB_IOCTL_FAILED       (driver ioctl call failed)
*****/

```

2.2.149 ccurPMFC_Get_Interrupt_Status()

This call returns the current status of the various interrupts.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Interrupt_Status (void                *Handle,
                             ccurpmfc_interrupt_t *intr)

Description: Get Interrupt Status information

Input:  void                *Handle            (handle pointer)
Output: ccurpmfc_interrupt_t *intr            (pointer to interrupt status)
        _ccurpmfc_intsta_dio_cos_t dio_cos_group2_int
        # CCURPMFC_INT_DIO_COS_NONE
        # CCURPMFC_INT_DIO_COS_OCCURRED
        _ccurpmfc_intsta_dio_cos_t dio_cos_group1_int
        # CCURPMFC_INT_DIO_COS_NONE
        # CCURPMFC_INT_DIO_COS_OCCURRED
        _ccurpmfc_intsta_dio_cos_t dio_cos_group0_int
        # CCURPMFC_INT_DIO_COS_NONE
        # CCURPMFC_INT_DIO_COS_OCCURRED
        _ccurpmfc_intsta_dac_t
        # CCURPMFC_INT_DAC_FIFO_THRESHOLD_NONE
        # CCURPMFC_INT_DAC_FIFO_THRESHOLD_OCCURRED
        _ccurpmfc_intsta_adc_t
        # CCURPMFC_INT_ADC_FIFO_THRESHOLD_NONE
        # CCURPMFC_INT_ADC_FIFO_THRESHOLD_OCCURRED
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR            (successful)
        # CCURPMFC_LIB_BAD_HANDLE         (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN           (device not open)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region error)
        # CCURPMFC_LIB_INVALID_ARG        (invalid argument)
*****/

```

2.2.150 ccurPMFC_Get_Interrupt_Timeout_Seconds()

This call returns the read time out maintained by the driver. It is the time that the read call will wait before it times out. The call could time out because a DMA fails to complete. The device should have been opened in the block mode (*O_NONBLOCK* not set) for reads to wait for the operation to complete.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Interrupt_Timeout_Seconds (void      *Handle,
                                         int       *int_timeout_secs)

Description: Get Interrupt Timeout Seconds

Input:   void      *Handle      (Handle pointer)
Output:  int       *int_timeout_secs (pointer to int tout secs)
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN      (device not open)
        # CCURPMFC_LIB_INVALID_ARG   (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_IOCTL_FAILED  (ioctl error)
*****/

```

2.2.151 ccurPMFC_Get_Lib_Error()

This call provides detailed information about the last library error that was maintained by the API. The call itself can fail with a return code if an invalid handle is provided, the device is not open or device authorization has failed. If the call succeeds *CCURPMFC_LIB_NO_ERROR*, the last library error information is supplied to the user in the *ccurpmfc_lib_error_t* structure.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Lib_Error (void      *Handle,
                       ccurpmfc_lib_error_t *lib_error)

Description: Get last error generated by the library.

Input:   void      *Handle      (Handle pointer)
Output:  ccurpmfc_lib_error_t *lib_error (error struct pointer)
        uint error      (last library error number)
        char name[CCURPMFC_LIB_ERROR_NAME_SIZE] (last library error name)
        char desc[CCURPMFC_LIB_ERROR_DESC_SIZE] (last library error description)
        int line_number (last library error line number in lib)
        char function[CCURPMFC_LIB_ERROR_FUNC_SIZE] (library function in error)

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN      (device not open)
        # CCURPMFC_LIB_AUTHORIZATION_FAILURE (device authorization failure)
*****/

```

```

typedef struct _ccurpmfc_lib_error_t {
    uint    error; /* lib error number */
    char    name[CCURPMFC_LIB_ERROR_NAME_SIZE]; /* error name used in lib */
    char    desc[CCURPMFC_LIB_ERROR_DESC_SIZE]; /* error description */
    int     line_number; /* line number in library */
    char    function[CCURPMFC_LIB_ERROR_FUNC_SIZE]; /* library function */
} ccurpmfc_lib_error_t;

```

Possible library errors:

```

typedef enum {
    CCURPMFC_LIB_NO_ERROR      = 0, /* Successful */
    CCURPMFC_LIB_INVALID_ARG   = -1, /* Invalid argument */
    CCURPMFC_LIB_ALREADY_OPEN  = -2, /* Already open */
}

```

```

CCURPMFC_LIB_OPEN_FAILED = -3, /* Open failed */
CCURPMFC_LIB_BAD_HANDLE = -4, /* Bad handle */
CCURPMFC_LIB_NOT_OPEN = -5, /* Device not opened */
CCURPMFC_LIB_MMAP_SELECT_FAILED = -6, /* Mmap selection failed */
CCURPMFC_LIB_MMAP_FAILED = -7, /* Mmap failed */
CCURPMFC_LIB_MUNMAP_FAILED = -8, /* Munmap failed */
CCURPMFC_LIB_NOT_MAPPED = -9, /* Not mapped */
CCURPMFC_LIB_ALREADY_MAPPED = -10, /* Already mapped */
CCURPMFC_LIB_IOCTL_FAILED = -11, /* Driver ioctl failed */
CCURPMFC_LIB_IO_ERROR = -12, /* I/O error */
CCURPMFC_LIB_INTERNAL_ERROR = -13, /* Internal library error */
CCURPMFC_LIB_NOT_IMPLEMENTED = -14, /* Call not implemented */
CCURPMFC_LIB_LOCK_FAILED = -15, /* Failed to get lib lock */
CCURPMFC_LIB_NO_LOCAL_REGION = -16, /* Local region not present */
CCURPMFC_LIB_NO_CONFIG_REGION = -17, /* Config region not present*/
CCURPMFC_LIB_NO_SOLUTION_FOUND = -18, /* No solution found */
CCURPMFC_LIB_NO_RESOURCE = -19, /* Resource not available */
CCURPMFC_LIB_CANNOT_OPEN_FILE = -20, /* Cannot open file */
CCURPMFC_LIB_DMA_BUSY = -21, /* DMA busy */
CCURPMFC_LIB_AVALON_TRANSLATION_TABLE = -22, /* Avalon Translation Table
Error */
CCURPMFC_LIB_ADDRESS_RANGE_ERROR = -23, /* Physical DMA Address
Exceeds Memory Size */
CCURPMFC_LIB_NO_SPACE_IN_TABLE = -24, /* No space available to
allocate any more physical
memory */
CCURPMFC_LIB_CANNOT_ALLOCATE_PHYS_MEM = -25, /* Cannot allocate physical
memory */
CCURPMFC_LIB_DMA_FAILED = -26, /* DMA failed */
CCURPMFC_LIB_THREAD_CREATE_FAILED = -27, /* Thread Creation failed */
CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE = -28, /* Clock Generator is not
active */
CCURPMFC_LIB_CANNOT_COMPUTE_OUTPUT_FREQ = -29, /* Cannot compute output
frequency */
CCURPMFC_LIB_N_DIVIDERS_EXCEEDED = -30, /* Number of N-Dividers
exceeded */
CCURPMFC_LIB_CLOCK_GENERATION_FAILED = -31, /* Clock Generation Failed */
CCURPMFC_LIB_CALIBRATION_RANGE_ERROR = -32, /* Calibration voltage out of
range */
CCURPMFC_LIB_BAD_DATA_IN_CAL_FILE = -33, /* Bad data in calibration
file*/
CCURPMFC_LIB_VOLTAGE_NOT_IN_RANGE = -34, /* Voltage not in range */
CCURPMFC_LIB_ADC_IS_NOT_ACTIVE = -35, /* ADC is not active */
CCURPMFC_LIB_DAC_IS_NOT_ACTIVE = -36, /* DAC is not active */
CCURPMFC_LIB_ADC_INCORRECTLY_CONFIGURED = -37,
/* ADC incorrectly configured for DAC readback */
CCURPMFC_LIB_SDRAM_IS_NOT_ACTIVE = -38, /* SDRAM is not active */
CCURPMFC_LIB_SDRAM_INITIALIZATION_FAILED = -39, /* SDRAM failed to initialize */
CCURPMFC_LIB_DAC_FIFO_UNDERFLOW = -40, /* DAC Fifo Underflow Occurred */
CCURPMFC_LIB_DAC_FIFO_OVERFLOW = -41, /* DAC Fifo Overflow Occurred */
CCURPMFC_LIB_DAC_IS_BUSY = -42, /* DAC is busy */
CCURPMFC_LIB_DIO_IS_NOT_ACTIVE = -43, /* DIO is not active */
CCURPMFC_LIB_SERIAL_PROM_FAILURE = -44, /* Serial PROM Failure -
Malfunction or not present */
CCURPMFC_LIB_SERIAL_PROM_BUSY = -45, /* Serial PROM Busy */
CCURPMFC_LIB_SERIAL_PROM_WRITE_PROTECTED = -46, /*Serial PROM is Write Protected*/
CCURPMFC_LIB_AUTHORIZATION_FAILURE = -47, /* Authorization failure */
CCURPMFC_LIB_INTHDLR_CREATE_FAILURE = -48, /* Interrupt handler creation
failure */
CCURPMFC_LIB_INTHDLR_ALREADY_RUNNING = -49, /* Interrupt handler already
running */
CCURPMFC_LIB_IPCORE_COS_IS_NOT_ACTIVE = -50, /* IP Core COS is Not active*/
CCURPMFC_LIB_NO_FREE_DESCRIPTOR_AVAILABLE

```

```

= -51, /* No Free Descriptors
Available */
CCURPMFC_LIB_ERROR_IN_DESCRIPTOR_LIST = -52, /* Error in Descriptor List */
CCURPMFC_LIB_MSGDMA_NOT_SUPPORTED = -53, /* Modular Scatter-Gather DMA
Not Supported */
CCURPMFC_LIB_MSGDMA_READS_NOT_ALLOWED_FOR_SELECTED_ADDRESS
= -54, /* MSG DMA Reads Not Allowed
for Selected Address */
CCURPMFC_LIB_NOT_OWNER_OF_MSGDMA = -55, /* Not Owner of Modular
Scatter-Gather DMA */
CCURPMFC_LIB_MSGDMA_IN_USE = -56, /* Modular Scatter-Gather DMA
In Use */
} _ccurpmfc_lib_error_number_t;

```

2.2.152 ccurPMFC_Get_Library_Info()

This call returns useful library information to the user.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Library_Info (void *Handle,
                           ccurpmfc_library_info_t *info)

Description: Get library information

Input: void *Handle (Handle pointer)
Output: ccurpmfc_library_info_t *info (info struct pointer)
        int fp;

        ccurpmfc_local_ctrl_data_t *local_ptr;
        -- structure in ccurpmfc_user.h
        void *munmap_local_ptr;
        int local_mmap_size;

        ccurpmfc_config_local_data_t *config_ptr;
        -- structure in ccurpmfc_user.h
        void *munmap_config_ptr;
        int config_mmap_size;

        ccurpmfc_user_phys_mem_t
        hysMem[CCURPMFC_MAX_AVALON_NUM_TRANS_TBL_ENTRIES];
        -- structure in ccurpmfc_user.h

        ccurpmfc_driver_library_common_t *driver_lib_ptr;
        -- structure in ccurpmfc_user.h
        void *munmap_driver_lib_ptr;
        int driver_lib_mmap_size;

        void *IpCore_Engine_ptr
        void *IpCore_InjIgn_Pulse_Capture_ptr
        void *IpCore_PWM_Input_ptr
        void *IpCore_PWM_Output_ptr
        void *IpCore_Tooth_Wheel_Generator_ptr
        ccurpmfc_ipcore_cos_t *IpCore_COS_ptr
        void *IpCore_SENT_Receiver_ptr
        void *IpCore_SENT_Transmitter_ptr
        void *IpCore_Angular_Encoder_ptr
        void *IpCore_Angular_Decoder_ptr
        void *IpCore_Knock_Sensor_ptr
        void *IpCore_Analog_Threshold_ptr
        void *IpCore_Inverter_ptr
        void *IpCore_Motor_ptr
        void *IpCore_21_ptr

```

```

void *IpCore_22_ptr
void *IpCore_23_ptr
void *IpCore_24_ptr
void *IpCore_25_ptr
void *IpCore_26_ptr
void *IpCore_27_ptr
void *IpCore_28_ptr
void *IpCore_29_ptr
void *IpCore_30_ptr
void *FpgaWbLib
_ccurpmfc_ipcore_t IpCoreSpecific[CCURPMFC_MAX_IO_CORES]
uint UserPid
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
*****/

```

2.2.153 ccurPMFC_Get_Mapped_Config_Ptr()

If the user wishes to bypass the API and communicate directly with the board configuration registers, then they can use this call to acquire a pointer to these registers. Please note that any type of access (read or write) by bypassing the API could compromise the API and results could be unpredictable. It is recommended that only advanced users should use this call and with extreme care and intimate knowledge of the hardware programming registers before attempting to access these registers. For information on the registers, refer to the *ccurpmfc_user.h* include file that is supplied with the driver.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Mapped_Config_Ptr (void *Handle,
                                ccurpmfc_config_local_data_t **config_ptr)

Description: Get mapped configuration pointer.

Input: void *Handle (Handle pointer)
Output: ccurpmfc_config_local_data_t **config_ptr (config struct ptr)
        -- structure in ccurpmfc_user.h
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_NO_CONFIG_REGION (config region not present)
*****/

```

2.2.154 ccurPMFC_Get_Mapped_Driver_Library_Ptr()

The driver and library share a common structure. This call returns a pointer to the shared driver/library structure.

```

/*****
ccurPMFC_Get_Mapped_Driver_Library_Ptr()
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Mapped_Driver_Library_Ptr (void *Handle,
                                         ccurpmfc_driver_library_common_t **driver_lib_ptr)

Description: Get mapped Driver/Library structure pointer.

Input: void *Handle (Handle pointer)
Output: ccurpmfc_driver_library_common_t **driver_lib_ptr (driver_lib

```

```

                                                    struct ptr)
-- structure in ccurpmfc_user.h
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN              (device not open)
        # CCURPMFC_LIB_INVALID_ARG          (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION      (local region not present)

*****/

```

2.2.155 ccurPMFC_Get_Mapped_Local_Ptr()

If the user wishes to bypass the API and communicate directly with the board control and data registers, then they can use this call to acquire a pointer to these registers. Please note that any type of access (read or write) by bypassing the API could compromise the API and results could be unpredictable. It is recommended that only advanced users should use this call and with extreme care and intimate knowledge of the hardware programming registers before attempting to access these registers. For information on the registers, refer to the *ccurpmfc_user.h* include file that is supplied with the driver.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Mapped_Local_Ptr (void                *Handle,
                               ccurpmfc_local_ctrl_data_t  **local_ptr)

Description: Get mapped local pointer.

Input:  void                *Handle    (Handle pointer)
Output: ccurpmfc_local_ctrl_data_t  **local_ptr (local struct ptr)
        -- structure in ccurpmfc_user.h
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN              (device not open)
        # CCURPMFC_LIB_INVALID_ARG          (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION      (local region not present)
*****/

```

2.2.156 ccurPMFC_Get_Open_File_Descriptor()

When the library *ccurPMFC_Open()* call is successfully invoked, the board is opened using the system call *open(2)*. The file descriptor associated with this board is returned to the user with this call. This call allows advanced users to bypass the library and communicate directly with the driver with calls like *read(2)*, *ioctl(2)*, etc. Normally, this is not recommended as internal checking and locking is bypassed and the library calls can no longer maintain integrity of the functions. This is only provided for advanced users who want more control and are aware of the implications.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Open_File_Descriptor (void *Handle,
                                   int *fd)

Description: Get Open File Descriptor

Input:  void                *Handle    (Handle pointer)
Output: int                *fd        (open file descriptor)
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN              (device not open)
        # CCURPMFC_LIB_INVALID_ARG          (invalid argument)
*****/

```


2.2.157 ccurPMFC_Get_Physical_Memory()

This call returns to the user the physical memory pointer and size that was previously allocated by the *ccurPMFC_Mmap_Physical_Memory()* call. The physical memory is allocated by the user when they wish to perform their own DMA and bypass the API. Once again, this call is only useful for advanced users.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_Get_Physical_Memory (void                *Handle,
                                ccurpmfc_user_phys_mem_t *phys_mem)

Description: Get previously mmaped() physical memory address and size

Input:   void                *Handle                (Handle pointer)
         ccurpmfc_user_phys_mem_t *phys_mem        (mem struct pointer)
         void                *mmaped_user_mem_ptr   (mmaped user virtual
                                                memory)

Output:  ccurpmfc_user_phys_mem_t *phys_mem        (mem struct pointer)
         uint                user_pid
         void                *phys_mem_ptr
         void                *driver_virt_mem_ptr
         void                *mmaped_user_mem_ptr
         uint                phys_mem_size
         uint                phys_mem_size_freed
         uint                entry_num_in_tran_table
         uint                num_of_entries_used

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR                (successful)
         # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN                (device not open)
         # CCURPMFC_LIB_INVALID_ARG            (invalid argument)
         # CCURPMFC_LIB_IOCTL_FAILED           (driver ioctl call failed)
*****/
```

2.2.158 ccurPMFC_Get_RunCount_UserProcess()

This call returns to the user a count of the number of times the User Process has entered. (*This is an experimental API for debugging and testing.*)

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_Get_RunCount_UserProcess(void                *UFuncHandle,
                                     unsigned int long long *RunCount)

Description: Get run count in user process

Input:   void                *UFuncHandle (UF Handle pointer)
Output:  unsigned int long long *RunCount (pointer to run count)

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR                (successful)
         # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
*****/
```

2.2.159 ccurPMFC_Get_TestBus_Control()

This call is provided for internal use in testing the hardware.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_Get_TestBus_Control (void                *Handle,
                                _ccurpmfc_testbus_control_t *test_control)

Description: Return the value of the Test Bus control information
```

```

Input:  void                *Handle          (handle pointer)
Output: _ccurpmfc_testbus_control_t
        *test_control (pointer to control select)
        # CCURPMFC_TBUS_CONTROL_OPEN
        # CCURPMFC_TBUS_CONTROL_CAL_BUS
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region error)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
*****/

```

2.2.160 ccurPMFC_Get_Value()

This call allows the user to read the board registers. The actual data returned will depend on the command register information that is requested. Refer to the hardware manual for more information on what is being returned. Most commands return a pointer to an unsigned integer.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Get_Value (void                *Handle,
                   CCURPMFC_CONTROL    cmd,
                   void                 *value)

Description: Return the value of the specified board register.

Input:  void                *Handle          (Handle pointer)
        CCURPMFC_CONTROL    cmd             (register definition)
        -- structure in ccurpmfc_lib.h
Output: void                *value;         (pointer to value)
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN         (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
*****/

```

2.2.161 ccurPMFC_Hex_To_Fraction()

This call converts a hexadecimal value to a fractional decimal.

```

/*****
double
ccurPMFC_Hex_To_Fraction (uint value)

Description: Convert Hexadecimal to Fractional Decimal

Input:  uint    value          (hexadecimal to convert)
Output: none
Return: double  Fraction       (converted fractional value)
*****/

```

2.2.162 ccurPMFC_Identify_Board()

This call is useful in identifying a physical board via software control. It causes the front LED to either flash or stay steady.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Identify_Board (void                *Handle,
                        _ccurpmfc_identify_t Identify)

```

Description: Identify the board by setting the front LED

```
Input:   void                *Handle                (Handle pointer)
         _ccurpmfc_identify_t Identify            (Identify board settings)
         # CCURPMFC_IDENTIFY_OFF
         # CCURPMFC_IDENTIFY_ON
         # Number of seconds to blink
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR                (successful)
         # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
         # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
         # CCURPMFC_LIB_NOT_OPEN              (device not open)
         # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
*****/
```

2.2.163 ccurPMFC_Initialize_Board()

This call resets the board to a default initial state. This call is currently identical to the *ccurPMFC_Reset_Board()* call.

```
/*
_ccurpmfc_lib_error_number_t
ccurPMFC_Initialize_Board (void *Handle)

Description: Initialize the board.

Input:   void                *Handle                (Handle pointer)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR                (successful)
         # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN              (device not open)
         # CCURPMFC_LIB_IOCTL_FAILED          (driver ioctl call failed)
         # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
*****/
```

2.2.164 ccurPMFC_IpCore_COS_Activate()

This call is the first call to use after the system is powered up to enable the IpCore COS module. This call can also be used to de-activate the module and get the current state of the module.

```
/*
_ccurpmfc_lib_error_number_t
ccurPMFC_IpCore_COS_Activate (void                *Handle,
                              _ccurpmfc_ipcore_cos_ip_enable_t activate,
                              _ccurpmfc_ipcore_cos_status_disabled_t
                              *current_state)

Description: Activate/DeActivate IP Core COS module

Input:   void                *Handle (Handle pointer)
         _ccurpmfc_ipcore_cos_ip_enable_t activate (activate/deactivate)
         # CCURPMFC_IPCORE_COS_IP_ENABLE
         # CCURPMFC_IPCORE_COS_IP_DISABLE
         # CCURPMFC_IPCODE_COS_IP_DO_NOT_CHANGE
Output:  _ccurpmfc_ipcore_cos_status_disabled_t *current_state
                                                (active/deactive)
         # CCURPMFC_IPCORE_COS_STATUS_IP_ENABLED
         # CCURPMFC_IPCORE_COS_STATUS_IP_DISABLED
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR                (successful)
*****/
```

```

# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (device not open)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
# CCURPMFC_LIB_NO_RESOURCE (COS ip core not present)
*****/

```

2.2.165 ccurPMFC_IpCore_COS_Configure()

The purpose of this call is to configure the Ip Core COS module. If the core is not active, it will activate it. User can decide to immediately start capture at the end of the configuration with the StartStop option. The test mode is simply provided for debugging the hardware and software. Users need to specify at least one channel to detect a change of state, otherwise the call will fail.

A point to note is that when this call is issued, the sampling timer is restarted.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_IpCore_COS_Configure (void *Handle,
                               ccurpmfc_ipcore_cos_configure_t *config)

Description: Configure IP Core Change-of-State

Input: void *Handle (Handle pointer)
Output: ccurpmfc_ipcore_cos_configure_t *config (pointer to config Struct)
        u_int32_t StartStop
        # CCURPMFC_IPCORE_COS_STOP_CAPTURE
        # CCURPMFC_IPCORE_COS_START_CAPTURE
        u_int32_t OperationalMode
        # CCURPMFC_IPCORE_COS_ENABLE_NORMAL_MODE
        # CCURPMFC_IPCORE_COS_ENABLE_TEST_MODE
        u_int32_t TestModePattern
        # CCURPMFC_IPCORE_COS_TEST_PATTERN_ALTERNATING
        # CCURPMFC_IPCORE_COS_TEST_PATTERN_INCREMENT
        u_iny32_t TestModeDivider
        # CCURPMFC_IPCORE_COS_TEST_DIVIDER_1
        # CCURPMFC_IPCORE_COS_TEST_DIVIDER_2
        # CCURPMFC_IPCORE_COS_TEST_DIVIDER_4
        # CCURPMFC_IPCORE_COS_TEST_DIVIDER_8
        # CCURPMFC_IPCORE_COS_TEST_DIVIDER_16
        # CCURPMFC_IPCORE_COS_TEST_DIVIDER_32
        # CCURPMFC_IPCORE_COS_TEST_DIVIDER_64
        # CCURPMFC_IPCORE_COS_TEST_DIVIDER_128
        u_int32_t ChannelMask_31_00
        u_int32_t ChannelMask_63_32

Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_NO_RESOURCE (COS Ip core not present)
*****/

```

2.2.166 ccurPMFC_IpCore_COS_Decode_Timestamp()

This is a useful call that is available to the user to decode the raw timestamp of the change-of-state that is supplied to the call.

```

/*****
void
ccurPMFC_IpCore_COS_Decode_Timestamp (uint timestamp_31_00,

```

```

                                uint          timestamp_63_32,
                                _ccurpmfc_ipcore_cos_decode_timestamp_t *decode_timestamp)

Description: IP Core Decode Timestamp

Input:   uint          timestamp_31_00
         uint          timestamp_63_32
Output:  _ccurpmfc_ipcore_cos_decode_timestamp_t *decode_timestamp
         (pointer to timestamp Struct)

         uint    Day
         uint    Hours
         uint    Minutes
         uint    Seconds
         uint    MilliSeconds
         uint    MicroSeconds

Return:  none
*****/

```

2.2.167 ccurPMFC_IpCore_COS_Get_Info()

This is a useful call to display the current state of the COS Ip Core. Users can use this call prior to making changes to using the COS configuration call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_IpCore_COS_Get_Info (void          *Handle,
                              ccurpmfc_ipcore_cos_info_t *info)

Description: Get Information of IP Core Change-of-State

Input:   void          *Handle (Handle pointer)
Output:  ccurpmfc_ipcore_cos_info_t *info (pointer to info Struct)

         u_int32_t      StartStop
         # CCURPMFC_IPCORE_COS_STOP_CAPTURE
         # CCURPMFC_IPCORE_COS_START_CAPTURE
         u_int32_t      OperationalMode
         # CCURPMFC_IPCORE_COS_ENABLE_NORMAL_MODE
         # CCURPMFC_IPCORE_COS_ENABLE_TEST_MODE
         u_int32_t      TestModePattern
         # CCURPMFC_IPCORE_COS_TEST_PATTERN_ALTERNATING
         # CCURPMFC_IPCORE_COS_TEST_PATTERN_INCREMENT
         u_iny32_t      TestModeDivider
         # CCURPMFC_IPCORE_COS_TEST_DIVIDER_1
         # CCURPMFC_IPCORE_COS_TEST_DIVIDER_2
         # CCURPMFC_IPCORE_COS_TEST_DIVIDER_4
         # CCURPMFC_IPCORE_COS_TEST_DIVIDER_8
         # CCURPMFC_IPCORE_COS_TEST_DIVIDER_16
         # CCURPMFC_IPCORE_COS_TEST_DIVIDER_32
         # CCURPMFC_IPCORE_COS_TEST_DIVIDER_64
         # CCURPMFC_IPCORE_COS_TEST_DIVIDER_128
         u_int32_t      IpEnable
         # CCURPMFC_IPCORE_COS_IP_DISABLE
         # CCURPMFC_IPCORE_COS_IP_ENABLE
         u_int32_t      ChannelMask_31_00
         u_int32_t      ChannelMask_63_32
         u_int32_t      FifoNotFull
         # CCURPMFC_IPCORE_COS_STATUS_FIFO_FULL
         # CCURPMFC_IPCORE_COS_STATUS_FIFO_NOT_FULL
         u_int32_t      OverflowDetected
         # CCURPMFC_IPCORE_COS_STATUS_FIFO_NO_OVERFLOW
         # CCURPMFC_IPCORE_COS_STATUS_FIFO_OVERFLOW
         u_int32_t      IpNotEnabled
         # CCURPMFC_IPCORE_COS_STATUS_IP_ENABLED

```

```

        # CCURPMFC_IPCORE_COS_STATUS_IP_DISABLED
        u_int32_t          FifoCount
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_INVALID_ARG            (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION        (local region not present)
        # CCURPMFC_LIB_NO_RESOURCE            (COS Ip core not present)
*****/

```

2.2.168 ccurPMFC_IpCore_COS_Read()

This call reads the COS FIFO and returns any raw change-of-state elements that have been detected by the firmware. The maximum size of the FIFO is *CCURPMFC_IPCORE_COS_MAX_READ_ELEMENTS* elements. The call requires as input the number of samples to read. This can be any number between 1 and *CCURPMFC_IPCORE_COS_MAX_READ_ELEMENTS*. Additionally, the user needs to select the mode of transfer, i.e. DMA or PIO. If DMA mode is selected, the user has the option to select the DMA engine *CCURPMFC_DMA0* or *CCURPMFC_DMA1*. An additional option to this call is to decode any raw change-of-state elements detected by setting the *timestamp* option to *CCURPMFC_TRUE*.

The call returns the number of elements that it read along with the raw and decoded information. If an overflow condition occurs (i.e. the FIFO gets full and the firmware is unable to add another change of state detected) all available elements are returned up to the user requested count and the overflow condition is cleared. Overflow can occur if the rate of change is state detection is very high and the application is unable to read the FIFO before turning around to collect more data. In that case, the application needs to speed up the process of capturing the data or reducing the rate of change of state.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_IpCore_COS_Read (void          *Handle,
                               ccurpmfc_ipcore_cos_data_t *CosDataPtr)

Description: Get Information of IP Core Change-of-State

Input:  void          *Handle      (Handle pointer)
        ccurpmfc_ipcore_cos_data_t *CosDataPtr (pointer to data struct)
        ushort num_elements      (number of elements to read)
        ushort decode_timestamp
        # CCURPMFC_FALSE
        # CCURPMFC_TRUE
        ushort transfer_mode
        # CCURPMFC_LIBRARY_PIO_MODE
        # CCURPMFC_LIBRARY_DMA_MODE
        ushort dma_engine_number
        # CCURPMFC_DMA0
        # CCURPMFC_DMA1

Output: ccurpmfc_ipcore_cos_data_t *CosDataPtr (pointer to data struct)
        ushort num_elements_returned (number of elements returned)
        ushort overflow_detected      (indicate if overflow occurred)
        # CCURPMFC_IPCORE_COS_STATUS_FIFO_NO_OVERFLOW
        # CCURPMFC_IPCORE_COS_STATUS_FIFO_OVERFLOW
        _ccurpmfc_ipcore_cos_data_t
        element[CCURPMFC_IPCORE_COS_MAX_READ_ELEMENTS]
        uint   timestamp_31_00
        uint   timestamp_63_32
        uint   channel_mask_31_00
        uint   channel_mask_63_32
        _ccurpmfc_ipcore_cos_decode_timestamp_t
        timestamp[CCURPMFC_IPCORE_COS_MAX_READ_ELEMENTS]
        uint   Days
        uint   Hours

```

```

        uint    Minutes
        uint    Second
        uint    MicroSeconds
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION          (local region not present)
        # CCURPMFC_LIB_NO_RESOURCE             (COS Ip core not present)
        # CCURPMFC_LIB_IPCORE_COS_NOT_ACTIVE   (COS Ip core not active)
*****/

```

2.2.169 ccurPMFC_IpCore_COS_Start_Stop()

This call can be used to control the starting and stopping of the change-of-state capture. When the capture is started, the user can select to restart the timer by setting the *ResetTimer* option to *CCURPMFC_TRUE*.

```

/*****
 _ccurpmfc_lib_error_number_t
ccurPMFC_IpCore_COS_Start_Stop (void                *Handle,
                               _ccurpmfc_ipcore_cos_start_capture_t StartStop,
                               uint                    ResetTimer)

Description: Start/Stop IP Core COS capture

Input:  void                *Handle (Handle pointer)
        _ccurpmfc_ipcore_cos_start_capture_t StartStop (start/stop COS
        capture)
        # CCURPMFC_IPCORE_COS_STOP_CAPTURE
        # CCURPMFC_IPCORE_COS_START_CAPTURE
        uint                    ResetTimer (clear timer)
        # CCURPMFC_TRUE
        # CCURPMFC_FALSE

Output: None
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION          (local region not present)
        # CCURPMFC_LIB_NO_RESOURCE             (COS Ip core not present)
        # CCURPMFC_LIB_IPCORE_COS_NOT_ACTIVE   (COS Ip core not active)
*****/

```

2.2.170 ccurPMFC_IpCore_Get_Info()

This call returns information of all the IP Core modules available. The COS core will return a *CCURPMFC_IPCODE_CHANGE_OF_STATE* code in *IpCoreCode*. Additional information about the core is also returned.

This call also returns to the user a memory mapped pointer address that the user can use to directly access the IP Core and bypass the driver and API. This type of access to the hardware should only be performed by Advanced users who are extremely familiar with both the hardware and internals of the core, otherwise, the system operation could be compromised.

```

/*****
 _ccurpmfc_lib_error_number_t
ccurPMFC_IpCore_Get_Info (void                *Handle,
                          ccurpmfc_ipcore_info_t *ip_info)

Description: Get IP Core Information

```

```

Input:  void                                     *Handle (Handle pointer)
Output: ccurpmfc_ipcore_info_t                 *ip_info (pointer to Ip Core Struct)
        u_int32_t                             NumberAdvancedIPCores;
        ccurpmfc_ipcore_info_t IpInfo[CCURPMFC_MAX_IO_CORES]
        _ccurpmfc_ipcore_t IpCore;
        u_int32_t IpCoreCode
        # CCURPMFC_IPCODE_ENGINE_IP
        # CCURPMFC_IPCODE_INJ_IGN_PULSE_CAPTURE
        # CCURPMFC_IPCODE_PWM_INPUT
        # CCURPMFC_IPCODE_PWM_OUTPUT
        # CCURPMFC_IPCODE_TOOTH_WHEEL_GENERATOR
        # CCURPMFC_IPCODE_CHANGE_OF_STATE
        # CCURPMFC_IPCODE_SENT_RECEIVER
        # CCURPMFC_IPCODE_SENT_TRANSMITTER
        # CCURPMFC_IPCODE_ANGULAR_ENCODER
        # CCURPMFC_IPCODE_ANGULAR_DECODER
        # CCURPMFC_IPCODE_KNOCK_SENSOR
        # CCURPMFC_IPCODE_ANALOG_THRESHOLD
        # CCURPMFC_IPCODE_INVERTER
        # CCURPMFC_IPCODE_MOTOR
        # CCURPMFC_IPCODE_21
        # CCURPMFC_IPCODE_22
        # CCURPMFC_IPCODE_23
        # CCURPMFC_IPCODE_24
        # CCURPMFC_IPCODE_25
        # CCURPMFC_IPCODE_26
        # CCURPMFC_IPCODE_27
        # CCURPMFC_IPCODE_28
        # CCURPMFC_IPCODE_29
        # CCURPMFC_IPCODE_30
        union {
            u_int32_t IpCoreRevision;
            ccurpmfc_ipcore_revision_t IpCRev
        }
        u_int32_t IpCoreOffset
        u_int32_t IpCoreInformation
        void *IpCoreMappedPtr
        char IpCoreName[CCURPMFC_IPCORE_NAME_SIZE]
        char IpCoreDescription[CCURPMFC_IPCORE_DESC_SIZE]
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
*****/

```

2.2.171 ccurPMFC_IpCore_Get_Mapped_Ptr()

This call returns to the user a memory mapped pointer address that the user can use to directly access the IP Core and bypass the driver and API. This type of access to the hardware should only be performed by Advanced users who are extremely familiar with both the hardware and internals of the core, otherwise, the system operation could be compromised.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_IpCore_Get_Mapped_Ptr (void *Handle,
                               u_int32_t IpCoreCode,
                               void **ipcore_ptr)

```

Description: Get mapped requested IP Core pointer.


```

Input:  void                *Handle      (Handle pointer)
        u_int32_t          IpCoreCode
        # CCURPMFC_IPCODE_ENGINE_IP
        # CCURPMFC_IPCODE_INJ_IGN_PULSE_CAPTURE
        # CCURPMFC_IPCODE_PWM_INPUT
        # CCURPMFC_IPCODE_PWM_OUTPUT
        # CCURPMFC_IPCODE_TOOTH_WHEEL_GENERATOR
        # CCURPMFC_IPCODE_CHANGE_OF_STATE
        # CCURPMFC_IPCODE_SENT_RECEIVER
        # CCURPMFC_IPCODE_SENT_TRANSMITTER
        # CCURPMFC_IPCODE_ANGULAR_ENCODER
        # CCURPMFC_IPCODE_ANGULAR_DECODER
        # CCURPMFC_IPCODE_KNOCK_SENSOR
        # CCURPMFC_IPCODE_ANALOG_THRESHOLD
        # CCURPMFC_IPCODE_INVERTER
        # CCURPMFC_IPCODE_MOTOR
        # CCURPMFC_IPCODE_21
        # CCURPMFC_IPCODE_22
        # CCURPMFC_IPCODE_23
        # CCURPMFC_IPCODE_24
        # CCURPMFC_IPCODE_25
        # CCURPMFC_IPCODE_26
        # CCURPMFC_IPCODE_27
        # CCURPMFC_IPCODE_28
        # CCURPMFC_IPCODE_29
        # CCURPMFC_IPCODE_30

Output: void                **ipcore_ptr (ipcore ptr)
        -- structure in ccurpmfc_user.h

Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE             (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN              (device not open)
        # CCURPMFC_LIB_INVALID_ARG           (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION       (local region not present)
        # CCURPMFC_LIB_NO_RESOURCE           (Ip core not present)
*****/

```

2.2.172 ccurPMFC_MMap_Physical_Memory()

This call is provided for advanced users to create a physical memory of specified size that can be used for DMA. The allocated DMA memory is rounded to a page size. If a physical memory is not available, this call will fail, at which point the user will need to issue the *ccurPMFC_Munmap_Physical_Memory()* API call to remove the previously allocated physical memory.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_MMap_Physical_Memory (void                *Handle,
                               int                  size,
                               ccurpmfc_user_phys_mem_t *phys_mem)

```

Description: Allocate a physical DMA memory for size bytes.

```

Input:  void                *Handle      (Handle pointer)
        int                size         (size in bytes)
Output: ccurpmfc_user_phys_mem_t *phys_mem (mem struct pointer)
        uint               user_pid
        void               *phys_mem_ptr
        void               *driver_virt_mem_ptr
        void               *mmaped_user_mem_ptr
        uint               phys_mem_size
        uint               phys_mem_size_freed
        uint               entry_num_in_tran_table
        uint               num_of_entries_used

```

```

Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_MMAP_SELECT_FAILED (mmap selection failed)
        # CCURPMFC_LIB_MMAP_FAILED       (mmap failed)
        # CCURPMFC_LIB_NO_SPACE_IN_TABLE (no space in phys memory table)
*****/

```

2.2.173 ccurPMFC_MsgDma_Configure_Descriptor()

This call assists the user in setting up modular scatter-gather DMA descriptors. It allows the user to specify a read and write address offset along with length of transfer. Additionally, the call also provides the option to attach to other previously created descriptor blocks for scatter-gather operation. To perform scatter-gather DMA operation, the user creates a chain of descriptors, each having its own read/write/length information along with a start and end of the chain. The DMA operation is started from the first descriptor block in the chain and sequentially processes the descriptor blocks until the last descriptor block in the chain is processed.

To distinguish between descriptors, they are labeled with descriptor ID's. They range from ID 1 to 31. Users can supply a valid specific ID to this call or let the call itself find a free descriptor ID available. It is entirely left up to the user to determine how to manage the various descriptors and their relative linkages.

If the user wishes to have a previously created descriptor to point to a newly created descriptor, they can supply the previously created descriptor ID to the *AttachToDescriptorID* argument in the newly created descriptor. The newly created descriptor will not point to any descriptor and will always be the last descriptor in the chain.

DMA transfers can occur from either of the following:

1. Physical PCIe memory to Physical PCIe memory
2. Physical PCIe memory to Avalon Memory
3. Avalon Memory to Physical PCIe memory
4. Avalon Memory to Avalon Memory

There are certain restrictions and limitations to this scatter-gather operation:

1. Scatter-gather DMA is only supported in certain FPGA cards
2. Reads from Avalon memory below DiagRam location are not allowed.
3. Invalid memory address supplied could result in the scatter-gather IP to lock up and the only way to recover will be to reload the driver.
4. Read and write addresses must be at a minimum full-word aligned and for maximum performance, it is recommended to be quad-word aligned.
5. Lengths are in bytes and must be at a minimum a multiple of a full-word and for maximum performance, it is recommended to be quad-word multiple.
6. You cannot cause a chain of descriptors to loop on itself.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_MsgDma_Configure_Descriptor (void          *Handle,
                                       _ccurpmfc_msgdma_descriptors_id_t *DescriptorID,
                                       ccurpmfc_msgdma_descriptor_t      *Descriptor,
                                       _ccurpmfc_msgdma_descriptors_id_t AttachToDescriptorID)

Description: Configure Modular Scatter-Gather DMA descriptor

Input:  void          *Handle (Handle pointer)
        _ccurpmfc_msgdma_descriptors_id_t *DescriptorID
                                             (Set to NULL or valid ID)
        # 0                               (let function find a free ID)
        # CCURPMFC_MSGDMA_DESCRIPTOR_ID_1 ...

```

```

        CCURPMFC_MSGDMA_DESCRIPTOR_ID_31
ccurpmfc_msgdma_descriptor_t *Descriptor (pointer to descriptor)
    __u64 ReadAddress
    __u64 WriteAddress
    __u32 Length
    _ccurpmfc_msgdma_descriptors_id_t AttachToDescriptorID
        (Attach to descriptor ID)
    # CCURPMFC_MSGDMA_DESCRIPTOR_ID_1 ...
    CCURPMFC_MSGDMA_DESCRIPTOR_ID_31
Output:  _ccurpmfc_msgdma_descriptors_id_t *DescriptorID (returned ID)
    # CCURPMFC_MSGDMA_DESCRIPTOR_ID_1 ...
    CCURPMFC_MSGDMA_DESCRIPTOR_ID_31
Return:  _ccurpmfc_lib_error_number_t
    # CCURPMFC_LIB_NO_ERROR (successful)
    # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
    # CCURPMFC_LIB_NOT_OPEN (device not open)
    # CCURPMFC_LIB_INVALID_ARG (invalid argument)
    # CCURPMFC_LIB_NO_FREE_DESCRIPTOR_AVAILABLE
        (no free descriptors available)
    # CCURPMFC_LIB_MSG_DMA_NOT_SUPPORTED (modular scatter-gather
        DMA not supported)
    # CCURPMFC_LIB_MSG_DMA_READS_NOT_ALLOWED_FOR_SELECTED_ADDRESS
        (MSG DMA Reads not allowed
        for selected address)
*****/

```

2.2.174 ccurPMFC_MsgDma_Configure_Single()

This call performs a similar function to the *ccurPMFC_MsgDma_Configure()* call with the exception that no DMA chaining is performed and only the single descriptor ID-1 is used to perform the DMA operation. The user has the option to supply a valid descriptor block when using the *ccurPMFC_MsgDma_Configure_Single()* API or a *NULL* pointer to the descriptor as an argument when using the *ccurPMFC_Transfer_Data()* API to perform the transfer.

Normally this call needs to be issued once with a *NULL* pointer for the *Descriptor* (i.e. during initialization) prior to using the *ccurPMFC_Transfer_Data()* call with the *LibMode* set to *CCURPMFC_LIBRARY_MSGDMA_MOD*. In this way, the descriptor ID-1 will be set up correctly prior to the transfer.

If instead, the user wishes to perform the DMA operation using the *ccurPMFC_MsgDma_Fire_Single()* call, they need to issue the *ccurPMFC_MsgDma_Configure_Single()* call with a valid descriptor block, otherwise, results will be unpredictable.

```

/*****
    _ccurpmfc_lib_error_number_t
ccurPMFC_MsgDma_Configure_Single (void *Handle,
    ccurpmfc_msgdma_descriptor_t *Descriptor)

```

Description: Configure Single Modular Scatter-Gather DMA descriptor

```

Input:  void *Handle (Handle pointer)
    ccurpmfc_msgdma_descriptor_t *Descriptor (pointer to descriptor)
    __u64 ReadAddress
    __u64 WriteAddress
    __u32 Length

```

```

Output: none
Return:  _ccurpmfc_lib_error_number_t
    # CCURPMFC_LIB_NO_ERROR (successful)
    # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
    # CCURPMFC_LIB_NOT_OPEN (device not open)
    # CCURPMFC_LIB_INVALID_ARG (invalid argument)
    # CCURPMFC_LIB_DMA_BUSY (DMA Busy, cannot be reset)

```

```

# CCURPMFC_LIB_MSG_DMA_NOT_SUPPORTED (modular scatter-gather DMA
not supported)
# CCURPMFC_LIB_MSG_DMA_READS_NOT_ALLOWED_FOR_SELECTED_ADDRESS
(MSG DMA Reads not allowed
for selected address)
*****/

```

2.2.175 ccurPMFC_MsgDma_Fire()

This call commences a scatter-gather DMA operation that has been previously configured and setup by the *ccurPMFC_MsgDma_Configure()* and *ccurPMFC_MsgDma_Setup()* call.

The *StartDescriptorID* can be set to either '0' or a valid Descriptor ID. Normally, the user will set the *StartDescriptorID* in the *ccurPMFC_MsgDma_Setup()* API during initialization and set it to '0' in this *ccurPMFC_MsgDma_Fire()* API. In this way, this call will not suffer the overhead of loading the *StartDescriptorID* in the internal prefetcher register when repeatedly calling the *ccurPMFC_MsgDma_Fire()* API. If the user specifies a valid *StartDescriptorID* that is already setup as a scatter-gather chain using the *ccurPMFC_MsgDma_Configure()* call, then this *ccurPMFC_MsgDma_Fire()* API will initiate the DMA starting with the user supplied start descriptor ID.

The *DescriptorIDMask* is a mask of all the valid descriptor ID's specified in the scatter-gather chain that was created earlier with the *ccurPMFC_MsgDma_Configure()* API. If this is incorrectly specified, the DMA operation will be unpredictable. This *ccurPMFC_MsgDma_Fire()* API call uses this mask to set the *ControlWord* for each of the IDs. Specifying this mask reduces the overhead in the call by not searching the scatter-gather chain to set the individual control words.

ControlWord for each descriptor is set based on the *DescriptorIDMask* mask. Normally, the following two flags are set:

- CCURPMFC_MSGD_DESC_CONTROL_GO
- CCURPMFC_MSGD_DESC_CONTROL_OWNED_BY_HW

LastIdForInterrupts is set to 0 if the DMA operation should use polling instead of using interrupts. If interrupts are to be used, the ID of the last descriptor in the DMA chain is to be specified. This is the ID that will be interrupted when the entire chain is completed. Incorrect ID entered will result in unpredictable results. Normally, interrupt handling adds additional overhead and reduces performance, however, it reduces the overhead experienced by the CPU and PCIe bus during polling.

Once the scatter-gather DMA operation commences, it performs DMA operations starting with the *StartDescriptorID* and traversing through the chain sequentially until it reaches the last descriptor ID in the chain, at which point the DMA operation concludes.

```

/*****
_ccurpmfc_lib_error_number_t
_ccurPMFC_MsgDma_Fire (void *Handle,
_ccurpmfc_msgdma_descriptors_id_t StartDescriptorID,
_ccurpmfc_msgdma_descriptors_id_mask_t DescriptorIDMask,
int ControlWord,
_ccurpmfc_msgdma_descriptors_id_t
LastIdForInterrupts)

```

Description: Fire Modular Scatter-Gather DMA descriptor

```

Input: void *Handle (Handle pointer)
_ccurpmfc_msgdma_descriptors_id_t StartDescriptorID (Set to
valid ID)
# 0 (don't set start descriptor ID
in prefetcher)
# CCURPMFC_MSGDMA_DESCRIPTOR_ID_1 ...
CCURPMFC_MSGDMA_DESCRIPTOR_ID_31
_ccurpmfc_msgdma_descriptors_id_mask_t DescriptorIDMask
(descriptor ID mask)

```

```

# CCURPMFC_MSGDMA_DESCRIPTOR_ID_1_MASK ...
CCURPMFC_MSGDMA_DESCRIPTOR_ID_31_MASK
# CCURPMFC_MSGDMA_DESCRIPTOR_ID_ALL_MASK
int ControlWord
# CCURPMFC_MSGD_DESC_CONTROL_GO
# CCURPMFC_MSGD_DESC_CONTROL_OWNED_BY_HW
_ccurpmfc_msgdma_descriptors_id_t LastIdForInterrupts (Set 0 or
Last ID for interrupts)
# 0
# CCURPMFC_MSGDMA_DESCRIPTOR_ID_1 ...
CCURPMFC_MSGDMA_DESCRIPTOR_ID_31
Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_DMA_FAILED (DMA failed)
# CCURPMFC_LIB_DMA_BUSY (DMA busy)
*****/

```

2.2.176 ccurPMFC_MsgDma_Fire_Single()

This call is similar in functionality to the *ccurPMFC_MsgDma_Fire()* call with the exception that it operates on the single descriptor ID-1. It can be used when a single DMA rather than scatter-gather DMA operation needs to be performed. This call can be called once the *ccurPMFC_MsgDma_Config_Single()* call has been issued to set up the read/write address offset and length of transfer. Unless the read/write address offset or length of transfer is changed, the *ccurPMFC_MsgDma_Fire_Single()* call can be made repeatedly to perform the same DMA operation.

```

/*****
_ccurpmfc_lib_error_number_t
_ccurPMFC_MsgDma_Fire_Single (void *Handle,
int UseInterrupts)

Description: Fire Single Modular Scatter-Gather DMA descriptor

Input: void *Handle (Handle pointer)
int UseInterrupts (Use interrupts flag)
# CCURPMFC_TRUE
# CCURPMFC_FALSE

Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_DMA_FAILED (DMA failed)
# CCURPMFC_LIB_DMA_BUSY (DMA busy)
*****/

```

UseInterrupts is a flag that can be set to specify if interrupt handling should be enabled.

2.2.177 ccurPMFC_MsgDma_Free_Descriptor()

This call can be used to free up already used descriptors.

```

/*****
_ccurpmfc_lib_error_number_t
_ccurPMFC_MsgDma_Free_Descriptor (void *Handle,
_ccurpmfc_msgdma_descriptors_id_mask_t DescriptorIDMask)

Description: Free Modular Scatter-Gather DMA descriptor

Input: void *Handle (Handle pointer)
_ccurpmfc_msgdma_descriptors_id_mask_t DescriptorIDMask

```

```

(descriptor ID mask)
# CCURPMFC_MSGDMA_DESCRIPTOR_ID_1_MASK ...
  CCURPMFC_MSGDMA_DESCRIPTOR_ID_31_MASK
# CCURPMFC_MSGDMA_DESCRIPTOR_ID_ALL_MASK
Output: none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
         # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
         # CCURPMFC_LIB_MSG_DMA_NOT_SUPPORTED (modular scatter-gather DMA
                                             not supported)
*****/

```

2.2.178 ccurPMFC_MsgDma_Get_Descriptor()

This call returns information on the selected descriptor.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_MsgDma_Get_Descriptor (void          *Handle,
                                   _ccurpmfc_msgdma_descriptors_id_t DescriptorID,
                                   ccurpmfc_msgdma_descriptor_t *Descriptor,
                                   __u64          *DescriptorAddress)

  Description: Get Modular Scatter-Gather DMA Descriptor

  Input:      void          *Handle (Handle pointer)
              _ccurpmfc_msgdma_descriptors_id_t DescriptorID (descriptor ID)
              # CCURPMFC_MSGDMA_DESCRIPTOR_ID_1 ...
              CCURPMFC_MSGDMA_DESCRIPTOR_ID_31

  Output:     ccurpmfc_msgdma_descriptor_t *Descriptor (pointer to descriptor)
              __u64  ReadAddress
              __u64  WriteAddress
              __u32  Length
              __u32  Control
              __u32  ReadBurstCount
              __u32  WriteBurstCount
              __u32  ReadStride
              __u32  WriteStride
              __u32  ActualBytesTransferred
              __u32  Status
              __u64          *DescriptorAddress (descriptor address)

  Return:     _ccurpmfc_lib_error_number_t
              # CCURPMFC_LIB_NO_ERROR           (successful)
              # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
              # CCURPMFC_LIB_NOT_OPEN          (device not open)
              # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
              # CCURPMFC_LIB_MSG_DMA_NOT_SUPPORTED (modular scatter-gather DMA
                                                    not supported)
*****/

```

Pointer to *DescriptorAddress* can be specified to return its address offset within the configuration space. This argument can be set to *NULL* if address is not required.

2.2.179 ccurPMFC_MsgDma_Get_Dispatcher_CSR()

This call returns useful control and status register information on the dispatcher.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_MsgDma_Get_Dispatcher_CSR (void          *Handle,
                                       ccurpmfc_msgdma_dispatcher_t *Dispatcher)

```

Description: Get Modular Scatter-Gather DMA Dispatcher CSR

```
Input:  void                                *Handle (Handle pointer)
Output: ccurpmfc_msgdma_dispatcher_t      *Dispatcher (pointer to dispatcher)
        __u32 Status
        # CCURPMFC_MSGD_DISP_STATUS_IRQ           :IRQ
        # CCURPMFC_MSGD_DISP_STATUS_STOPPED_ETERM :Stopped on Early
        Termination
        # CCURPMFC_MSGD_DISP_STATUS_STOPPED_ERROR :Stopped on Error
        # CCURPMFC_MSGD_DISP_STATUS_RESETTING    :Resetting
        # CCURPMFC_MSGD_DISP_STATUS_STOPPED      :Stopped
        # CCURPMFC_MSGD_DISP_STATUS_RESP_BUF_FULL :Response Buffer
        Full
        # CCURPMFC_MSGD_DISP_STATUS_RESP_BUF_EMPTY :Response Buffer
        Empty
        # CCURPMFC_MSGD_DISP_STATUS_DESC_BUF_FULL :Descriptor Buffer
        Full
        # CCURPMFC_MSGD_DISP_STATUS_DESC_BUF_EMPTY :Descriptor Buffer
        Empty
        # CCURPMFC_MSGD_DISP_STATUS_BUSY         :Busy
        __u32 Control
        # CCURPMFC_MSGD_DISP_CONTROL_STOP_DESC   :Stop Descriptors
        # CCURPMFC_MSGD_DISP_CONTROL_INT_ENA_MASK :Global Interrupt
        Enable Mask
        # CCURPMFC_MSGD_DISP_CONTROL_STOP_ETERM  :Stop on Early
        Termination
        # CCURPMFC_MSGD_DISP_CONTROL_STOP_ON_ERROR :Stop on Error
        # CCURPMFC_MSGD_DISP_CONTROL_RESET_DISP  :Reset Dispatcher
        # CCURPMFC_MSGD_DISP_CONTROL_STOP_DISP   :Stop Dispatcher
        __u32 ReadFillLevel
        __u32 WriteFillLevel
        __u32 ResponseFillLevel
        __u32 ReadSequenceNumber
        __u32 WriteSequenceNumber
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                 (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_INVALID_ARG            (invalid argument)
        # CCURPMFC_LIB_MSG_DMA_NOT_SUPPORTED (modular scatter-gather DMA
        not supported)
*****/
```

2.2.180 ccurPMFC_MsgDma_Get_Prefetcher_CSR()

This call returns useful control and status register information on the prefetcher.

```
/*
_ccurpmfc_lib_error_number_t
ccurPMFC_MsgDma_Get_Prefetcher_CSR (void                                *Handle,
                                     ccurpmfc_msgdma_prefetcher_t      *Prefetcher)
```

Description: Get Modular Scatter-Gather DMA Prefetcher CSR

```
Input:  void                                *Handle (Handle pointer)
Output: ccurpmfc_msgdma_prefetcher_t      *Prefetcher (pointer to prefetcher)
        __u32 Status
        # CCURPMFC_MSGD_PREF_STATUS_IRQ           :IRQ Occurred
        __u32 Control
        # CCURPMFC_MSGD_PREF_CONTROL_PARK_MODE    :Park Mode
        # CCURPMFC_MSGD_PREF_CONTROL_INT_ENA_MASK :Global Interrupt
        Enable Mask
```

```

        # CCURPMFC_MSGD_PREF_CONTROL_RESET           :Reset Prefetcher
                                                    Core
        # CCURPMFC_MSGD_PREF_CONTROL_DESC_POLL_EN   :Descriptor Polling
                                                    Enable
        # CCURPMFC_MSGD_PREF_CONTROL_RUN           :Start Descriptor
                                                    fetching operation

        __u64 NextDescriptorPointer
        __u32 DescriptorPollingFrequency
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                     (successful)
        # CCURPMFC_LIB_BAD_HANDLE                   (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                     (device not open)
        # CCURPMFC_LIB_INVALID_ARG                  (invalid argument)
        # CCURPMFC_LIB_MSG_DMA_NOT_SUPPORTED        (modular scatter-gather DMA
                                                    not supported)
*****/

```

2.2.181 ccurPMFC_MsgDma_Release()

This *ccurPMFC_MsgDma_Release()* API call is used to free up the Modular Scatter-Gather DMA resource that has been reserved by the *ccurPMFC_MsgDma_Seize()* API.

```

/*****
    _ccurpmfc_lib_error_number_t    ccurPMFC_MsgDma_Release (void *Handle)

Description: Release MsgDMA operation for others to use

Input:      void                      *Handle (Handle pointer)
Output:     none
Return:     _ccurpmfc_lib_error_number_t
            # CCURPMFC_LIB_NO_ERROR         (successful)
            # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURPMFC_LIB_MSGDMA_NOT_SUPPORTED (modular scatter-gather DMA
                                                    not supported)
            # CCURPMFC_LIB_NOT_OWNER_OF_MSGDMA (not owner of modular
                                                    scatter-gather)
*****/

```

2.2.182 ccurPMFC_MsgDma_Seize()

Modular Scatter-Gather DMA is a two part operation. The first part is to configure the Scatter-Gather DMA and the second part is to execute the DMA. Various MsgDma API calls have been provided for this. Since this two part operation is not autonomous, it is necessary for the user of these calls to prevent other applications from configuring and using the MsgDMA resources while it is being actively used by another application. For this reason, the *ccurPMFC_MsgDma_Seize()* and *ccurPMFC_MsgDma_Release()* API calls have been introduced to assist the user in preventing other applications from accessing the Scatter-Gather DMA resource while it is reserved. Basically, before any MsgDma API call is issued that could modify the setting and execution of the MsgDma operation, the user needs to issue the *ccurPMFC_MsgDma_Seize()* API call once. In this way, on one else will have access to the MsgDma resource until the application has issued the *ccurPMFC_MsgDma_Release()* API call or has terminated.

```

/*****
    _ccurpmfc_lib_error_number_t    ccurPMFC_MsgDma_Seize (void *Handle)

Description: Seize MsgDMA operation for private to use and become owner

Input:      void                      *Handle (Handle pointer)
Output:     none
Return:     _ccurpmfc_lib_error_number_t
            # CCURPMFC_LIB_NO_ERROR         (successful)
            # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURPMFC_LIB_NOT_OPEN        (device not open)
*****/

```



```

# CCURPMFC_LIB_MSGDMA_NOT_SUPPORTED (modular scatter-gather DMA
not supported)
# CCURPMFC_LIB_MSGDMA_IN_USE (modular scatter-gather DMA in
use)
*****/

```

2.2.183 ccurPMFC_MsgDma_Setup()

This call is used in conjunction with the *ccurPMFC_MsgDma_Configure()* and *ccurPMFC_MsgDma_Fire()* calls. This call is made after all the descriptors are first configured with the help of the *ccurPMFC_MsgDma_Configure()* call. The purpose of this call is to specify the first descriptor in the chain. Additionally, the user can set the *ForceReset* flag to reset the dispatcher and prefetcher. Optionally, the user can request useful active descriptor information if *ActiveDescriptorsInfo* argument is specified (*i.e not NULL*). In addition to returning useful active descriptor information, the descriptor chain and prefetcher settings are also validated for proper configuration.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_MsgDma_Setup (void *Handle,
_ccurpmfc_msgdma_descriptors_id_t StartDescriptorID,
int ForceReset,
_ccurpmfc_msgdma_active_descriptors_info_t
*ActiveDescriptorsInfo)

```

Description: Setup MsgDMA Dispatcher and Prefetcher

Input: void *Handle (Handle pointer)
_ccurpmfc_msgdma_descriptors_id_t *StartDescriptorID (Set to valid ID)

CCURPMFC_MSGDMA_DESCRIPTOR_ID_1 ...
CCURPMFC_MSGDMA_DESCRIPTOR_ID_31
int ForceReset
Output: ccurpmfc_msgdma_active_descriptors_info_t *ActiveDescriptorsInfo;
_ccurpmfc_msgdma_descriptors_id_t ID
CCURPMFC_MSGDMA_DESCRIPTOR_ID_1 ...
CCURPMFC_MSGDMA_DESCRIPTOR_ID_31
_ccurpmfc_msgdma_descriptors_id_mask_t Mask
CCURPMFC_MSGDMA_DESCRIPTOR_ID_1_MASK ...
CCURPMFC_MSGDMA_DESCRIPTOR_ID_31_MASK
CCURPMFC_MSGDMA_DESCRIPTOR_ID_ALL_MASK
_u32 NumberOfDescriptors
_u32 TotalBytes

Return: _ccurpmfc_lib_error_number_t
CCURPMFC_LIB_NO_ERROR (successful)
CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
CCURPMFC_LIB_NOT_OPEN (device not open)
CCURPMFC_LIB_INVALID_ARG (invalid argument)
CCURPMFC_LIB_DMA_BUSY (DMA Busy, cannot be reset)
CCURPMFC_LIB_ERROR_IN_DESCRIPTOR_LIST (invalid descriptor list)
CCURPMFC_LIB_MSG_DMA_NOT_SUPPORTED (modular scatter-gather DMA not supported)

```

*****/

```

2.2.184 ccurPMFC_Munmap_Physical_Memory()

This call simply removes a physical memory that was previously allocated by the *ccurPMFC_MMap_Physical_Memory()* API call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Munmap_Physical_Memory (void *Handle,

```

```
void *mmaped_user_mem_ptr)
```

Description: Unmap a previously mapped physical DMA memory.

```
Input: void *Handle (Handle pointer)
Output: void *mmaped_user_mem_ptr (virtual memory pointer)
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN (device not open)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_MUNMAP_FAILED (failed to un-map memory)
        # CCURPMFC_LIB_NOT_MAPPED (memory not mapped)
```

```
*****/
```

2.2.185 ccurPMFC_NanoDelay()

This call goes into a tight loop spinning for the requested nano seconds specified by the user.

```
/*****
```

```
void
ccurPMFC_NanoDelay (unsigned long long NanoDelay)
```

Description: Delay (loop) for user specified nano-seconds

```
Input: unsigned long long NanoDelay (number of nano-secs to delay)
Output: none
Return: none
```

```
*****/
```

2.2.186 ccurPMFC_Open()

This is the first call that needs to be issued by a user to open a device and access the board through the rest of the API calls. What is returned is a handle to a *void pointer* that is supplied as an argument to the other API calls. The *Board_Number* is a valid board number [0..9] that is associated with a physical card. There must exist a character special file */dev/ccurpmfc<Board_Number>* for the call to be successful. One character special file is created for each board found when the driver is successfully loaded.

The *oflag* is the flag supplied to the *open(2)* system call by this API. It is normally a 0, however the user may use the *O_NONBLOCK* option for *read(2)* calls which will change the default reading in block mode.

In case of error, *errno* is also set for some non-system related errors encountered.

```
/*****
```

```
_ccurpmfc_lib_error_number_t
ccurPMFC_Open (void **My_Handle,
               int Board_Number,
               int oflag)
```

Description: Open a device.

```
Input: void **Handle (Handle pointer to pointer)
        int Board_Number (0-9 board number)
        int oflag (open flags)
Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR (successful)
        # CCURPMFC_LIB_INVALID_ARG (invalid argument)
        # CCURPMFC_LIB_ALREADY_OPEN (device already opened)
        # CCURPMFC_LIB_OPEN_FAILED (device open failed)
        # CCURPMFC_LIB_ALREADY_MAPPED (memory already mmaped)
        # CCURPMFC_LIB_MMAP_SELECT_FAILED (mmap selection failed)
```

```

# CCURPMFC_LIB_MMAP_FAILED (mmap failed)
*****/

```

2.2.187 ccurPMFC_Pause_UserProcess()

This call causes a running User Process to sleep for user specified micro-seconds. (*This is an experimental API for debugging and testing.*)

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Pause_UserProcess(void *UFuncHandle,
                           int usleep)

Description: Pause running user process

Input:   void *UFuncHandle (UF Handle pointer)
         int usleep (micro-seconds sleep)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR (successful)
         # CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
*****/

```

2.2.188 ccurPMFC_Program_All_Output_Clocks()

This is the main call to program all the output clocks with a single call. All existing clock activity is stopped and replaced with the new clocks selection. Though the user can select the Input Clock Frequency with this call, it is expected that they will use the default CCURPMFC_DEFAULT_INPUT_CLOCK_FREQUENCY value.

The input clock can be one of:

```

CCURPMFC_CG_INPUT_CLOCK_SELECT_IN0 → 10MHz TCXO (Temperature Compensated
                                       Oscillator Clock).
CCURPMFC_CG_INPUT_CLOCK_SELECT_IN1 → External Input
CCURPMFC_CG_INPUT_CLOCK_SELECT_IN2 → FPGA Supplied
CCURPMFC_CG_INPUT_CLOCK_SELECT_INXAXB → Not used

```

When using this card, the default clock should be set to *CCURPMFC_CG_INPUT_CLOCK_SELECT_NO* i.e. the 10MHz internal clock.

If the desired output clock frequencies are unable to be computed due to hardware limitation, they may wish to increase the desired tolerance for the particular clock. Note that this tolerance is only applicable to computing a clock value as close to the desired frequency and not a representation of the accuracy of the output clocks.

Additionally, the programming could fail if the number of N-Divider resource gets exhausted due to the user selecting several output clocks with widely different output clocks.

```

/*****
ccurPMFC_Program_All_Output_Clocks()
_ccurpmfc_lib_error_number_t
ccurPMFC_Program_All_Output_Clocks(void *Handle,
                                     double InputClockFrequency,
                                     _ccurpmfc_cg_input_clock_select_register_t InputClockSel,
                                     ccurpmfc_compute_all_output_clocks_t *AllClocks,
                                     int ProgramClocks,
                                     int ActivateClocks)

```

Description: Program All Output Clocks

```

Input:  void                                     *Handle
                                              (Handle pointer)
double  InputClockFrequency
                                              (input clock frequency)
       _ccurpmfc_cg_input_clock_select_register_t InputClockSel
                                              (select input clock)
       # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN0
       # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN1
       # CCURPMFC_CG_INPUT_CLOCK_SELECT_IN2
       # CCURPMFC_CG_INPUT_CLOCK_SELECT_INXAXB
ccurpmfc_compute_all_output_clocks_t      *AllClocks      (pointer to
                                              all Clocks)
ccurpmfc_compute_single_output_clock_t    *Clock           (Pointer to
                                              returned output clock info)
long double                               DesiredFrequency
double                                    DesiredTolerancePPT
int                                         ProgramClocks     (program
                                              clocks)
int                                         ActivateClocks    (1=activate
                                              clocks after program)
Output: ccurpmfc_compute_all_output_clocks_t *AllClocks      (Pointer to
                                              returned output clocks info)
       ccurpmfc_compute_single_output_clock_t *Clock           (Pointer to
                                              returned output clock info)
       _ccurpmfc_clock_generator_output_t  OutputClock
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_0
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_1
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_2
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_3
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_4
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_5
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_6
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_7
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_8
       # CCURPMFC_CLOCK_GENERATOR_OUTPUT_9
double                                     InputClockFrequency
long double                               FrequencyDeviation
int                                         FrequencyFound
long double                               ActualFrequency
double                                     ActualTolerancePPT
__u64                                       Mdiv_Numerator
__u32                                       Mdiv_Denominator
__u64                                       Ndiv_Numerator
__u32                                       Ndiv_Denominator
       _ccurpmfc_cg_outmux_ndiv_select_t   Ndiv_ToUse
       # CCURPMFC_CG_OUTPUT_MUX_NDIV_0
       # CCURPMFC_CG_OUTPUT_MUX_NDIV_1
       # CCURPMFC_CG_OUTPUT_MUX_NDIV_2
       # CCURPMFC_CG_OUTPUT_MUX_NDIV_3
       # CCURPMFC_CG_OUTPUT_MUX_NDIV_4
__u32                                       Rdiv_value
__u32                                       Rdivider
__u32                                       Pdivider
Return: _ccurpmfc_lib_error_number_t
       # CCURPMFC_LIB_NO_ERROR              (successful)
       # CCURPMFC_LIB_BAD_HANDLE           (no/bad handler supplied)
       # CCURPMFC_LIB_NOT_OPEN             (device not open)
       # CCURPMFC_LIB_NO_LOCAL_REGION      (local region error)
       # CCURPMFC_LIB_IO_ERROR             (device not ready)
       # CCURPMFC_LIB_N_DIVIDERS_EXCEEDED  (number of N-Dividers
                                              exceeded)
       # CCURPMFC_LIB_CANNOT_COMPUTE_OUTPUT_FREQ (cannot compute
                                              output freq)

```

```

# CCURPMFC_LIB_INVALID_ARG          (invalid argument)
# CCURPMFC_LIB_CLOCK_GENERATION_FAILED (clock generation
failed)

```

```

/*****/

```

2.2.189 ccurPMFC_Read()

Currently, this call is not supported. It basically calls the *read(2)* system call with the exception that it performs necessary *locking* and returns the *errno* returned from the system call in the pointer to the *error* variable.

For specific information about the data being returned for the various read modes, refer to the *read(2)* system call description the *Driver Direct Access* section.

```

/*****/

```

```

_ccurpmfc_lib_error_number_t
ccurPMFC_Read (void *Handle,
              void *buf,
              int size,
              int *bytes_read,
              int *error)

```

Description: Perform a read operation.

```

Input:  void *Handle          (Handle pointer)
        int size              (size of buffer in bytes)
Output: void *buf             (pointer to buffer)
        int *bytes_read       (bytes read)
        int *error            (returned errno)
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN      (device not open)
        # CCURPMFC_LIB_IO_ERROR      (read failed)

```

```

/*****/

```

2.2.190 ccurPMFC_Reload_Firmware()

The purpose of this call is to power cycle the board which in turn will reload the latest firmware on the board.

```

/*****/

```

```

ccurPMFC_Reload_Firmware()

```

Description: This call power-cycles the board which in turn forces it to reload its firmware. Typically, this is called after a new firmware has been installed in the board. This saves the need to perform a system reboot after a firmware installation.

```

Input:  void *Handle          (Handle pointer)
Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN      (device not open)
        # CCURPMFC_LIB_IOCTL_FAILED  (driver ioctl call failed)

```

```

/*****/

```

2.2.191 ccurPMFC_Remove_Irq()

The purpose of this call is to remove the interrupt handler that was previously set up. The interrupt handler is managed internally by the driver and the library. The user should not issue this call, otherwise reads will time out.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Remove_Irq (void *Handle)

Description: By default, the driver sets up a shared IRQ interrupt handler
            when the device is opened. Now if for any reason, another
            device is sharing the same IRQ as this driver, the interrupt
            handler will also be entered every time the other shared
            device generates an interrupt. There are times that a user,
            for performance reasons may wish to run the board without
            interrupts enabled. In that case, they can issue this ioctl
            to remove the interrupt handling capability from the driver.

Input:      void *Handle                (Handle pointer)
Output:     none
Return:     _ccurpmfc_lib_error_number_t
            # CCURPMFC_LIB_NO_ERROR      (successful)
            # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
            # CCURPMFC_LIB_NOT_OPEN      (device not open)
            # CCURPMFC_LIB_IOCTL_FAILED  (driver ioctl call failed)
*****/

```

2.2.192 ccurPMFC_Reset_Board()

This call resets the board to a known initial default state. This call is currently identical to the *ccurPMFC_Initialize_Board()* call.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Reset_Board (void *Handle)

Description: Reset the board.

Input:      void *Handle                (Handle pointer)
Output:     none
Return:     _ccurpmfc_lib_error_number_t
            # CCURPMFC_LIB_NO_ERROR      (successful)
            # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
            # CCURPMFC_LIB_NOT_OPEN      (device not open)
            # CCURPMFC_LIB_IOCTL_FAILED  (driver ioctl call failed)
            # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
*****/

```

2.2.193 ccurPMFC_Reset_Clock()

This call performs a hardware reset of the clock. All active output clocks are stopped and set to default state.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Reset_Clock (void *Handle,
                    int activate)

Description: Perform Hardware Clock Reset

Input:      void *Handle                (Handle pointer)
            int activate                (1=activate after reset)
Output:     none
Return:     _ccurpmfc_lib_error_number_t
            # CCURPMFC_LIB_NO_ERROR      (successful)
            # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
            # CCURPMFC_LIB_NOT_OPEN      (device not open)
            # CCURPMFC_LIB_IOCTL_FAILED  (driver ioctl call failed)
*****/

```

```

# CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
*****

```

2.2.194 ccurPMFC_Resume_UserProcess()

Use this call to resume an already paused User Process. *(This is an experimental API for debugging and testing).*

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Resume_UserProcess(void *UFuncHandle)

Description: Resume paused running user process

Input:   void          *UFuncHandle          (UF Handle pointer)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR             (successful)
        # CCURPMFC_LIB_BAD_HANDLE          (no/bad handler supplied)
*****

```

2.2.195 ccurPMFC_Return_Board_Info_Description()

Return board information description

```

/*****
char *
ccurPMFC_Return_Board_Info_Description (_ccurpmfc_board_function_t
                                       BoardFunction)

Description: Return Board Information Description

Input:   _ccurpmfc_board_function_t  BoardFunction          (board function)
        # CCURPMFC_BOARD_FUNCTION_MULTIFUNCTION_IO
        # CCURPMFC_BOARD_FUNCTION_ENGINE_CONTROL
        # CCURPMFC_BOARD_FUNCTION_IPCORE_COS
        # CCURPMFC_BOARD_FUNCTION_BASE_LEVEL
        # CCURPMFC_BOARD_FUNCTION_CUSTOM_IPCORE
        # CCURPMFC_BOARD_FUNCTION_UNDEFINED

Output:  none
Return:  char          *BoardFuncDesc          (board function
                                               description)
*****

```

2.2.196 ccurPMFC_SDRAM_Activate()

This call must be the first call to activate the SDRAM. Without activation, all other calls will fail. The user can also use this call to return the current state of the SDRAM without any change.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_SDRAM_Activate (void          *Handle,
                        _ccurpmfc_sdram_all_enable_t  activate,
                        _ccurpmfc_sdram_all_enable_t  *current_state)

Description: Activate/DeActivate SDRAM module

Input:   void          *Handle          (Handle pointer)
        _ccurpmfc_sdram_all_enable_t  activate          (activate/deactivate)
        # CCURPMFC_SDRAM_ALL_DISABLE
        # CCURPMFC_SDRAM_ALL_ENABLE
        # CCURPMFC_SDRAM_ALL_ENABLE_DO_NOT_CHANGE

Output:  _ccurpmfc_sdram_all_enable_t  *current_state  (active/deactive)

```

```

        # CCURPMFC_SDRAM_ALL_DISABLE
        # CCURPMFC_SDRAM_ALL_ENABLE
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION         (local region not present)
        # CCURPMFC_LIB_SDRAM_INITIALIZATION_FAILED (SDRAM init failed)
*****/

```

2.2.197 ccurPMFC_SDRAM_Get_CSR()

This call returns the SDRAM control and status register information.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_SDRAM_Get_CSR (void          *Handle,
                        ccurpmfc_sdr_ t *sdr_csr)

Description: Get SDRAM Control and Status information

Input:  void          *Handle (Handle pointer)
Output: ccurpmfc_sdr_ t      *sdr_csr (pointer to SDRAM csr)
        _ccurpmfc_sdr_ read_auto_increment_t read_auto_increment;
        # CCURPMFC_SDRAM_READ_AUTO_INCREMENT_DISABLE
        # CCURPMFC_SDRAM_READ_AUTO_INCREMENT_ENABLE
        _ccurpmfc_sdr_ write_auto_increment_t write_auto_increment;
        # CCURPMFC_SDRAM_WRITE_AUTO_INCREMENT_DISABLE
        # CCURPMFC_SDRAM_WRITE_AUTO_INCREMENT_ENABLE
        _ccurpmfc_sdr_ read_timeout_t read_timeout;
        # CCURPMFC_SDRAM_READ_TIMEOUT_DID_NOT_OCCUR
        # CCURPMFC_SDRAM_READ_TIMEOUT_OCCURRED
        _ccurpmfc_sdr_ calibration_fail_t calibration_failed;
        # CCURPMFC_SDRAM_CALIBRATION_FAIL_RESET
        # CCURPMFC_SDRAM_CALIBRATION_FAIL_SET
        _ccurpmfc_sdr_ calibration_pass_t calibration_passed;
        # CCURPMFC_SDRAM_CALIBRATION_PASS_RESET
        # CCURPMFC_SDRAM_CALIBRATION_PASS_SET
        _ccurpmfc_sdr_ initialization_done_t initialization_done;
        # CCURPMFC_SDRAM_INITIALIZATION_NOT_COMPLETE
        # CCURPMFC_SDRAM_INITIALIZATION_COMPLETE
Return:  _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR                (successful)
        # CCURPMFC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN                (device not open)
        # CCURPMFC_LIB_INVALID_ARG             (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION         (local region not present)
        # CCURPMFC_LIB_SDRAM_IS_NOT_ACTIVE     (SDRAM is not active)
*****/

```

2.2.198 ccurPMFC_SDRAM_Read()

This call provided the user the ability to read any portion of the SDRAM. Its range is from 1 to 0x10000000 (256Mwords). Offset to this routine is only set if it is 0 or greater. Maximum offset is 0x0FFFFFFF. If offset is negative, then the read commences from the last read location.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_SDRAM_Read (void          *Handle,
                    u_int32_t *Buf,
                    int          Offset,
                    u_int32_t Size,

```



```
u_int32_t *Words_read)
```

Description: Perform a SDRAM read operation.

```
Input:  void                *Handle    (Handle pointer)
        int                Offset     (word offset into SDRAM)
        u_int32_t         Size       (size of buffer in words)
Output: u_int32_t         *Buf       (pointer to buffer)
        u_int32_t         *Words_read (words read)
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_SDRAM_IS_NOT_ACTIVE (SDRAM is not active)
```

```
*****/
```

2.2.199 ccurPMFC_SDRAM_Set_CSR()

This call sets the SDRAM control and status register.

```
/*
_ccurpmfc_lib_error_number_t
ccurPMFC_SDRAM_Set_CSR (void                *Handle,
                       ccurpmfc_sdram_csr_t *sdram_csr)
```

Description: Set SDRAM Control and Status information

```
Input:  void                *Handle    (Handle pointer)
        _ccurpmfc_sdram_read_auto_increment_t read_auto_increment;
        # CCURPMFC_SDRAM_READ_AUTO_INCREMENT_DISABLE
        # CCURPMFC_SDRAM_READ_AUTO_INCREMENT_ENABLE
        # CCURPMFC_SDRAM_READ_AUTO_INCREMENT_DO_NOT_CHANGE
        _ccurpmfc_sdram_write_auto_increment_t write_auto_increment;
        # CCURPMFC_SDRAM_WRITE_AUTO_INCREMENT_DISABLE
        # CCURPMFC_SDRAM_WRITE_AUTO_INCREMENT_ENABLE
        # CCURPMFC_SDRAM_READ_AUTO_INCREMENT_DO_NOT_CHANGE
        _ccurpmfc_sdram_read_timeout_t read_timeout;
        # CCURPMFC_SDRAM_READ_TIMEOUT_DID_NOT_OCCUR
        # CCURPMFC_SDRAM_READ_TIMEOUT_OCCURRED
        # CCURPMFC_SDRAM_READ_TIMEOUT_DO_NOT_CHANGE
        _ccurpmfc_sdram_calibration_fail_t calibration_failed;
        # CCURPMFC_SDRAM_CALIBRATION_FAIL_RESET
        # CCURPMFC_SDRAM_CALIBRATION_FAIL_SET
        # CCURPMFC_SDRAM_CALIBRATION_FAIL_DO_NOT_CHANGE
        _ccurpmfc_sdram_calibration_pass_t calibration_passed;
        # CCURPMFC_SDRAM_CALIBRATION_PASS_RESET
        # CCURPMFC_SDRAM_CALIBRATION_PASS_SET
        # CCURPMFC_SDRAM_CALIBRATION_PASS_DO_NOT_CHANGE
        _ccurpmfc_sdram_initilization_done_t initialization_done;
        # CCURPMFC_SDRAM_INITIALIZATION_NOT_COMPLETE
        # CCURPMFC_SDRAM_INITIALIZATION_COMPLETE
        # CCURPMFC_SDRAM_INITIALIZATION_DO_NOT_CHANGE

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN      (device not open)
        # CCURPMFC_LIB_INVALID_ARG   (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION (local region not present)
        # CCURPMFC_LIB_SDRAM_IS_NOT_ACTIVE (SDRAM is not active)
```

```
*****/
```

2.2.200 ccurPMFC_SDRAM_Write()

This call provided the user the ability to write to any portion of the SDRAM. Its range is from 1 to 0x10000000 (256Mwords). Offset to this routine is only set if it is 0 or greater. Maximum offset is 0x0FFFFFFF. If offset is negative, then the write commences from the last written location.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_SDRAM_Write (void      *Handle,
                      u_int32_t *Buf,
                      int       Offset,
                      u_int32_t Size,
                      u_int32_t *Words_written)

Description: Perform a SDRAM write operation.

Input:  void      *Handle      (Handle pointer)
        u_int32_t *Buf        (pointer to buffer)
        int       Offset      (word offset into SDRAM)
        u_int32_t Size        (size of buffer in words)
Output: u_int32_t *Words_written (words written)
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURPMFC_LIB_SDRAM_IS_NOT_ACTIVE (SDRAM is not active)
*****/
```

2.2.201 ccurPMFC_Set_Board_CSR()

This call is used to set the board control register.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Set_Board_CSR (void      *Handle,
                       ccurpmfc_board_csr_t *bcsr)

Description: Set Board Control and Status information

Input:  void      *Handle      (Handle pointer)
        ccurpmfc_board_csr_t *bcsr (pointer to board csr)
        _ccurpmfc_bcsr_identify_board_t identify_board
        # CCURPMFC_BCSR_IDENTIFY_BOARD_DISABLE
        # CCURPMFC_BCSR_IDENTIFY_BOARD_ENABLE

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN        (device not open)
        # CCURPMFC_LIB_INVALID_ARG     (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION  (local region not present)
*****/
```

2.2.202 ccurPMFC_Set_Calibration_CSR()

This call sets the current calibration control and status register.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Set_Calibration_CSR (void      *Handle,
                              ccurpmfc_calibration_csr_t *CalCSR)

Description: Set Calibration Control and Status Register
```

```

Input:  void                *Handle      (Handle pointer)
        ccurpmfc_calibration_csr_t *CalCSR (pointer to calibration CSR)
        _ccurpmfc_calbus_control_t BusControl (bus control)
        # CCURPMFC_CB_GROUND
        # CCURPMFC_CB_POSITIVE_REFERENCE
        # CCURPMFC_CB_NEGATIVE_REFERENCE
        # CCURPMFC_CB_BUS_OPEN
        # CCURPMFC_CB_2_5V_REFERENCE
        # CCURPMFC_CB_5V_REFERENCE
        # CCURPMFC_CB_DAC_CHANNEL_0
        # CCURPMFC_CB_DAC_CHANNEL_1
        # CCURPMFC_CB_DAC_CHANNEL_2
        # CCURPMFC_CB_DAC_CHANNEL_3
        # CCURPMFC_CB_DAC_CHANNEL_4
        # CCURPMFC_CB_DAC_CHANNEL_5
        # CCURPMFC_CB_DAC_CHANNEL_6
        # CCURPMFC_CB_DAC_CHANNEL_7
        # CCURPMFC_CB_DAC_CHANNEL_8
        # CCURPMFC_CB_DAC_CHANNEL_9
        # CCURPMFC_CB_DAC_CHANNEL_10
        # CCURPMFC_CB_DAC_CHANNEL_11
        # CCURPMFC_CB_DAC_CHANNEL_12
        # CCURPMFC_CB_DAC_CHANNEL_13
        # CCURPMFC_CB_DAC_CHANNEL_14
        # CCURPMFC_CB_DAC_CHANNEL_15

Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR          (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
        # CCURPMFC_LIB_NO_LOCAL_REGION    (local region not present)
*****/

```

2.2.203 ccurPMFC_Set_Interrupt_Status()

This call sets/clears the various interrupts. In the case of DIO COS interrupts, the change-of-status for all the channels in a particular channel group (Group0=Ch00..31, Group1=Ch32..63, Group2=Ch64..95) are cleared in the DIO COS status registers in order to clear the corresponding DIO COS interrupt status.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Set_Interrupt_Status (void                *Handle,
                               ccurpmfc_interrupt_t *intr)

```

Description: Set Interrupt Status

```

Input:  void                *Handle      (handle pointer)
        ccurpmfc_interrupt_t *intr      (pointer to interrupt status)
        _ccurpmfc_intsta_dio_cos_t dio_cos_group2_int
        # CCURPMFC_INT_DIO_COS_NONE
        # CCURPMFC_INT_DIO_COS_RESET
        # CCURPMFC_INT_DIO_COS_DO_NOT_CHANGE
        _ccurpmfc_intsta_dio_cos_t dio_cos_group1_int
        # CCURPMFC_INT_DIO_COS_NONE
        # CCURPMFC_INT_DIO_COS_RESET
        # CCURPMFC_INT_DIO_COS_DO_NOT_CHANGE
        _ccurpmfc_intsta_dio_cos_t dio_cos_group0_int
        # CCURPMFC_INT_DIO_COS_NONE
        # CCURPMFC_INT_DIO_COS_RESET
        # CCURPMFC_INT_DIO_COS_DO_NOT_CHANGE
        _ccurpmfc_intsta_dac_t
        # CCURPMFC_INT_DAC_FIFO_THRESHOLD_NONE
        # CCURPMFC_INT_DAC_FIFO_THRESHOLD_RESET

```

```

        # CCURPMFC_INT_DAC_FIFO_THRESHOLD_DO_NOT_CHANGE
    _ccurpmfc_intsta_adc_t
        # CCURPMFC_INT_ADC_FIFO_THRESHOLD_NONE
        # CCURPMFC_INT_ADC_FIFO_THRESHOLD_RESET
        # CCURPMFC_INT_ADC_FIFO_THRESHOLD_DO_NOT_CHANGE
Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR           (successful)
        # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURPMFC_LIB_NOT_OPEN          (device not open)
        # CCURPMFC_LIB_NO_LOCAL_REGION   (local region error)
        # CCURPMFC_LIB_INVALID_ARG       (invalid argument)

    *****/

```

2.2.204 ccurPMFC_Set_Interrupt_Timeout_Seconds()

This call sets the read *timeout* maintained by the driver. It allows the user to change the default time out from 30 seconds to a user specified value. It is the time that the read call will wait before it times out. The call could time out if the DMA fails to complete. The device should have been opened in the blocking mode (*O_NONBLOCK* not set) for reads to wait for the operation to complete.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Set_Interrupt_Timeout_Seconds (void      *Handle,
                                           int        timeout_secs)

Description: Set Interrupt Timeout Seconds

Input:   void      *Handle      (Handle pointer)
         int        timeout_secs (interrupt tout secs)
Output:  none
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
         # CCURPMFC_LIB_INVALID_ARG       (invalid argument)
    *****/

```

2.2.205 ccurPMFC_Set_TestBus_Control()

This call is provided for internal use in testing the hardware.

```

/*****
    _ccurpmfc_lib_error_number_t
    ccurPMFC_Set_TestBus_Control (void      *Handle,
                                  _ccurpmfc_testbus_control_t test_control)

Description: Set the value of the Test Bus control information

Input:   void      *Handle      (handle pointer)
Output:  _ccurpmfc_testbus_control_t
         test_control (control select)
         # CCURPMFC_TBUS_CONTROL_OPEN
         # CCURPMFC_TBUS_CONTROL_CAL_BUS
Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR           (successful)
         # CCURPMFC_LIB_NO_LOCAL_REGION   (local region error)
         # CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN          (device not open)
    *****/

```

2.2.206 ccurPMFC_Set_Value()

This call allows the advanced user to set the writable board registers. The actual data written will depend on the command register information that is requested. Refer to the hardware manual for more information on what can be written to.

Normally, users should not be changing these registers as it will bypass the API integrity and could result in an unpredictable outcome.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_Set_Value (void          *Handle,
                     CCURPMFC_CONTROL cmd,
                     void          *value)

  Description: Set the value of the specified board register.

  Input:   void          *Handle      (Handle pointer)
           CCURPMFC_CONTROL cmd      (register definition)
           -- structure in ccurpmfc_lib.h
           void          *value      (pointer to value to be set)

  Output:  none

  Return:  _ccurpmfc_lib_error_number_t
           # CCURPMFC_LIB_NO_ERROR      (successful)
           # CCURPMFC_LIB_BAD_HANDLE   (no/bad handler supplied)
           # CCURPMFC_LIB_NOT_OPEN     (device not open)
           # CCURPMFC_LIB_INVALID_ARG  (invalid argument)
*****/
```

2.2.207 ccurPMFC_SPROM_Read()

This is a basic call to read short word entries from the serial prom. The user specifies a word offset within the serial prom and a word count, and the call returns the data read in a pointer to short words.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_SPROM_Read(void          *Handle,
                     ccurpmfc_sprom_rw_t *spr)

  Description: Read Serial Prom for specified number of words

  Input:   void          *Handle      (handle pointer)
           ccurpmfc_sprom_rw_t *spr   (pointer to struct)
           u_short word_offset
           u_short num_words

  Output:  ccurpmfc_sprom_rw_t *spr   (pointer to struct)
           u_short *data_ptr

  Return:  CCURPMFC_LIB_NO_ERROR      (successful)
           CCURPMFC_LIB_NO_LOCAL_REGION (error)
           CCURPMFC_LIB_INVALID_ARG   (invalid argument)
           CCURPMFC_LIB_SERIAL_PROM_BUSY (serial prom busy)
           CCURPMFC_LIB_SERIAL_PROM_FAILURE (serial prom failure)
*****/
```

2.2.208 ccurPMFC_SPROM_Read_Item()

This call is used to read well defined sections in the serial prom. The user supplies the serial prom section that needs to be read and the data is returned in a section specific structure.

```

/*****
  _ccurpmfc_lib_error_number_t
  ccurPMFC_SPROM_Read_Item(void          *Handle,
                            _ccurpmfc_sprom_access_t item,

```

```

                                void                                *item_ptr)

Description: Read Serial Prom for specified item

Input:      void                                *Handle    (handle pointer)
            _ccurpmfc_sprom_access_t item    (select item)
            # CCURPMFC_SPROM_HEADER

Output:     void                                *item_ptr (pointer to item struct)
            *ccurpmfc_sprom_header_t sprom_header
            u_int32_t                                board_serial_number
            u_short                                sprom_revision

Return:     CCURPMFC_LIB_NO_ERROR                (successful)
            CCURPMFC_LIB_NO_LOCAL_REGION        (error)
            CCURPMFC_LIB_INVALID_ARG           (invalid argument)
            CCURPMFC_LIB_SERIAL_PROM_BUSY      (serial prom busy)
            CCURPMFC_LIB_SERIAL_PROM_FAILURE   (serial prom failure)
*****/

```

2.2.209 ccurPMFC_SPROM_Write()

This is a basic call to write short word entries to the serial prom. The user specifies a word offset within the serial prom and a word count, and the call writes the data pointed to by the *spw* pointer, in short words.

Prior to using this call, the user will need to issue the *ccurPMFC_SPROM_Write_Override()* to allow writing to the serial prom.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_SPROM_Write(void                                *Handle,
                    ccurpmfc_sprom_rw_t *spw)

Description: Write data to Serial Prom for specified number of words

Input:      void                                *Handle    (handle pointer)
            ccurpmfc_sprom_rw_t *spw    (pointer to struct)
            u_short word_offset
            u_short num_words
            u_short *data_ptr

Output:     none

Return:     CCURPMFC_LIB_NO_ERROR                (successful)
            CCURPMFC_LIB_NO_LOCAL_REGION        (error)
            CCURPMFC_LIB_INVALID_ARG           (invalid argument)
            CCURPMFC_LIB_SERIAL_PROM_BUSY      (serial prom busy)
            CCURPMFC_LIB_SERIAL_PROM_FAILURE   (serial prom failure)
*****/

```

2.2.210 ccurPMFC_SPROM_Write_Item()

This call is used to write well defined sections in the serial prom. The user supplies the serial prom section that needs to be written and the data points to the section specific structure. This call should normally not be used by the user.

Prior to using this call, the user will need to issue the *ccurPMFC_SPROM_Write_Override()* to allowing writing to the serial prom.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_SPROM_Write_Item(void                                *Handle,
                          _ccurpmfc_sprom_access_t item,
                          void                                *item_ptr)

Description: Write Serial Prom with specified item

```

```

Input:      void          *Handle      (handle pointer)
           _ccurpmfc_sprom_access_t item  (select item)
           # CCURPMFC_SPROM_HEADER
void        *item_ptr (pointer to item struct)
           *ccurpmfc_sprom_header_t sprom_header
           u_int32_t      board_serial_number
           u_short        sprom_revision

Output:     none
Return:     CCURPMFC_LIB_NO_ERROR          (successful)
           CCURPMFC_LIB_NO_LOCAL_REGION   (error)
           CCURPMFC_LIB_INVALID_ARG      (invalid argument)
           CCURPMFC_LIB_SERIAL_PROM_BUSY (serial prom busy)
           CCURPMFC_LIB_SERIAL_PROM_FAILURE (serial prom failure)
*****/

```

2.2.211 ccurPMFC_SPROM_Write_Override()

The serial prom is non-volatile and its information is preserved during a power cycle. It contains useful information and settings that the customer could lose if they were to inadvertently overwrite. For this reason, all calls that write to the serial proms will fail with a write protect error, unless this write protect override API is invoked prior to writing to the serial proms. Once the Write Override is enabled, it will stay in effect until the user closes the device or re-issues this call to disable writes to the serial prom.

The calls that will fail unless the write protect is disabled are:

- ccurPMFC_Write_Serial_Prom()
- ccurPMFC_Write_Serial_Prom_Item()

When *action* is set to *CCURPMFC_TRUE*, the serial prom write protecting is disabled, otherwise, it is enabled.

```

/*****
   _ccurpmfc_lib_error_number_t
   ccurPMFC_SPROM_Write_Override (void *Handle,
                                 int action)

Description: Set Serial Prom Write Override

Input:      void          *Handle (handle pointer)
           int            action; (override action)
           # CCURPMFC_TRUE
           # CCURPMFC_FALSE

Output:     none
Return:     CCURPMFC_LIB_NO_ERROR          (successful)
           CCURPMFC_LIB_BAD_HANDLE        (no/bad handler supplied)
           CCURPMFC_LIB_NOT_OPEN          (device not open)
           CCURPMFC_LIB_INVALID_ARG      (invalid argument)
           CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
*****/

```

2.2.212 ccurPMFC_Transfer_Data()

This is the main call that the user can use to transfer data from physical memory that the user has previously allocated to a region in the local register, and vice-versa. The operation can be performed via DMA or programmed I/O mode. In the case of DMA mode, the user can select whether interrupts are to be used to wait for DMA to complete instead of polling. User can also specify which DMA engine to use during this operation.

If the board supports modular scatter-gather DMA, then the user can specify that instead of the basic DMA engine. In this case, the user needs to first call the *ccurPMFC_MsgDma_Configure_Single()* with the *NULL* argument to setup descriptor ID-1 for scatter-gather DMA operation.

When scatter-gather DMA is selected, the *DmaEngineNo* argument is ignored and the *IoControl* argument must be set to *CCURPMFC_DMA_CONTROL_INCREMENT*.

There are certain limitations to modular scatter-gather feature:

1. Scatter-gather DMA is only supported in certain cards
2. Reads from Avalon memory below *DiagRam* location are not allowed.
3. Invalid memory address supplied could result in the scatter-gather IP to lock up and the only way to recover will be to reload the driver or reboot the system.
4. Read and write addresses must be at a minimum full-word aligned and for maximum performance, it is recommended to be quad-word aligned.
5. Lengths are in bytes and must be at a minimum a multiple of a full-word and for maximum performance, it is recommended to be quad-word multiple.
6. Scatter-gather chaining cannot be performed with this call.

/******

```

_ccurpmfc_lib_error_number_t
ccurPMFC_Transfer_Data(void                *Handle,
                        volatile void      *PciDmaMemory,
                        volatile void      *AvalonMem,
                        uint                TransferSize,
                        _ccurpmfc_direction_t XferDirection,
                        _ccurpmfc_library_rw_mode_t LibMode,
                        ccurpmfc_dma_engine_t DMAEngineNo,
                        ccurpmfc_bool      UseInterrupts,
                        int                 IoControl)

```

Description: Routine to transfer data from PCI memory to Avalon memory or vice-versa

```

Input:  void                *Handle           (Handle pointer)
        volatile void      *PciDmaMemory    (pointer to virtual memory)
        volatile void      *AvalonMem       (pointer to virtual Avalon
        uint                TransferSize     (size of transfer in bytes)
        _ccurpmfc_direction_t XferDirection (direction of transfer)
        # CCURPMFC_AVALON_2_PCIMEM
        # CCURPMFC_PCIMEM_2_AVALON
        _ccurpmfc_library_rw_mode_t LibMode  (Lib transfer mode)
        # CCURPMFC_LIBRARY_PIO_MODE
        # CCURPMFC_LIBRARY_DMA_MODE
        # CCURPMFC_LIBRARY_MSGDMA_MODE
        ccurpmfc_dma_engine_t DMAEngineNo   (select DMA engine)
        # CCURPMFC_DMA0
        # CCURPMFC_DMA1
        # CCURPMFC_NONE
        ccurpmfc_bool      UseInterrupts    (enable interrupts)
        # CCURPMFC_TRUE
        # CCURPMFC_FALSE
        int                 IoControl        (DMA or PIO control flags)
        # CCURPMFC_DMA_CONTROL_RCON        (DMA: read constant)
        # CCURPMFC_DMA_CONTROL_WCON        (DMA: write constant)
        # CCURPMFC_DMA_CONTROL_INCREMENT   (DMA: increment)
        # CCURPMFC_PIO_CONTROL_RCON        (PIO: read constant)
        # CCURPMFC_PIO_CONTROL_WCON        (PIO: write constant)
        # CCURPMFC_PIO_CONTROL_INCREMENT   (PIO: increment)

Output: none
Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR            (no error)
        # CCURPMFC_LIB_BAD_HANDLE          (no/bad handler supplied)

```



```

# CCURPMFC_LIB_NOT_OPEN (library not open)
# CCURPMFC_LIB_IOCTL_FAILED (driver ioctl call failed)
# CCURPMFC_LIB_MSG_DMA_READS_NOT_ALLOWED_FOR_SELECTED_ADDRESS
(MSG DMA Reads not allowed
for selected address)
*****/

```

2.2.213 ccurPMFC_Update_Clock_Generator_Divider()

Update the selected clock generator divider so that its changes take affect.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Update_Clock_Generator_Divider (void *Handle,
_ccurpmfc_clock_generator_divider_t WhichDivider)

Description: Update Clock Generator Divider

Input: void *Handle (Handle pointer)
_ccurpmfc_clock_generator_divider_t WhichDivider (select divider)
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_M
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_N0
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_N1
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_N2
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_N3
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_N_ALL
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_P0
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_P1
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_P2
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_PFB
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_P_ALL
# CCURPMFC_CLOCK_GENERATOR_DIVIDER_PXAXB

Output: none
Return: _ccurpmfc_lib_error_number_t
# CCURPMFC_LIB_NO_ERROR (successful)
# CCURPMFC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURPMFC_LIB_NOT_OPEN (library not open)
# CCURPMFC_LIB_NO_LOCAL_REGION (local region error)
# CCURPMFC_LIB_INVALID_ARG (invalid argument)
# CCURPMFC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

2.2.214 ccurPMFC_UserProcess_Command()

The user can control the execution of the created User Process with the help of this call. *(This is an experimental API for debugging and testing).*

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_UserProcess_Command(void *Handle,
void *UFuncHandle,
ccurpmfc_uf_action_t Action)

Description: Command User process

Input: void *UFuncHandle (User Process Handle pointer)
ccurpmfc_uf_action_t Action (command action)
# CCURPMFC_UF_ACTION_STOP
# CCURPMFC_UF_ACTION_RUN
# CCURPMFC_UF_ACTION_TERMINATE

Output: none
Return: none
*****/

```

2.2.215 ccurPMFC_VoltsToData()

This call returns to the user the raw converted value for the requested voltage in the specified format. Voltage supplied must be within the input range of the selected board type. If the voltage is out of range, the call sets the voltage to the appropriate limit value.

```

/*****
uint
ccurPMFC_VoltsToData (double          volts,
                     ccurpmfc_volt_convert_t *conv)

Description: Convert Volts to data

Input:  double          volts          (volts to convert)
        ccurpmfc_volt_convert_t *conv  (pointer to conversion struct)
        double          VoltageRange  (maximum voltage range)
        _ccurpmfc_csr_dataformat_t Format  (format)
        # CCURPMFC_OFFSET_BINARY
        # CCURPMFC_TWOS_COMPLEMENT
        ccurpmfc_bool    BiPolar      (bi-polar)
        # CCURPMFC_TRUE
        # CCURPMFC_FALSE
        int              ResolutionBits (Number of resolution bits)

Output: none
Return: uint            data          (returned data)
*****/
```

2.2.216 ccurPMFC_Wait_For_Interrupt()

This call is made available to advanced users to bypass the API and perform their own data collection. The user can wait for a DMA complete interrupt. If a time out value greater than zero is specified, the call will time out after the specified seconds, otherwise it will not time out.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Wait_For_Interrupt (void          *Handle,
                             ccurpmfc_driver_int_t *drv_int)

Description: Wait For Interrupt

Input:  void          *Handle          (Handle pointer)
        ccurpmfc_driver_int_t *drv_int (pointer to drv_int struct)
        uint          WakeupInterruptMask
        # CCURPMFC_DMA0_INTMASK
        # CCURPMFC_DMA1_INTMASK
        # CCURPMFC_MSGDMA_INTMASK
        # CCURPMFC_ADC_FIFO_INTMASK
        # CCURPMFC_DAC_FIFO_INTMASK
        int          timeout_seconds

Output: ccurpmfc_driver_int_t *drv_int (pointer to drv_int struct)
        long long unsigned count
        long long unsigned dma_count[CCURPMFC_DMA_MAX_ENGINES]
        long long unsigned MsgDma_count
        uint          InterruptsOccurredMask
        uint          WakeupInterruptMask
        int          DmaControl      (DMA control flags)
        # CCURPMFC_DMA_CONTROL_RCON (read constant)
        # CCURPMFC_DMA_CONTROL_WCON (write constant)
        # CCURPMFC_DMA_CONTROL_INCREMENT (increment)

Return: _ccurpmfc_lib_error_number_t
        # CCURPMFC_LIB_NO_ERROR      (successful)
        # CCURPMFC_LIB_BAD_HANDLE    (no/bad handler supplied)
*****/
```

```

# CCURPMFC_LIB_NOT_OPEN          (device not open)
# CCURPMFC_LIB_NO_LOCAL_REGION   (local region not present)
# CCURPMFC_LIB_INVALID_ARG       (invalid argument)
*****/

```

2.2.217 ccurPMFC_Write()

This call is currently not supported.

```

/*****
_ccurpmfc_lib_error_number_t
ccurPMFC_Write (void      *Handle,
                void      *buf,
                int        size,
                int        *bytes_written,
                int        *error)

Description: Perform a write operation.

Input:   void      *Handle      (Handle pointer)
         int        size        (number of bytes to write)
Output:  void      *buf        (pointer to buffer)
         int        *bytes_written (bytes written)
         int        *error      (returned errno)

Return:  _ccurpmfc_lib_error_number_t
         # CCURPMFC_LIB_NO_ERROR      (successful)
         # CCURPMFC_LIB_BAD_HANDLE   (no/bad handler supplied)
         # CCURPMFC_LIB_NOT_OPEN     (device not open)
         # CCURPMFC_LIB_IO_ERROR     (write failed)
         # CCURPMFC_LIB_NOT_IMPLEMENTED (call not implemented)
*****/

```

3. Test Programs

This driver and API are accompanied with an extensive set of test examples. Examples under the *Direct Driver Access* do not use the API, while those under *Application Program Interface Access* use the API.

3.1 Direct Driver Access Example Tests

These set of tests are located in the `.../test` directory and do not use the API. They communicate directly with the driver. Users should be extremely familiar with both the driver and the hardware registers if they wish to communicate directly with the hardware.

3.1.1 ccurpmfc_disp

Useful program to display the local board registers. This program uses the *curses* library.

```
Usage: ./ccurpmfc_disp [-b BoardNo] [-d Delay] [-l LoopCnt] [-o Offset] [-s Size]
-b BoardNo (Board number -- default is 0)
-d Delay (Delay between screen refresh -- default is 0)
-l LoopCnt (Loop count -- default is 0)
-o Offset (Hex offset to read from -- default is 0x0)
-s Size (Number of bytes to read -- default is 0x400)
```

Example display:

```
./ccurpmfc_disp
```

```
Board Number [-b]: 0
Delay [-d]: 0 milli-seconds
Loop Count [-l]: ***Forever***
Offset [-o]: 0x00000000
Size [-s]: 1024 (bytes)
```

```
ScanCount = 59758

      00      04      08      0C      10      14      18      1C
=====
000000  92900101 05252016 00550003 00000000 00000000 00000000 00000000
000020  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000040  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000060  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000080  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0000a0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0000c0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0000e0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000100  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000120  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000140  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000160  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000180  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0001a0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0001c0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0001e0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000200  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000220  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000240  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000260  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000280  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0002a0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0002c0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0002e0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000300  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000320  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000340  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000360  00000000 00000000 00000000 00000000 00000000 00000000 00000000
000380  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0003a0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
0003c0  00000000 00000000 00000000 00000000 00000000 00000000 00000000
```

0003e0 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000

3.1.2 ccurpmfc_dma

This test transfers data from physical memory to the Local register area and back. There are three modes of operation. Two are DMA and one is programmed I/O. Depending on the number of DMA engines supported by the card, the user can select one of them to perform the DMA. Area select is one of three areas the user can specify. They represent the area in physical memory and local register where the transfer is to occur. The test automatically switches to a different area corresponding to the DMA engine supplied. If multiple copies of this application is run on the same card using the same DMA engine, then the user needs to manually select a different area '-A' so the data mismatch does not occur due to using the same area region.

```
Usage: ./ccurpmfc_dma [-A Area2Select] [-b Board] [-D DMAEngineNo] [-i]
                        [-l LoopCnt] [-m XferMode] [-s Size] [-v VerboseNo]
-A Area2Select (Area to select -- default = -1)
-b Board      (Board number -- default = 0)
-D DMAEngineNo (DMA Engine number -- default = 0)
-i           (Enable Interrupts -- default = Disable)
-l LoopCnt   (Loop Count - default = 1000)
-m XferMode  (Transfer Mode -- default = Simple DMA)
  -md       (Simple DMA mode)
  -mp       (Programmed I/O mode)
  -mx       (Low-Level DMA mode)
-s Size      (Transfer Size (multiple of byte width) - default = 12288)
-V VerboseNo (Verbose -- default = 0)
```

Example display:

```
./ccurpmfc_dma
```

```
Device Name: /dev/ccurpmfc0
```

```
LOCAL REGION: Physical Addr=0xc4900000 Size=65536 (0x00010000)
CONFIG REGION: Physical Addr=0xc4910000 Size=32768 (0x00008000)
```

```
LOCAL: Register 0x7ffff7fe7000 Offset=0x0 Size=0x00010000
CONFIG: Register 0x7ffff7fd0000 Offset=0x0 Size=0x00008000
LIBPTR: Register 0x7ffff7fd0000 Offset=0x0 Size=0x00001070
DMA: Address 0x7ffff70f4000 Offset 0x0 Size=0x00200000
                                           Physical Address=0x79800000
```

Physical Memory Information:

```
UserPID          =5665
PhysMemPtr       =0x79800000
DriverVirtMemPtr=0xffff880079800000
MmappedUserMemPtr=0x7ffff70f4000
PhysMemSize      =0x00200000
PhysMemSizeFreed=0x00000000
EntryInTxTbl    =0
NumOfEntriesUsed=2
```

```
### Avalon Address[A0]: 0x00001000 - 0x00004000
### DMA Address[A0]: 0x00100400 - 0x00103400
### Transfer Size: 12288 (0x00003000) (Simple DMA without interrupts: DMA
Engine 0) ###
1000: A2P: Total: 566.125us ( 21.71 MB/s): first=0xface0000 last=0xface0bff
```

	(micro-seconds)			(MBytes/second)		
	Min	Max	Ave	Min	Max	Ave
P2A:	513.56	519.96	515.66	23.63	23.93	23.83
A2P:	566.01	571.24	566.77	21.51	21.71	21.68

3.1.3 ccurpmfc_dump

This test is for debugging purpose. It dumps all the hardware registers.

Usage: ccurpmfc_dump [-b board]

-b board: board number -- default board is 0

Example display:

```
./ccurpmfc_dump
```

```
Device Name: /dev/ccurpmfc0
```

```
LOCAL REGION: Physical Addr=0xc4900000 Size=65536 (0x00010000)
```

```
CONFIG REGION: Physical Addr=0xc4910000 Size=32768 (0x00008000)
```

```
LOCAL: Register 0x7ffff7fe7000 Offset=0x0 Size=0x00010000
```

```
CONFIG: Register 0x7ffff7fdf000 Offset=0x0 Size=0x00008000
```

```
LIBPTR: Register 0x7ffff7fdd000 Offset=0x0 Size=0x00001070
```

```
===== LOCAL BOARD REGISTERS =====
```

```
LBR: @0x0000 --> 0x92900101
```

```
LBR: @0x0004 --> 0x05252016
```

```
LBR: @0x0008 --> 0x00550003
```

```
LBR: @0x000c --> 0x00000000
```

```
LBR: @0x0010 --> 0x00000000
```

```
LBR: @0x0014 --> 0x00000000
```

```
LBR: @0x0018 --> 0x00000000
```

```
LBR: @0x001c --> 0x00000000
```

```
LBR: @0x0020 --> 0x00000000
```

```
LBR: @0x0024 --> 0x00000000
```

```
LBR: @0x0028 --> 0x00000000
```

```
LBR: @0x002c --> 0x00000000
```

```
LBR: @0x0030 --> 0x00000000
```

```
.
```

```
.
```

```
.
```

```
LBR: @0xffcc --> 0x00000000
```

```
LBR: @0xffd0 --> 0x00000000
```

```
LBR: @0xffd4 --> 0x00000000
```

```
LBR: @0xffd8 --> 0x00000000
```

```
LBR: @0xffdc --> 0x00000000
```

```
LBR: @0xffe0 --> 0x00000000
```

```
LBR: @0xffe4 --> 0x00000000
```

```
LBR: @0xffe8 --> 0x00000000
```

```
LBR: @0xffec --> 0x00000000
```

```
LBR: @0xffff0 --> 0x00000000
```

```
LBR: @0xffff4 --> 0x00000000
```

```
LBR: @0xffff8 --> 0x00000000
```

```
LBR: @0xffffc --> 0x00000000
```

```
===== LOCAL CONFIG REGISTERS =====
```

```
#### CONFIG REGS (PCIeLinkPartnerRegs) ####
```

```
LCR: @0x0000 --> 0x00000000
```

```
LCR: @0x0004 --> 0x00000000
```

```
LCR: @0x0008 --> 0x00000000
```

```
LCR: @0x000c --> 0x00000000
```

```
LCR: @0x0010 --> 0x00000000
```

```

LCR: @0x0014 --> 0x00000000
LCR: @0x0018 --> 0x00000000
LCR: @0x001c --> 0x00000000
LCR: @0x0020 --> 0x00000000
LCR: @0x0024 --> 0x00000000
LCR: @0x0028 --> 0x00000000
LCR: @0x002c --> 0x00000000
LCR: @0x0030 --> 0x00000000
.
.
.
LCR: @0x0fc0 --> 0x00000000
LCR: @0x0fc4 --> 0x00000000
LCR: @0x0fc8 --> 0x00000000
LCR: @0x0fcc --> 0x00000000
LCR: @0x0fd0 --> 0x00000000
LCR: @0x0fd4 --> 0x00000000
LCR: @0x0fd8 --> 0x00000000
LCR: @0x0fdc --> 0x00000000
LCR: @0x0fe0 --> 0x00000000
LCR: @0x0fe4 --> 0x00000000
LCR: @0x0fe8 --> 0x00000000
LCR: @0x0fec --> 0x00000000
LCR: @0x0ff0 --> 0x00000000
LCR: @0x0ff4 --> 0x00000000
LCR: @0x0ff8 --> 0x00000000
LCR: @0x0ffc --> 0x00000000

#### CONFIG REGS (AvalonMM_2_PCIeAddrTrans) ####
LCR: @0x1000 --> 0x00000000
LCR: @0x1004 --> 0x00000000
LCR: @0x1008 --> 0x00000000
LCR: @0x100c --> 0x00000000
LCR: @0x1010 --> 0x00000000
LCR: @0x1014 --> 0x00000000
LCR: @0x1018 --> 0x00000000
LCR: @0x101c --> 0x00000000
LCR: @0x1020 --> 0x00000000
LCR: @0x1024 --> 0x00000000
LCR: @0x1028 --> 0x00000000
LCR: @0x102c --> 0x00000000
LCR: @0x1030 --> 0x00000000
.
.
.
LCR: @0x1fb0 --> 0x00000000
LCR: @0x1fb4 --> 0x00000000
LCR: @0x1fb8 --> 0x00000000
LCR: @0x1fbc --> 0x00000000
LCR: @0x1fc0 --> 0x00000000
LCR: @0x1fc4 --> 0x00000000
LCR: @0x1fc8 --> 0x00000000
LCR: @0x1fcc --> 0x00000000
LCR: @0x1fd0 --> 0x00000000
LCR: @0x1fd4 --> 0x00000000
LCR: @0x1fd8 --> 0x00000000
LCR: @0x1fdc --> 0x00000000

```

```

LCR: @0x1fe0 --> 0x00000000
LCR: @0x1fe4 --> 0x00000000
LCR: @0x1fe8 --> 0x00000000
LCR: @0x1fec --> 0x00000000
LCR: @0x1ff0 --> 0x00000000
LCR: @0x1ff4 --> 0x00000000
LCR: @0x1ff8 --> 0x00000000
LCR: @0x1ffc --> 0x00000000

```

```

#### CONFIG REGS (DMA Control Table) ####

```

```

LCR: @0x4000 --> 0x00000011
LCR: @0x4004 --> 0x0000c000
LCR: @0x4008 --> 0x00903400
LCR: @0x400c --> 0x00000000
LCR: @0x4010 --> 0x00000000
LCR: @0x4014 --> 0x00000000
LCR: @0x4018 --> 0x00000000
LCR: @0x401c --> 0x00000000
LCR: @0x4020 --> 0x00000000
LCR: @0x4024 --> 0x00000000
LCR: @0x4028 --> 0x00000000
LCR: @0x402c --> 0x00000000
LCR: @0x4030 --> 0x00000000
LCR: @0x4034 --> 0x00000000
LCR: @0x4038 --> 0x00000000
LCR: @0x403c --> 0x00000000

```

```

===== PCI CONFIG REG ADDR MAPPING =====

```

```

PCR: @0x0000 --> 0x92901542
PCR: @0x0004 --> 0x00100406
PCR: @0x0008 --> 0x08800001
PCR: @0x000c --> 0x00000010
PCR: @0x0010 --> 0xc4910000
PCR: @0x0014 --> 0x00000000
PCR: @0x0018 --> 0xc4900000
PCR: @0x001c --> 0x00000000
PCR: @0x0020 --> 0x00000000
PCR: @0x0024 --> 0x00000000
PCR: @0x0028 --> 0x00000000
PCR: @0x002c --> 0x01001542
PCR: @0x0030 --> 0x00000000
PCR: @0x0034 --> 0x00000050
PCR: @0x0038 --> 0x00000000
PCR: @0x003c --> 0x0000010b
PCR: @0x0040 --> 0x00000000
PCR: @0x0044 --> 0x02006160
PCR: @0x0048 --> 0x00000000
PCR: @0x004c --> 0x00000000
PCR: @0x0050 --> 0x00857805

```

3.1.4 ccurpmfc_rdreg

This is a simple program that returns the local register value for a given offset.

```

Usage: ./ccurpmfc_rdreg [-b Board] [-C] [-f] [-o Offset] [-s Size]
  -b Board    : Board number -- default board is 0
  -C          : Select Config Registers instead of Local Registers
  -f          : Fast Memory Reads

```

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-o Offset : Hex offset to read from -- default offset is 0x0
-s Size : Number of bytes to read in decimal -- default size is 0x4

Example display:

./ccurpmfc_rdreg -s64

Device Name: /dev/ccurpmfc0

LOCAL REGION: Physical Addr=0xc4900000 Size=65536 (0x00010000)
CONFIG REGION: Physical Addr=0xc4910000 Size=32768 (0x00008000)

LOCAL: Register 0x7ffff7fe7000 Offset=0x0 Size=0x00010000
CONFIG: Register 0x7ffff7fdf000 Offset=0x0 Size=0x00008000
LIBPTR: Register 0x7ffff7fdd000 Offset=0x0 Size=0x00001070

```
#### LOCAL REGS #### (length=64)
+LCL+      0  92900101  05252016  00550003  00000000  *.....% ..U.....*
+LCL+     0x10 00000000  00000000  00000000  00000000  *.....*
+LCL+     0x20 00000000  00000000  00000000  00000000  *.....*
+LCL+     0x30 00000000  00000000  00000000  00000000  *.....*
```

./ccurpmfc_rdreg -C -o4020 -s20

Device Name: /dev/ccurpmfc0

LOCAL REGION: Physical Addr=0xc4900000 Size=65536 (0x00010000)
CONFIG REGION: Physical Addr=0xc4910000 Size=32768 (0x00008000)

LOCAL: Register 0x7ffff7fe7000 Offset=0x0 Size=0x00010000
CONFIG: Register 0x7ffff7fdf000 Offset=0x0 Size=0x00008000
LIBPTR: Register 0x7ffff7fdd000 Offset=0x0 Size=0x00001070

```
#### LOCAL REGS #### (length=20)
+LCL+   0x4020 00000000  00000000  00000000  00000000  *.....*
+LCL+   0x4030 00000000
```

3.1.5 ccurpmfc_reg

This call displays all the boards local and configuration registers.

Usage: ./ccurpmfc_reg [-b board]
-b board: Board number -- default board is 0

Example display:

./ccurpmfc_reg

Device Name: /dev/ccurpmfc0

LOCAL REGION: Physical Addr=0xc4900000 Size=65536 (0x00010000)
CONFIG REGION: Physical Addr=0xc4910000 Size=32768 (0x00008000)

LOCAL: Register 0x7ffff7fe7000 Offset=0x0 Size=0x00010000
CONFIG: Register 0x7ffff7fdf000 Offset=0x0 Size=0x00008000
LIBPTR: Register 0x7ffff7fdd000 Offset=0x0 Size=0x00001070
LOCAL Register 0x7ffff7fe7000 size=0x00010000

```
#### LOCAL REGS #### (length=65536)
+LCL+      0  92900101  05252016  00550003  00000000  *.....% ..U.....*
+LCL+     0x10 00000000  00000000  00000000  00000000  *.....*
+LCL+     0x20 00000000  00000000  00000000  00000000  *.....*
+LCL+     0x30 00000000  00000000  00000000  00000000  *.....*
```

```

+LCL+ 0x40 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x50 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x60 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x70 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x80 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x90 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xa0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xb0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xc0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xd0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xe0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xf0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x100 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x110 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x120 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x130 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x140 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x150 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x160 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x170 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x180 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x190 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1a0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1b0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1c0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1d0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1e0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1f0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x200 00000000 00000000 00000000 00000000 *.....*
.
.
+LCL+ 0xfed0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xfef0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xfef0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff00 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff10 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff20 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff30 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff40 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff50 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff60 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff70 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff80 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xff90 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xffa0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xffb0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xffc0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xffd0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xffe0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0xffff0 00000000 00000000 00000000 00000000 *.....*

```

CONFIG Register 0x7ffff7fdf000 size=0x00008000

```

#### CONFIG REGS (PCIeLinkPartnerRegs) #### (length=4096)
+CFG+ 0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x10 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x20 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x30 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x40 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x50 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x60 00000004 00000004 00000008 00000008 *.....*
+CFG+ 0x70 00000000 00000000 00000000 00000000 *.....*

```

```

+CFG+ 0x80 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x90 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xa0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xb0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xc0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xd0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xe0 00000004 00000004 00000008 00000008 *.....*
+CFG+ 0xf0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x100 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x110 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x120 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x130 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x140 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x150 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x160 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x170 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x180 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x190 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1a0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1b0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1c0 00000000 00000000 00000000 00000000 *.....*
.
.
+CFG+ 0xf00 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf10 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf20 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf30 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf40 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf50 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf60 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf70 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf80 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xf90 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xfa0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xfb0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xfc0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xfd0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xfe0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xff0 00000000 00000000 00000000 00000000 *.....*

#### CONFIG REGS (AvalonMM_2_PCIeAddrTrans) #### (length=4096)
+CFG+ 0x1000 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1010 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1020 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1030 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1040 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1050 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1060 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1070 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1080 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1090 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x10a0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x10b0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x10c0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x10d0 00000000 00000000 00000000 00000000 *.....*
.
.
+CFG+ 0x1f50 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1f60 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1f70 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1f80 00000000 00000000 00000000 00000000 *.....*

```

```

+CFG+ 0x1f90 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1fa0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1fb0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1fc0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1fd0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1fe0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x1ff0 00000000 00000000 00000000 00000000 *.....*

```

```

#### CONFIG REGS (DMA Control Table) #### (length=64)
+CFG+ 0x4000 00000011 0000c000 00903400 00000000 *.....4.....*
+CFG+ 0x4010 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x4020 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x4030 00000000 00000000 00000000 00000000 *.....*

```

===== LOCAL REGISTERS =====

```

BoardInfo                =0x92900101 @0x00000000
FirmwareDate              =0x05252016 @0x00000004
FirmwareRevision          =0x00550003 @0x00000008
FirmwareTime              =0x00093204 @0x0000000c
FirmwareFlavorCode        =0x47453031 @0x00000010
NumberAdvancedIPCores     =0x00000001 @0x00000014
BoardCSR                  =0x00000000 @0x00002000
InterruptStatus           =0x00000000 @0x00002010
SPI_CommandStatus         =0x03004000 @0x000020f0
SPI_FirmwareAddress       =0x01ffff00 @0x000020f4
SPI_Ram[0]                =0x7fb75d7d @0x00002100
SPROM_StatAddrWriteData   =0x001f0000 @0x00002300
SPROM_ReadData            =0x001f0000 @0x00002304
FPGA_ChipIdentification[0] =0x00e9400c @0x00002400
FPGA_ChipIdentification[1] =0x18730811 @0x00002404
FPGA_ChipTemperature      =0x00000023 @0x00002410
ClockGen_CSR              =0x00000003 @0x00002500
ClockGen_access           =0x000d00f6 @0x00002504
CalibrationCSR            =0x00000000 @0x00002600
TestBusControl            =0x00000000 @0x00002604
ADC_Enable                =0x00000001 @0x00003000
ADC_ControlStatus[CCURPMFC_ADC_0] =0x00000001 @0x00003010
ADC_ControlStatus[CCURPMFC_ADC_1] =0x00000001 @0x00003014
ADC_FifoCSR               =0x81000000 @0x00003030
ADC_FifoThreshold         =0x00020000 @0x00003034
ADC_FifoChannelSelect     =0x0000ffff @0x00003038
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_0] =0x7fd5d725 @0x00003100
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_1] =0x7fd0b404 @0x00003104
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_2] =0x7fcc0e9f @0x00003108
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_3] =0x7fd41be3 @0x0000310c
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_4] =0x7fc2410a @0x00003110
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_5] =0x7fd2ccac @0x00003114
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_6] =0x7ff9f82b @0x00003118
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_7] =0x7fd002ff @0x0000311c
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_8] =0x7fc9d098 @0x00003120
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_9] =0x7fb24778 @0x00003124
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_10] =0x7fc4b32d @0x00003128
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_11] =0x7fb61607 @0x0000312c
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_12] =0x7fb6c93a @0x00003130
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_13] =0x7fe4526b @0x00003134
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_14] =0x7fc54c68 @0x00003138
ADC_PositiveCalibration[CCURPMFC_ADC_CHANNEL_15] =0x7fd45401 @0x0000313c
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_0] =0x7fd42e90 @0x00003140
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_1] =0x7fd1488d @0x00003144
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_2] =0x7fcae7da @0x00003148
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_3] =0x7fd5b5ef @0x0000314c

```

ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_4]	=0x7fc1635b	@x00003150
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_5]	=0x7fd1c38b	@x00003154
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_6]	=0x7ffa3a42	@x00003158
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_7]	=0x7fce5fe4	@x0000315c
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_8]	=0x7fc7cf4b	@x00003160
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_9]	=0x7fb18546	@x00003164
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_10]	=0x7fc57a75	@x00003168
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_11]	=0x7fb5d398	@x0000316c
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_12]	=0x7fb6057f	@x00003170
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_13]	=0x7fe2e1a0	@x00003174
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_14]	=0x7fc33037	@x00003178
ADC_NegativeCalibration[CCURPMFC_ADC_CHANNEL_15]	=0x7fd3a2d9	@x0000317c
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_0]	=0x00000002	@x00003180
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_1]	=0x00000001	@x00003184
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_2]	=0x00000000	@x00003188
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_3]	=0x0000ffff	@x0000318c
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_4]	=0x00000001	@x00003190
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_5]	=0x00000001	@x00003194
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_6]	=0x0000fffe	@x00003198
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_7]	=0x00000000	@x0000319c
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_8]	=0x00000001	@x000031a0
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_9]	=0x00000000	@x000031a4
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_10]	=0x00000000	@x000031a8
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_11]	=0x0000ffff	@x000031ac
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_12]	=0x00000000	@x000031b0
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_13]	=0x00000000	@x000031b4
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_14]	=0x0000fffe	@x000031b8
ADC_OffsetCalibration[CCURPMFC_ADC_CHANNEL_15]	=0x0000ffff	@x000031bc
ADC_Data[CCURPMFC_ADC_CHANNEL_0]	=0x00007fff	@x00003200
ADC_Data[CCURPMFC_ADC_CHANNEL_1]	=0x00007fff	@x00003204
ADC_Data[CCURPMFC_ADC_CHANNEL_2]	=0x00007fff	@x00003208
ADC_Data[CCURPMFC_ADC_CHANNEL_3]	=0x00007fff	@x0000320c
ADC_Data[CCURPMFC_ADC_CHANNEL_4]	=0x00008000	@x00003210
ADC_Data[CCURPMFC_ADC_CHANNEL_5]	=0x00008000	@x00003214
ADC_Data[CCURPMFC_ADC_CHANNEL_6]	=0x00007fff	@x00003218
ADC_Data[CCURPMFC_ADC_CHANNEL_7]	=0x00007fff	@x0000321c
ADC_Data[CCURPMFC_ADC_CHANNEL_8]	=0x00007fff	@x00003220
ADC_Data[CCURPMFC_ADC_CHANNEL_9]	=0x00008000	@x00003224
ADC_Data[CCURPMFC_ADC_CHANNEL_10]	=0x00007fff	@x00003228
ADC_Data[CCURPMFC_ADC_CHANNEL_11]	=0x00008000	@x0000322c
ADC_Data[CCURPMFC_ADC_CHANNEL_12]	=0x00008000	@x00003230
ADC_Data[CCURPMFC_ADC_CHANNEL_13]	=0x00008000	@x00003234
ADC_Data[CCURPMFC_ADC_CHANNEL_14]	=0x00008000	@x00003238
ADC_Data[CCURPMFC_ADC_CHANNEL_15]	=0x00007fff	@x0000323c
ADC_FifoData	=0xbaadbeef	@x00003300
DAC_Enable	=0x00000000	@x00004000
DAC_UpdateSourceSelect	=0x00000000	@x00004004
DAC_FifoChannelSelect	=0x00000000	@x00004008
DAC_ControlStatus[CCURPMFC_DAC_0]	=0x00000000	@x00004010
DAC_ControlStatus[CCURPMFC_DAC_1]	=0x00000000	@x00004014
DAC_ControlStatus[CCURPMFC_DAC_2]	=0x00000000	@x00004018
DAC_ControlStatus[CCURPMFC_DAC_3]	=0x00000000	@x0000401c
DAC_FifoCSR	=0x00000000	@x00004030
DAC_FifoThreshold	=0x00000000	@x00004034
DAC_FifoWriteCount	=0x00000000	@x00004038
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_0]	=0x00000000	@x00004100
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_1]	=0x00000000	@x00004104
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_2]	=0x00000000	@x00004108
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_3]	=0x00000000	@x0000410c
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_4]	=0x00000000	@x00004110
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_5]	=0x00000000	@x00004114
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_6]	=0x00000000	@x00004118
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_7]	=0x00000000	@x0000411c

```

DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_8]           =0x00000000 @0x00004120
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_9]           =0x00000000 @0x00004124
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_10]          =0x00000000 @0x00004128
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_11]          =0x00000000 @0x0000412c
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_12]          =0x00000000 @0x00004130
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_13]          =0x00000000 @0x00004134
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_14]          =0x00000000 @0x00004138
DAC_GainCalibration[CCURPMFC_DAC_CHANNEL_15]          =0x00000000 @0x0000413c
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_0]         =0x00000000 @0x00004140
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_1]         =0x00000000 @0x00004144
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_2]         =0x00000000 @0x00004148
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_3]         =0x00000000 @0x0000414c
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_4]         =0x00000000 @0x00004150
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_5]         =0x00000000 @0x00004154
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_6]         =0x00000000 @0x00004158
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_7]         =0x00000000 @0x0000415c
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_8]         =0x00000000 @0x00004160
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_9]         =0x00000000 @0x00004164
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_10]        =0x00000000 @0x00004168
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_11]        =0x00000000 @0x0000416c
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_12]        =0x00000000 @0x00004170
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_13]        =0x00000000 @0x00004174
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_14]        =0x00000000 @0x00004178
DAC_OffsetCalibration[CCURPMFC_DAC_CHANNEL_15]        =0x00000000 @0x0000417c
DAC_Data[CCURPMFC_DAC_CHANNEL_0]                     =0x00000000 @0x00004200
DAC_Data[CCURPMFC_DAC_CHANNEL_1]                     =0x00000000 @0x00004204
DAC_Data[CCURPMFC_DAC_CHANNEL_2]                     =0x00000000 @0x00004208
DAC_Data[CCURPMFC_DAC_CHANNEL_3]                     =0x00000000 @0x0000420c
DAC_Data[CCURPMFC_DAC_CHANNEL_4]                     =0x00000000 @0x00004210
DAC_Data[CCURPMFC_DAC_CHANNEL_5]                     =0x00000000 @0x00004214
DAC_Data[CCURPMFC_DAC_CHANNEL_6]                     =0x00000000 @0x00004218
DAC_Data[CCURPMFC_DAC_CHANNEL_7]                     =0x00000000 @0x0000421c
DAC_Data[CCURPMFC_DAC_CHANNEL_8]                     =0x00000000 @0x00004220
DAC_Data[CCURPMFC_DAC_CHANNEL_9]                     =0x00000000 @0x00004224
DAC_Data[CCURPMFC_DAC_CHANNEL_10]                    =0x00000000 @0x00004228
DAC_Data[CCURPMFC_DAC_CHANNEL_11]                    =0x00000000 @0x0000422c
DAC_Data[CCURPMFC_DAC_CHANNEL_12]                    =0x00000000 @0x00004230
DAC_Data[CCURPMFC_DAC_CHANNEL_13]                    =0x00000000 @0x00004234
DAC_Data[CCURPMFC_DAC_CHANNEL_14]                    =0x00000000 @0x00004238
DAC_Data[CCURPMFC_DAC_CHANNEL_15]                    =0x00000000 @0x0000423c
DAC_FifoData                                          =0x00000000 @0x00004300
DIO_Enable                                           =0x00000000 @0x00005000
DIO_Mode                                              =0x00000000 @0x00005004
DIO_InputSnapshot                                    =0x00000000 @0x00005008
DIO_OutputSync                                       =0x00000000 @0x0000500c
DIO_Direction                                        =0x00000000 @0x00005020
DIO_Set_OutputDirection                              =0x00000000 @0x00005024
DIO_Set_InputDirection                               =0x00000000 @0x00005028
DIO_OutputChannels[CCURPMFC_DIO_CHAN_00_31]          =0x00000000 @0x00005030
DIO_OutputChannels[CCURPMFC_DIO_CHAN_32_63]          =0x00000000 @0x00005034
DIO_OutputChannels[CCURPMFC_DIO_CHAN_64_95]          =0x00000000 @0x00005038
DIO_OutputChannelsX.chan_00_31                      =0x00000000 @0x00005030
DIO_OutputChannelsX.chan_32_63                      =0x00000000 @0x00005034
DIO_OutputChannelsX.chan_64_95                      =0x00000000 @0x00005038
DIO_Set_OutputChannelsHigh[CCURPMFC_DIO_CHAN_00_31] =0x00000000 @0x00005040
DIO_Set_OutputChannelsHigh[CCURPMFC_DIO_CHAN_32_63] =0x00000000 @0x00005044
DIO_Set_OutputChannelsHigh[CCURPMFC_DIO_CHAN_64_95] =0x00000000 @0x00005048
DIO_Set_OutputChannelsHighX.chan_00_31              =0x00000000 @0x00005040
DIO_Set_OutputChannelsHighX.chan_32_63              =0x00000000 @0x00005044
DIO_Set_OutputChannelsHighX.chan_64_95              =0x00000000 @0x00005048
DIO_Set_OutputChannelsLow[CCURPMFC_DIO_CHAN_00_31]  =0x00000000 @0x00005050
DIO_Set_OutputChannelsLow[CCURPMFC_DIO_CHAN_32_63]  =0x00000000 @0x00005054
DIO_Set_OutputChannelsLow[CCURPMFC_DIO_CHAN_64_95]  =0x00000000 @0x00005058

```

DIO_Set_OutputChannelsLowX.chan_00_31	=0x00000000	@0x00005050
DIO_Set_OutputChannelsLowX.chan_32_63	=0x00000000	@0x00005054
DIO_Set_OutputChannelsLowX.chan_64_95	=0x00000000	@0x00005058
DIO_CustomChannels[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x00005060
DIO_CustomChannels[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x00005064
DIO_CustomChannels[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x00005068
DIO_CustomChannelsX.chan_00_31	=0x00000000	@0x00005060
DIO_CustomChannelsX.chan_32_63	=0x00000000	@0x00005064
DIO_CustomChannelsX.chan_64_95	=0x00000000	@0x00005068
DIO_InputChannels[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x00005070
DIO_InputChannels[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x00005074
DIO_InputChannels[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x00005078
DIO_InputChannelsX.chan_00_31	=0x00000000	@0x00005070
DIO_InputChannelsX.chan_32_63	=0x00000000	@0x00005074
DIO_InputChannelsX.chan_64_95	=0x00000000	@0x00005078
DIO_InputChannelsFilter[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x00005090
DIO_InputChannelsFilter[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x00005094
DIO_InputChannelsFilter[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x00005098
DIO_InputChannelsFilterX.chan_00_31	=0x00000000	@0x00005090
DIO_InputChannelsFilterX.chan_32_63	=0x00000000	@0x00005094
DIO_InputChannelsFilterX.chan_64_95	=0x00000000	@0x00005098
DIO_ChannelsPolarity[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x000050a0
DIO_ChannelsPolarity[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x000050a4
DIO_ChannelsPolarity[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x000050a8
DIO_ChannelsPolarityX.chan_00_31	=0x00000000	@0x000050a0
DIO_ChannelsPolarityX.chan_32_63	=0x00000000	@0x000050a4
DIO_ChannelsPolarityX.chan_64_95	=0x00000000	@0x000050a8
DIO_COS_ChannelsEnable[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x000050b0
DIO_COS_ChannelsEnable[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x000050b4
DIO_COS_ChannelsEnable[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x000050b8
DIO_COS_ChannelsEnableX.chan_00_31	=0x00000000	@0x000050b0
DIO_COS_ChannelsEnableX.chan_32_63	=0x00000000	@0x000050b4
DIO_COS_ChannelsEnableX.chan_64_95	=0x00000000	@0x000050b8
DIO_COS_ChannelsMode[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x000050c0
DIO_COS_ChannelsMode[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x000050c4
DIO_COS_ChannelsMode[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x000050c8
DIO_COS_ChannelsModeX.chan_00_31	=0x00000000	@0x000050c0
DIO_COS_ChannelsModeX.chan_32_63	=0x00000000	@0x000050c4
DIO_COS_ChannelsModeX.chan_64_95	=0x00000000	@0x000050c8
DIO_COS_ChannelsEdgeSense[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x000050d0
DIO_COS_ChannelsEdgeSense[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x000050d4
DIO_COS_ChannelsEdgeSense[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x000050d8
DIO_COS_ChannelsEdgeSenseX.chan_00_31	=0x00000000	@0x000050d0
DIO_COS_ChannelsEdgeSenseX.chan_32_63	=0x00000000	@0x000050d4
DIO_COS_ChannelsEdgeSenseX.chan_64_95	=0x00000000	@0x000050d8
DIO_COS_ChannelsOverflow[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x000050e0
DIO_COS_ChannelsOverflow[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x000050e4
DIO_COS_ChannelsOverflow[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x000050e8
DIO_COS_ChannelsOverflowX.chan_00_31	=0x00000000	@0x000050e0
DIO_COS_ChannelsOverflowX.chan_32_63	=0x00000000	@0x000050e4
DIO_COS_ChannelsOverflowX.chan_64_95	=0x00000000	@0x000050e8
DIO_COS_ChannelsStatus[CCURPMFC_DIO_CHAN_00_31]	=0x00000000	@0x000050f0
DIO_COS_ChannelsStatus[CCURPMFC_DIO_CHAN_32_63]	=0x00000000	@0x000050f4
DIO_COS_ChannelsStatus[CCURPMFC_DIO_CHAN_64_95]	=0x00000000	@0x000050f8
DIO_COS_ChannelsStatusX.chan_00_31	=0x00000000	@0x000050f0
DIO_COS_ChannelsStatusX.chan_32_63	=0x00000000	@0x000050f4
DIO_COS_ChannelsStatusX.chan_64_95	=0x00000000	@0x000050f8
SDRAM_Enable	=0x00000000	@0x00007000
SDRAM_CSR	=0x00000000	@0x00007004
SDRAM_Address	=0x00000000	@0x00007008
SDRAM_Data	=0x00000000	@0x0000700c
DiagRam[0]	=0x00000000	@0x00008000

```

===== CONFIG REGISTERS =====
    PcieLinkPartners.a2p_interrupt_status          =0x00000000 @0x00000040
    PcieLinkPartners.a2p_interrupt_enable         =0x00000000 @0x00000050

#### PCIe Link Partners (p2a_mailbox) #### (length=32)
+P2A+ 0x800 00000000 00000000 00000000 00000000 *.....*
+P2A+ 0x810 00000000 00000000 00000000 00000000 *.....*

#### PCIe Link Partners (a2p_mailbox) #### (length=32)
+A2P+ 0x900 00000000 00000000 00000000 00000000 *.....*
+A2P+ 0x910 00000000 00000000 00000000 00000000 *.....*
    DMAEngine[CCURPMFC_DMA0].dma_status          =0x00000011 @0x00004000
    DMAEngine[CCURPMFC_DMA0].dma_readaddress     =0x0000c000 @0x00004004
    DMAEngine[CCURPMFC_DMA0].dma_writeaddress    =0x00903400 @0x00004008
    DMAEngine[CCURPMFC_DMA0].dma_length         =0x00000000 @0x0000400c
    DMAEngine[CCURPMFC_DMA0].dma_control        =0x00000000 @0x00004018

    DMAEngine[CCURPMFC_DMA1].dma_status          =0x00000000 @0x00004020
    DMAEngine[CCURPMFC_DMA1].dma_readaddress     =0x00000000 @0x00004024
    DMAEngine[CCURPMFC_DMA1].dma_writeaddress    =0x00000000 @0x00004028
    DMAEngine[CCURPMFC_DMA1].dma_length         =0x00000000 @0x0000402c
    DMAEngine[CCURPMFC_DMA1].dma_control        =0x00000000 @0x00004038

    MsgDmaDispatcherCsr.Status                  =0x00000000 @0x00004200
    MsgDmaDispatcherCsr.Control                 =0x00000000 @0x00004204
    MsgDmaDispatcherCsr.ReadFillLevel           =0x00000000 @0x00004208
    MsgDmaDispatcherCsr.WriteFillLevel          =0x00000000 @0x0000420a
    MsgDmaDispatcherCsr.ResponseFillLevel       =0x00000000 @0x0000420c
    MsgDmaDispatcherCsr.ReadSequenceNumber      =0x00000000 @0x00004210
    MsgDmaDispatcherCsr.WriteSequenceNumber     =0x00000000 @0x00004212

    MsgDmaPrefetcherCsr.Control                 =0x00000000 @0x00004220
    MsgDmaPrefetcherCsr.NextDescriptorPointerLow =0x00000000 @0x00004224
    MsgDmaPrefetcherCsr.NextDescriptorPointerHigh =0x00000000 @0x00004228
    MsgDmaPrefetcherCsr.DescriptorPollingFrequency =0x00000000 @0x0000422c
    MsgDmaPrefetcherCsr.Status                  =0x00000000 @0x00004230

=== Descriptor at offset 0 ===
    MsgDmaExtendedDescriptor[Id].ReadAddressLow =0x00000000 @0x00004800
    MsgDmaExtendedDescriptor[Id].WriteAddressLow =0x00000000 @0x00004804
    MsgDmaExtendedDescriptor[Id].Length         =0x00000000 @0x00004808
    MsgDmaExtendedDescriptor[Id].NextDescriptorPointerLow =0x00000000 @0x0000480c
    MsgDmaExtendedDescriptor[Id].ActualBytesTransferred =0x00000000 @0x00004810
    MsgDmaExtendedDescriptor[Id].Status         =0x00000000 @0x00004814
    MsgDmaExtendedDescriptor[Id].SequenceNumber =0x00000000 @0x0000481c
    MsgDmaExtendedDescriptor[Id].ReadBurstCount =0x00000000 @0x0000481e
    MsgDmaExtendedDescriptor[Id].WriteBurstCount =0x00000000 @0x0000481f
    MsgDmaExtendedDescriptor[Id].ReadStride     =0x00000000 @0x00004820
    MsgDmaExtendedDescriptor[Id].WriteStride    =0x00000000 @0x00004822
    MsgDmaExtendedDescriptor[Id].ReadAddressHigh =0x00000000 @0x00004824
    MsgDmaExtendedDescriptor[Id].WriteAddressHigh =0x00000000 @0x00004828
    MsgDmaExtendedDescriptor[Id].NextDescriptorPointerHigh =0x00000000 @0x0000482c
    MsgDmaExtendedDescriptor[Id].Control        =0x00000000 @0x0000483c

=== Descriptor at offset 1 ===
    MsgDmaExtendedDescriptor[Id].ReadAddressLow =0x00000000 @0x00004840
    MsgDmaExtendedDescriptor[Id].WriteAddressLow =0x00000000 @0x00004844
    MsgDmaExtendedDescriptor[Id].Length         =0x00000000 @0x00004848
    MsgDmaExtendedDescriptor[Id].NextDescriptorPointerLow =0x00000000 @0x0000484c
    MsgDmaExtendedDescriptor[Id].ActualBytesTransferred =0x00000000 @0x00004850

```



```

MsgDmaExtendedDescriptor [Id] .Status                =0x00000000 @0x00004854
MsgDmaExtendedDescriptor [Id] .SequenceNumber        =0x00000000 @0x0000485c
MsgDmaExtendedDescriptor [Id] .ReadBurstCount        =0x00000000 @0x0000485e
MsgDmaExtendedDescriptor [Id] .WriteBurstCount       =0x00000000 @0x0000485f
MsgDmaExtendedDescriptor [Id] .ReadStride            =0x00000000 @0x00004860
MsgDmaExtendedDescriptor [Id] .WriteStride           =0x00000000 @0x00004862
MsgDmaExtendedDescriptor [Id] .ReadAddressHigh       =0x00000000 @0x00004864
MsgDmaExtendedDescriptor [Id] .WriteAddressHigh      =0x00000000 @0x00004868
MsgDmaExtendedDescriptor [Id] .NextDescriptorPointerHigh
                                                    =0x00000000 @0x0000486c
MsgDmaExtendedDescriptor [Id] .Control                =0x00000000 @0x0000487c

=== Descriptor at offset 2 ===
MsgDmaExtendedDescriptor [Id] .ReadAddressLow        =0x00000000 @0x00004880
MsgDmaExtendedDescriptor [Id] .WriteAddressLow       =0x00000000 @0x00004884
MsgDmaExtendedDescriptor [Id] .Length                =0x00000000 @0x00004888
MsgDmaExtendedDescriptor [Id] .NextDescriptorPointerLow
                                                    =0x00000000 @0x0000488c
MsgDmaExtendedDescriptor [Id] .ActualBytesTransferred=0x00000000 @0x00004890
MsgDmaExtendedDescriptor [Id] .Status                =0x00000000 @0x00004894
MsgDmaExtendedDescriptor [Id] .SequenceNumber        =0x00000000 @0x0000489c
MsgDmaExtendedDescriptor [Id] .ReadBurstCount        =0x00000000 @0x0000489e
MsgDmaExtendedDescriptor [Id] .WriteBurstCount       =0x00000000 @0x0000489f
MsgDmaExtendedDescriptor [Id] .ReadStride            =0x00000000 @0x000048a0
MsgDmaExtendedDescriptor [Id] .WriteStride           =0x00000000 @0x000048a2
MsgDmaExtendedDescriptor [Id] .ReadAddressHigh       =0x00000000 @0x000048a4
MsgDmaExtendedDescriptor [Id] .WriteAddressHigh      =0x00000000 @0x000048a8
MsgDmaExtendedDescriptor [Id] .NextDescriptorPointerHigh
                                                    =0x00000000 @0x000048ac
MsgDmaExtendedDescriptor [Id] .Control                =0x00000000 @0x000048bc

=== Descriptor at offset 3 ===
MsgDmaExtendedDescriptor [Id] .ReadAddressLow        =0x00000000 @0x000048c0
MsgDmaExtendedDescriptor [Id] .WriteAddressLow       =0x00000000 @0x000048c4
MsgDmaExtendedDescriptor [Id] .Length                =0x00000000 @0x000048c8
MsgDmaExtendedDescriptor [Id] .NextDescriptorPointerLow
                                                    =0x00000000 @0x000048cc
MsgDmaExtendedDescriptor [Id] .ActualBytesTransferred=0x00000000 @0x000048d0
MsgDmaExtendedDescriptor [Id] .Status                =0x00000000 @0x000048d4
MsgDmaExtendedDescriptor [Id] .SequenceNumber        =0x00000000 @0x000048dc
MsgDmaExtendedDescriptor [Id] .ReadBurstCount        =0x00000000 @0x000048de
MsgDmaExtendedDescriptor [Id] .WriteBurstCount       =0x00000000 @0x000048df
MsgDmaExtendedDescriptor [Id] .ReadStride            =0x00000000 @0x000048e0
MsgDmaExtendedDescriptor [Id] .WriteStride           =0x00000000 @0x000048e2
MsgDmaExtendedDescriptor [Id] .ReadAddressHigh       =0x00000000 @0x000048e4
MsgDmaExtendedDescriptor [Id] .WriteAddressHigh      =0x00000000 @0x000048e8
MsgDmaExtendedDescriptor [Id] .NextDescriptorPointerHigh
                                                    =0x00000000 @0x000048ec
MsgDmaExtendedDescriptor [Id] .Control                =0x00000000 @0x000048fc
.
.
.
=== Descriptor at offset 29 ===
MsgDmaExtendedDescriptor [Id] .ReadAddressLow        =0x00000000 @0x00004f40
MsgDmaExtendedDescriptor [Id] .WriteAddressLow       =0x00000000 @0x00004f44
MsgDmaExtendedDescriptor [Id] .Length                =0x00000000 @0x00004f48
MsgDmaExtendedDescriptor [Id] .NextDescriptorPointerLow
                                                    =0x00000000 @0x00004f4c
MsgDmaExtendedDescriptor [Id] .ActualBytesTransferred=0x00000000 @0x00004f50
MsgDmaExtendedDescriptor [Id] .Status                =0x00000000 @0x00004f54
MsgDmaExtendedDescriptor [Id] .SequenceNumber        =0x00000000 @0x00004f5c
MsgDmaExtendedDescriptor [Id] .ReadBurstCount        =0x00000000 @0x00004f5e
MsgDmaExtendedDescriptor [Id] .WriteBurstCount       =0x00000000 @0x00004f5f

```

```

MsgDmaExtendedDescriptor[Id].ReadStride           =0x00000000 @0x00004f60
MsgDmaExtendedDescriptor[Id].WriteStride          =0x00000000 @0x00004f62
MsgDmaExtendedDescriptor[Id].ReadAddressHigh      =0x00000000 @0x00004f64
MsgDmaExtendedDescriptor[Id].WriteAddressHigh     =0x00000000 @0x00004f68
MsgDmaExtendedDescriptor[Id].NextDescriptorPointerHigh
                                                    =0x00000000 @0x00004f6c
MsgDmaExtendedDescriptor[Id].Control              =0x00000000 @0x00004f7c

=== Descriptor at offset 30 ===
MsgDmaExtendedDescriptor[Id].ReadAddressLow       =0x00000000 @0x00004f80
MsgDmaExtendedDescriptor[Id].WriteAddressLow      =0x00000000 @0x00004f84
MsgDmaExtendedDescriptor[Id].Length              =0x00000000 @0x00004f88
MsgDmaExtendedDescriptor[Id].NextDescriptorPointerLow
                                                    =0x00000000 @0x00004f8c
MsgDmaExtendedDescriptor[Id].ActualBytesTransferred=0x00000000 @0x00004f90
MsgDmaExtendedDescriptor[Id].Status               =0x00000000 @0x00004f94
MsgDmaExtendedDescriptor[Id].SequenceNumber      =0x00000000 @0x00004f9c
MsgDmaExtendedDescriptor[Id].ReadBurstCount      =0x00000000 @0x00004f9e
MsgDmaExtendedDescriptor[Id].WriteBurstCount     =0x00000000 @0x00004f9f
MsgDmaExtendedDescriptor[Id].ReadStride          =0x00000000 @0x00004fa0
MsgDmaExtendedDescriptor[Id].WriteStride         =0x00000000 @0x00004fa2
MsgDmaExtendedDescriptor[Id].ReadAddressHigh     =0x00000000 @0x00004fa4
MsgDmaExtendedDescriptor[Id].WriteAddressHigh    =0x00000000 @0x00004fa8
MsgDmaExtendedDescriptor[Id].NextDescriptorPointerHigh
                                                    =0x00000000 @0x00004fac
MsgDmaExtendedDescriptor[Id].Control              =0x00000000 @0x00004fbc

=== Terminating Descriptor at offset 31 ===
MsgDmaTerminatingDescriptor.ReadAddressLow        =0x00000000 @0x00004fc0
MsgDmaTerminatingDescriptor.WriteAddressLow      =0x00000000 @0x00004fc4
MsgDmaTerminatingDescriptor.Length               =0x00000000 @0x00004fc8
MsgDmaTerminatingDescriptor.NextDescriptorPointerLow
                                                    =0x00000000 @0x00004fcc
MsgDmaTerminatingDescriptor.ActualBytesTransferred =0x00000000 @0x00004fd0
MsgDmaTerminatingDescriptor.Status               =0x00000000 @0x00004fd4
MsgDmaTerminatingDescriptor.SequenceNumber       =0x00000000 @0x00004fdc
MsgDmaTerminatingDescriptor.ReadBurstCount       =0x00000000 @0x00004fde
MsgDmaTerminatingDescriptor.WriteBurstCount     =0x00000000 @0x00004fdf
MsgDmaTerminatingDescriptor.ReadStride           =0x00000000 @0x00004fe0
MsgDmaTerminatingDescriptor.WriteStride         =0x00000000 @0x00004fe2
MsgDmaTerminatingDescriptor.ReadAddressHigh     =0x00000000 @0x00004fe4
MsgDmaTerminatingDescriptor.WriteAddressHigh    =0x00000000 @0x00004fe8
MsgDmaTerminatingDescriptor.NextDescriptorPointerHigh
                                                    =0x00000000 @0x00004fec
MsgDmaTerminatingDescriptor.Control              =0x00000000 @0x00004ffc

```

3.1.6 ccurpmfc_regedit

This is an interactive test to display and write to local, configuration and physical memory.

Usage: ./ccurpmfc_regedit [-b board]
 -b board: Board number -- default board is 0

Example display:

```
./ccurpmfc_regedit
```

```
Device Name: /dev/ccurpmfc0
```

```

LOCAL REGION: Physical Addr=0xc4900000 Size=65536 (0x00010000)
CONFIG REGION: Physical Addr=0xc4910000 Size=32768 (0x00008000)

```

```

LOCAL: Register 0x7ffff7fe7000 Offset=0x0 Size=0x00010000
CONFIG: Register 0x7ffff7fdf000 Offset=0x0 Size=0x00008000
LIBPTR: Register 0x7ffff7 added000 Offset=0x0 Size=0x00001070

```

```
Initialize_Board: Firmware Rev. 0x550003 successful
```

```
Virtual Address: 0x7ffff7fe7000
```

```

1 = Create Physical Memory          2 = Destroy Physical memory
3 = Display Channel Data            4 = Display Driver Information
5 = Display Physical Memory Info    6 = Display Registers (CONFIG)
7 = Display Registers (LOCAL)      8 = Dump Physical Memory
9 = Reset Board                    10 = Write Register (LOCAL)
11 = Write Register (CONFIG)       12 = Write Physical Memory

```

```
Main Selection ('h'=display menu, 'q'=quit)->
```

3.1.7 ccurpmfc_tst

This is an interactive test to exercise some of the driver features.

```
Usage: ./ccurpmfc_tst [-b board]
-b board: Board number -- default board is 0
```

Example display:

```
./ccurpmfc_tst
```

```
Device Name: /dev/ccurpmfc0
```

```

LOCAL REGION: Physical Addr=0xc4900000 Size=65536 (0x00010000)
CONFIG REGION: Physical Addr=0xc4910000 Size=32768 (0x00008000)

LOCAL: Register 0x7ffff7fe7000 Offset=0x0 Size=0x00010000
CONFIG: Register 0x7ffff7 added000 Offset=0x0 Size=0x00008000
LIBPTR: Register 0x7ffff7 added000 Offset=0x0 Size=0x00001070
Initialize_Board: Firmware Rev. 0x550003 successful

```

```

01 = add irq                        02 = disable pci interrupts
03 = enable pci interrupts          04 = get device error
05 = get driver info                06 = get physical memory
07 = init board                     08 = mmap select
09 = mmap(CONFIG registers)         10 = mmap(LOCAL registers)
11 = mmap(physical memory)          12 = munmap(physical memory)
13 = no command                     14 = read operation
15 = remove irq                    16 = reset board
17 = restore config registers        18 = write operation

```

```
Main Selection ('h'=display menu, 'q'=quit)->
```

3.1.8 ccurpmfc_wreg

This is a simple test to write to the local registers at the user specified offset.

```
Usage: ./ccurpmfc_wreg [-b Board] [-C] [-o Offset] [-s Size] [-v Value] [-x]
-b Board   : Board selection -- default board is 0
-C         : Select Config Registers instead of Local Registers
-o Offset  : Hex offset to write to -- default offset is 0x0
-s Size    : Number of bytes to write in decimal -- default size is 0x4
-v Value   : Hex value to write at offset -- default value is 0x0
-x         : Do not read back just written values -- default read back values
```

Example display:

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```
./ccurpmfc_wreg -v12345678 -o0x8000 -s400
```

```
Device Name: /dev/ccurpmfc0
```

```
LOCAL REGION: Physical Addr=0xc4900000 Size=65536 (0x00010000)  
CONFIG REGION: Physical Addr=0xc4910000 Size=32768 (0x00008000)
```

```
LOCAL: Register 0x7ffff7fe7000 Offset=0x0 Size=0x00010000  
CONFIG: Register 0x7ffff7fdf000 Offset=0x0 Size=0x00008000  
LIBPTR: Register 0x7ffff7fdd000 Offset=0x0 Size=0x00001070
```

```
Writing 0x12345678 to offset 0x8000 for 400 bytes
```

```
#### LOCAL REGS #### (length=400)  
+LCL+ 0x8000 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8010 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8020 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8030 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8040 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8050 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8060 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8070 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8080 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8090 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x80a0 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x80b0 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x80c0 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x80d0 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x80e0 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x80f0 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8100 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8110 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8120 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8130 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8140 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8150 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8160 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8170 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*  
+LCL+ 0x8180 12345678 12345678 12345678 12345678 * .4Vx.4Vx.4Vx.4Vx*
```

3.1.9 Flash/ccurpmfc_flash

This program is used to burn new firmware. This must only be done at the direction of Concurrent Real-Time support team, otherwise, they could render the board useless.

```
./ccurpmfc_flash -b[Board] -B -F -i -L -q -Q -r[OutFile] -R -v -w[InFile] -X  
-b [Board] : Board number. Must be specified  
-B : Reload Base Level Firmware if MultiFirmware support present  
-F : Force Read Flash: Overwrite output file if exists  
 : Force Write Flash: Do not abort Flash burn for header label  
 : mismatch  
-i : Query chip, on-board flash and InFile if specified  
-L : Update License only. (default is to update entire firmware)  
-q : Quite (non-interactive) mode  
-Q : Quite (non-interactive) mode. Also dump FPGAWB message  
-r : Read Flash and write to output file created by  
 : ./ccurpmfc_flash  
-r [OutFile] : Read Flash and write to output file 'OutFile'  
-R : Reload Firmware at sector address in Flash  
-R [SectorNumber] : Reload Firmware at sector address 'SectorNumber'  
-v : Enable verbose mode  
-w [InFile] : Read input FPGA file and Flash the board  
-X : Use Full File. Do not truncate for firmware write
```

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```

===== Notes =====
Board must be specified. Use '-b' option
Query option '-i' not allowed with '-B', '-R#', '-L', 'r' or '-X' options
Firmware reload '-B' or '-R' not allowed with '-i', '-L', '-r', '-w' or '-X'
options
Firmware read flash '-r' not allowed with '-B', '-i', '-L', '-R', '-w' or '-X'
options
Base Run Level '-B' or '-R#' option not allowed with '-i', '-L', 'r', '-w' or
'-X' options
Must specify write flash option '-w' when License only option '-L' is specified
License only option '-L' not allowed with '-B', '-i', '-R', '-w' or '-X'
options
Don't truncate file option '-X' cannot be selected with the license only update
'-L' option
Don't truncate file option '-X' can only be used with the '-w' option
Inquiry '-i' can be used '-w' options
=====

```

```

e.g. ./ccurpmfc_flash -b0 (Query chip and on-board Flash)
./ccurpmfc_flash -b0 -i (Query chip and on-board Flash)
./ccurpmfc_flash -b0 -i -w InFile (Query chip, on-board Flash and InFile)
./ccurpmfc_flash -b0 -r OutFile (On-board FPGA ==> OutFile)
./ccurpmfc_flash -b0 -w InFile (InFile ==> On-board FPGA - use
truncated file)
./ccurpmfc_flash -b0 -w InFile -v (InFile ==> On-board FPGA - use
truncated file - verbose)
./ccurpmfc_flash -b0 -w InFile -X (InFile ==> On-board FPGA - use entire
file)
./ccurpmfc_flash -b0 -w InFile -L (InFile ==> On-board FPGA - only
license updated - interactive)
./ccurpmfc_flash -b0 -w InFile -L -q (InFile ==> On-board FPGA - only
license updated - non-interactive)
./ccurpmfc_flash -b0 -R (Reload Firmware - i.e. power-cycle the
card) - Run Level
./ccurpmfc_flash -b0 -B (Reload Firmware - i.e. power-cycle the
card) - Base Level
./ccurpmfc_flash -b0 -R -B (Reload Firmware - i.e. power-cycle the
card) - Base Level
./ccurpmfc_flash -b0 -R 200 (Reload Firmware - i.e. power-cycle the
card) - at sector 200

```

3.1.10 Flash/ccurpmfc_label

This utility is only supplied for those customers that are creating their own firmware and need to install in on a RedHawk system. In its simplest form, the customer will request a License from Concurrent Real-Time for the option to burn their custom firmware. The license file (*.lic) supplied by Concurrent Real-Time, along with the customer firmware (*.rpd) file will be supplied to this utility to create a burnable FPGA file (*.cust), that will be supplied to the *ccurpmfc_flash* utility to burn the firmware on the card.

```

./ccurpmfc_label -d[OutputDirectory] -c[ChipName] -F -i[InputFile]
-L[LicenseFile] -m[MemberCode] -o[OutputFile]
-S[RunLevelSectorAddress] -t[Tag]

-d [OutputDirectory] : Directory to use for Output File
-c [ChipName] : Chip Name. One of:
EPCQ16 EPCQ32 EPCQ64 EPCQ128 EPCQ256 EPCQ512
(This option is mandatory if not specified in
license file)
-F : Force overwriting of output file if it exists
-i [InputFile] : Raw input file. (.rpd extension)
-L [LicenseFile] : License file (.lic extension) to restrict firmware
access (this option is mandatory)

```

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```

                                If '-i' option is not specified, the license file is
                                dumped to stderr
-m [MemberCode]                : Specify Member Code (A1,A3,A5,A7,B1,B3,B5,B7)
                                (This option is mandatory if not specified in
                                license file)
-o [OutputFile]                : Use output file instead of the default file created
                                by the program
-S [RunLevelSectorAddress]    : Run Level Sector Address. (This option is mandatory
                                if not specified in license file)
                                : S0=Base Level, S#=Run Level Number
-t [Tag]                       : Insert this tag name in the default file created by
                                the program

```

==== Notes ====

- Options '-L' is required. If option '-i' is not specified, license file is dumped
- Options 'c', '-m' and '-S' are required if they have not already been defined in LicenseFile
- You cannot specify a Run Level Sector '-S' with Single Level Firmware '-1' option
- Run Level Sector address of zero '-S0' represents the Base Level Firmware in Multi-Firmware support
- If option '-o' is not specified, the created customer FPGA file name will be as follows:

```

    <OutputDirectory>/<InputFile>_<Tag>_<Function>_<ChipName><MemberCode><RunLevel>.cust

```

```

e.g. ./ccurpmfc_label -iraw_file.rpd -L LicenseFile.lic (in its simplest form)
      (output file created is: 'raw_file_<Function>_<ChipName><MemberCode><RunLevel>.cust')
./ccurpmfc_label -L LicenseFile.lic (this will display licensing information)
./ccurpmfc_label -iraw_RUN_file.rpd -ooutput_file.cust -S100 -L LicenseFile.lic
./ccurpmfc_label -iraw_SINGLE_file.rpd -L LicenseFile.lic
./ccurpmfc_label -iraw_RUN_file.rpd -ooutput_file.cust -S200 -L LicenseFile.lic
./ccurpmfc_label -iraw_BASE_file.rpd -S0 -L LicenseFile.lic
      (Will cause firmware to be loaded at start offset Base Run Level)

```

3.1.11 Flash/ccurpmfc_dump_license

This utility is allows the customer to dump the license information from a firmware (*.cust) file.

```
./ccurpmfc_dump_license <Firmware file>
```

This utility only dumps the license information from the *.cust file
and *not* the *.lic license file

```
e.g ./ccurpmfc_dump_license COS_IpCoreCOS_EPCQ256A5S100.cust
```

3.2 Application Program Interface (API) Access Example Tests

These set of tests are in the `.../test/lib` directory and use the API.

3.2.1 lib/ccurpmfc_adc

This test performs validation of the Multi-Function ADC card.

```
Usage: ./ccurpmfc_adc [-A] [-a RollingAve] [-b BoardNo] [-C AdcUpdateClock]
                        [-d Delay] [-D DMAEngine] [-E ExpInpVolt] [-f DataFormat]
                        [-F DebugFile] [-i] [-l LoopCnt] [-m XferMode]
                        [-n NumChans] [-N] [-s InputSignal] [-t Compare]
                        [-T TestBus] [-V MaxBoardVolts]
-A                      (Perform Auto Calibration first using reference voltage)
-a RollingAve          (Rolling average -- default "=== None ===")
-b BoardNo             (Board number -- default is 0)
-C AdcUpdateClock     (select ADC update clock, 0..6 or 'n|N')
  -C 0,6               (Ch0..7=Clock0, Ch8..15=Clock6 at MAX SPS)
  -C 6@20000.0/n      (Ch0..7=Clock6 at 20000 SPS, Ch8..15=No Clock)
  -C 4                 (Ch0..15=Clock4 at MAX SPS)
  -C 4@150000.0       (Ch0..15=Clock4) at 150000 SPS
-d Delay               (Delay between screen refresh -- default is 0
                        milli-seconds)
-D DMA Engine         (DMA Engine number -- default = 1)
-E <ExpInpVolts>@<Tol> (Expected Input Volts@Tolerance -- default Tol=0.003000)
  +@<Tol>              (Positive Calibration Ref Volt@Tolerance)
  -@<Tol>              (Negative Calibration Ref Volt@Tolerance)
-f DataFormat         (select data format, '2' or 'b')
  -f b,2               (Ch0..7=Offset binary, Ch8..15=Two's complement)
  -f 2/b               (Ch0..7=Two's complement, Ch8..15=Offset binary)
  -f b                 (Ch0..15=Offset binary)
-F DebugFile          (Debug file with menu display -- default "=== None ===")
  #DebugFile           (Debug file without display (only summary) -- default
                        "=== None ===")
  @DebugFile           (Debug file without display -- default "=== None ===")
  @ or #               (No debug file and no display -- default "=== None ===")
-i                    (Enable Interrupts -- default = Disable)
-l LoopCnt            (Loop count -- default is 0)
-m XferMode           (Transfer Mode -- default = 'DMA Channel')
  -mdp                 (Driver: (Channel Registers) PIO mode)
  -mdP                 (Driver: (FIFO) PIO mode)
  -mlc                 (Library: (Channel Registers) program I/O Fast Memory
                        Copy)
  -mld                 (Library: (Channel Registers) DMA mode)
  -m1D                 (Library: (FIFO) DMA mode)
  -mlp                 (Library: (Channel Registers) PIO
                        mode)
  -mlP                 (Library: (FIFO) PIO mode)
-n NumChans           (Number of channels -- default is 16)
-N                    (Open device with O_NONBLOCK flag)
-s InputSignal        (select input signal, 'e', 'g', '+', '-', 't', 'f',
                        '0..15')
  -s e,g               (Ch0..7=External input, Ch8..15=ground calibration)
  -s +/e               (Ch0..7=Postive calibration, Ch8..15=external reference)
  -s -                 (Ch0..15=Negative calibration)
  -s t                 (Ch0..15=2.5 volt calibration)
  -s e/f               (Ch0..7=external reference, Ch8..15=5 volt calibration)
  -s e/12              (Ch0..7=external reference, Ch8..15=DAC Channel 12)
-t Compare            (Compare two channels for +/- -- default is
                        "=== None ===")
  -t0,15               (Compare channel 0 and 15 for being in sync)
  -t5/7                (Compare channel 5 and 7 for being in sync)
  -t12,4@0.500        (Compare channel 4 and 12 for being in sync with 0.5V
```

```

                                tolerance)
-T TestBus                      (Test Bus Control 'b' or 'o'. Exit after programming
                                this option)
-T b                            (Calibration Bus Control)
-T o                            (Open Bus Control)
-V MaxBoardVolts                (Voltage range 'b5' or 'b10')
-V b5,b10                      (Ch0..7=5V, Ch8..15=10V)
-Vb10/b5                       (Ch0..7=10V, Ch8..15=5V)
-V b10                         (Ch0..15=10V)

e.g. ./ccurpmfc_adc -A -C0@150000.0/1@1234.0 -se/+ (Autocal, ADC0=150000Hz
external input, ADC1=1234Hz
Positive Cal.)
./ccurpmfc_adc -A -C0 -s+ -E+ (Autocal, Max Clock, Positive
cal. input, validate result)
./ccurpmfc_adc -A -C0 -s- -t0,15 -a100 (Autocal, Max Clock, Negative
cal. input, compare ch0 and
ch15, rolling ave=100)

```

Example display:

```
./ccurpmfc_adc -A -C0@150000.0/1@1234.0 -se/+
```

```

local_ptr=0x7ffff7fd7000
Physical Memory Information:
  UserPID           =22341
  PhysMemPtr       =0x352d9000
  DriverVirtMemPtr=0xffff8800352d9000
  MmappedUserMemPtr=0x7ffff7fcc000
  PhysMemSize      =0x00001000
  PhysMemSizeFreed=0x00000000
  EntryInTxTbl     =0
  NumOfEntriesUsed=1
Auto Calibration started...done. (2.357 seconds)

Board Number          [-b]: 0
Update Clock Selected [-C]: Ch00..07 OutputClock=0 (0x7) (150000.000 SPS)
                       : Ch08..15 OutputClock=1 (0x1) (1234.000 SPS)
Delay                 [-d]: 0 milli-seconds
DMA Engine            [-D]: 1
Expected Input Volts [-E]: === Not Specified ===
Data Format            [-f]: Ch00..07 Offset binary (0x0)
                       : Ch08..15 Offset binary (0x0)
Interrupts            [-i]: Disabled
Loop Count            [-l]: ***Forever***
Transfer Mode          [-m]: Library: (Channel Registers) DMA I/O
Number of Channels     [-n]: 16
Input Signal           [-s]: Ch00..07 [0]External Input
                       : Ch08..15 [1]Calibration Input (0x01: Positive 9.91)
Voltage Range          [-V]: Ch00..07 +/-10 Volts (0x1)
                       : Ch08..15 +/-10 Volts (0x1)

Scan Count             : 51661
Read Duration (microsecs) : TotalDelta:      7.266 (min=      7.064/max=      74.005/ave=      7.390)

##### Raw Data #####
 [0]    [1]    [2]    [3]    [4]    [5]    [6]    [7]    [8]    [9]
====    ====    ====    ====    ====    ====    ====    ====    ====    ====
[0]  7fff    8000    7fff    7fff    8000    8001    7fff    8000    fed6    fed6
[1]  fed8    fed9    fed7    fed8    fed8    fed8

##### Volts #####

```

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```

    [0]      [1]      [2]      [3]      [4]      [5]      [6]      [7]      [8]      [9]
    =====
[0] -0.0003 +0.0000 -0.0003 -0.0003 +0.0000 +0.0003 -0.0003 +0.0000 +9.9091 +9.9091
[1] +9.9097 +9.9100 +9.9094 +9.9097 +9.9097 +9.9097

```

```

=====
Date: Mon Oct 25 12:43:14 2017
Expected Input Volts: === Not Specified ===
Scan Counter: 246540
=====

```

```

<----- (volts) ----->
Chan  Min      Max      Ave      TolerExeededCnt
=====
00   -0.0015   0.0006  -0.0002  -
01   -0.0009   0.0009  -0.0000  -
02   -0.0012   0.0000  -0.0003  -
03   -0.0009   0.0003  -0.0002  -
04   -0.0006   0.0021   0.0002  -
05   -0.0006   0.0018   0.0001  -
06   -0.0015   0.0021  -0.0002  -
07   -0.0006   0.0003  -0.0000  -
08    9.9075   9.9121   9.9100  -
09    9.9081   9.9118   9.9101  -
10    9.9078   9.9124   9.9099  -
11    9.9078   9.9121   9.9101  -
12    9.9069   9.9124   9.9098  -
13    9.9081   9.9124   9.9101  -
14    9.9078   9.9124   9.9101  -
15    9.9078   9.9121   9.9101  -
=====

```

3.2.2 lib/ccurpmfc_adc_calibrate

This test is useful for performing, saving and restoring ADC calibration.

```

Usage: ./ccurpmfc_adc_calibrate [-A] [-b board] [-i inCalFile] [-o outCalFile]
-A                                     (perform Auto Calibration)
-b <board>                             (board #, default = 0)
-i <In Cal File>                       (input calibration file [input->board_reg])
-o <Out Cal File>                      (output calibration file [board_reg->output])

```

```

e.g. ./ccurpmfc_adc_calibrate           (Dump calibration information to
                                          stdout)
./ccurpmfc_adc_calibrate -A -o Calfile (Perform Auto calibration and dump
                                          information to 'Calfile')
./ccurpmfc_adc_calibrate -i Calfile    (Update board calibration with
                                          supplied 'Calfile')

```

Example display:

```
./ccurpmfc_adc_calibrate -A
```

```

Device Name      : /dev/ccurpmfc0
Board Serial No: 98765 (0x000181cd)
Auto Calibration started...done. (2.067 seconds)

```

```
=====> Dump to 'stdout'
```

```
#Date           : Wed Jul 12 13:15:01 2017
```

```

#Chan  Negative          Offset          Positive
#====  =====
ch00:  0.99858815083280205727  0.0006103515625000000  0.99863700661808252335

```

```

ch01: 0.99849565094336867332 0.00030517578125000000 0.99847780773416161537
ch02: 0.99830451887100934982 0.00000000000000000000 0.99833975685760378838
ch03: 0.99862672341987490654 -0.00030517578125000000 0.99858157476410269737
ch04: 0.99798926850780844688 0.00030517578125000000 0.99801187450066208839
ch05: 0.99849147163331508636 0.00030517578125000000 0.99852089816704392433
ch06: 0.99974241713061928749 -0.00061035156250000000 0.99974604090675711632
ch07: 0.99841002095490694046 0.00000000000000000000 0.99846544535830616951
ch08: 0.99820307642221450806 0.00030517578125000000 0.99826521240174770355
ch09: 0.99752102326601743698 0.00000000000000000000 0.99755099555477499962
ch10: 0.99814050458371639252 0.00000000000000000000 0.99812307395040988922
ch11: 0.99766269559040665627 -0.00030517578125000000 0.99767517531290650368
ch12: 0.99766628351062536240 0.00000000000000000000 0.99769096216186881065
ch13: 0.99902953673154115677 0.00000000000000000000 0.99908065097406506538
ch14: 0.99805873911827802658 -0.00061035156250000000 0.99813077831640839577
ch15: 0.99856105307117104530 -0.00030517578125000000 0.99859240418300032616

```

3.2.3 lib/ccurpmfc_adc_fifo

This test performs validation of the Multi-Function ADC FIFO operation of the card.

```

Usage: ./ccurpmfc_adc_fifo [-A] [-b BoardNo] [-c ChannelSelectMask]
                                [-C AdcUpdateClock] [-d Delay] [-D DMAEngine]
                                [-E ExpInpVolt] [-f DataFormat] [-F DebugFile] [-i]
                                [-l LoopCnt] [-m XferMode] [-N] [-s InputSignal]
                                [-S NumberOfSamples] [-T TestBus] [-V MaxBoardVolts]
-A                               (Perform Auto Calibration first using reference voltage)
-b BoardNo                       (Board number -- default is 0)
-c ChannelSelectMask             (Specify channel selection mask 0x0..0xffff)
-C AdcUpdateClock               (select ADC update clock, 0..6 or 'n|N')
    -C 0,6                       (Ch0..7=Clock0, Ch8..15=Clock6 at MAX SPS)
    -C 6@20000.0/n              (Ch0..7=Clock6 at 20000 SPS, Ch8..15=No Clock)
    -C 4                          (Ch0..15=Clock4 at MAX SPS)
    -C 4@150000.0              (Ch0..15=Clock4) at 150000 SPS
-d Delay                         (Delay between screen refresh -- default is 0
                                milli-seconds)
-D DMA Engine                   (DMA Engine number -- default = 1)
-E <ExpInpVolts>@<Tol>         (Expected Input Volts@Tolerance -- default Tol=0.003000)
    +@<Tol>                      (Positive Calibration Ref Volt@Tolerance)
    -@<Tol>                      (Negative Calibration Ref Volt@Tolerance)
-f DataFormat                   (select data format, '2' or 'b')
    -f b,2                       (Ch0..7=Offset binary, Ch8..15=Two's complement)
    -f 2/b                      (Ch0..7=Two's complement, Ch8..15=Offset binary)
    -f b                          (Ch0..15=Offset binary)
-F DebugFile                   (Debug file with menu display -- default "=== None ===")
    @DebugFile                  (Debug file without display -- default "=== None ===")
    @                            (No debug file and no display -- default "=== None ===")
-i                               (Enable Interrupts -- default = Disable)
-l LoopCnt                     (Loop count -- default is 0)
-m XferMode                    (Transfer Mode -- default = DMA)
    -mdP                        (Driver: (FIFO) PIO mode)
    -mlD                        (Library: (FIFO) DMA mode)
    -mlP                        (Library: (FIFO) PIO mode)
-N                               (Open device with O_NONBLOCK flag for driver operations)
-s InputSignal                 (select input signal, 'e', 'g', '+', '-', 't', 'f',
                                '0..15')
    -s e,g                      (Ch0..7=External input, Ch8..15=ground calibration)
    -s +/e                      (Ch0..7=Postive calibration, Ch8..15=external reference)
    -s -                        (Ch0..15=Negative calibration)
    -s t                        (Ch0..15=2.5 volt calibration)
    -s e/f                      (Ch0..7=external reference, Ch8..15=5 volt calibration)
    -s e/12                    (Ch0..7=external reference, Ch8..15=DAC Channel 12)
-S NumberOfSamples             (Number of Samples -- default is 49152)
-T TestBus                     (Test Bus Control 'b' or 'o'. Exit after programming)

```

```

                this option)
-T b           (Calibration Bus Control)
-T o           (Open Bus Control)
-V MaxBoardVolts (Voltage range 'b5' or 'b10')
-V b5,b10     (Ch0..7=5V, Ch8..15=10V)
-Vb10/b5     (Ch0..7=10V, Ch8..15=5V)
-V b10       (Ch0..15=10V)

```

```

e.g. ./ccurpmfc_adc_fifo -C0,1@100000 -se/+ (ADC0=300000Hz external input,
                                             ADC1=100000Hz Positive Cal.)

```

Example display:

```
./ccurpmfc_adc_fifo
```

```

local_ptr=0x7ffff7fd7000
      Number of Samples =49152
      Transfer Mode     =Library DMA Mode
      Physical Memory Information:
        UserPID         =26293
        PhysMemPtr      =0x3680000
        DriverVirtMemPtr=0xffff880003680000
        MmappedUserMemPtr=0x7ffff7f44000
        PhysMemSize     =0x00080000
        PhysMemSizeFreed=0x00000000
        EntryInTxTbl    =0
        NumOfEntriesUsed=1
      NumOfChannels=16, FirstChannel=0, LastChannel=15, NumAdc0Chans=8
      NumAdc1Chans=8

```

```
(** Enter <CONTROL-C> to Terminate **)
```

```

6800: usec=11097.26 (min=11095.58/max=11102.85/ave=11097.46) 17.72 MBytes/Sec -
EmptyCnt=92905 (71%)

```

```

=====
                        Date: Mon Oct 25 14:15:44 2017
      Expected Input Volts: === Not Specified ===
        Scan Counter: ADC0=31629312 ADC1=10543104
      Approx. Sample/Second: ADC0=299997 ADC1=99999
        NumberOfChans: ADC0=8 ADC1=8
=====

```

```

<----- (volts) ----->
Chan  Min      Max      Ave      DetectedCnt  TolerExeededCnt
=====
00   -0.0015   0.0003  -0.0002   31629312     -
01   -0.0012   0.0009  -0.0000   31629312     -
02   -0.0012   0.0003  -0.0003   31629312     -
03   -0.0012   0.0003  -0.0002   31629312     -
04   -0.0006   0.0009   0.0002   31629312     -
05   -0.0009   0.0009   0.0001   31629312     -
06   -0.0012   0.0003  -0.0002   31629312     -
07   -0.0009   0.0006  -0.0000   31629312     -
08    9.9072   9.9124   9.9099   10543104     -
09    9.9075   9.9127   9.9100   10543104     -
10    9.9072   9.9124   9.9098   10543104     -
11    9.9075   9.9127   9.9100   10543104     -
12    9.9072   9.9124   9.9097   10543104     -
13    9.9075   9.9124   9.9099   10543104     -
14    9.9075   9.9127   9.9100   10543104     -
15    9.9072   9.9127   9.9100   10543104     -
=====

```

3.2.4 lib/ccurpmfc_clock

This is a useful tool to display information of the various clocks and also program them.

```
Usage: ./ccurpmfc_clock [-b BoardNo] [-C UpdateClock] [-d Delay] [-l LoopCnt]
-b BoardNo          (Board number -- default is 0)
-C <Clock>@<Frequency> (set update clock '0..6' with frequency )
-d Delay            (Delay between screen refresh -- default is 10 milli-
seconds)
-l LoopCnt          (Loop count -- default is 0)
-R                  (Reset/Clear all clocks)

e.g. ./ccurpmfc_clock -C 1@300000
      (Set Clock 1 to 300000 SPS - do not change any other
      running clocks)
      ./ccurpmfc_clock -R -C0@100000 -C4@12345
      (Reset all clocks and then set Clock 0 to 100000 SPS and
      Clock 4 to 12345 SPS)
```

Example display:

```
./ccurpmfc_clock -R -C0@100000 -C4@12345

Board Number [-b]: 0
Delay [-d]: 10 milli-seconds
Loop Count [-l]: ***Forever***
Scan Count: 693

_____ Clock Revision _____
Silicon Revision: A1
Base Part Number: 5341
Device Speed Grade: A
Device Revision: A

_____ Clock CSR _____
Clock Interface: Idle
Clock Output: Enabled
Clock State: Active

_____ Input Clock Status _____
Calibration: Not In-Progress
SMBUS Timeout: Not Timed Out
PLL Lock: Locked
Input Signal: Present
Input_0 Clock: Present
Input_1 Clock: *** Not Present ***
Input_2 Clock: *** Not Present ***
Input_FB Clock: Present
XAXB Input Clock: *** Not Present ***

_____ Output Clock Setting _____
User output clock frequency 0: 100000.000 Samples/Second/Channel
User output clock frequency 1: 1234.000 Samples/Second/Channel
User output clock frequency 2: *** Not Set ***
User output clock frequency 3: *** Not Set ***
User output clock frequency 4: *** Not Set ***
User output clock frequency 5: *** Not Set ***
User output clock frequency 6: *** Not Set ***
SD-RAM output clock frequency 7: 10000000.000 Samples/Second/Channel
External output clock frequency 8: 10000000.000 Samples/Second/Channel
Feed-Back output clock frequency 9: 10000000.000 Samples/Second/Channel
```

3.2.5 lib/ccurpmfc_dac

This test is useful in programming the DAC interface and displaying the DAC registers.

```
Usage: ./ccurpmfc_dac [-A] [-a RollingAve] [-b BoardNo] [-C AdcUpdateClock]
[-d Delay] [-D DMAEngine] [-E ExpInpVolt] [-f DataFormat]
[-F DebugFile] [-l LoopCnt] [-n NumChans] [-o OutputSelect]
[-s InputSignal] [-v DacVoltage] [-V OutputRange] [-Z]
-A (Perform DAC Auto Calibration first using reference
    voltage)
-a RollingAve (Rolling average -- default "=== None ===")
-b BoardNo (Board number -- default is 0)
-C AdcUpdateClock (select ADC update clock, 0..6 or 'n')
  -C 0,6 (Ch0..7=Clock0, Ch8..15=Clock6 at MAX SPS)
  -C 6@20000.0/n (Ch0..7=Clock6 at 20000 SPS, Ch8..15=No Clock)
  -C 4 (Ch0..15=Clock4 at MAX SPS)
  -C 4@150000.0 (Ch0..15=Clock4) at 150000 SPS
-d Delay (Delay between screen refresh -- default is 0 milli-
    seconds)
-D DMA Engine (DMA Engine number -- default = 1)
-E <ExpInpVolts>@<Tol> (Expected Input Volts@Tolerance -- default Tol=0.006000)
  +@<Tol> (Positive Calibration Ref Volt@Tolerance)
  -@<Tol> (Negative Calibration Ref Volt@Tolerance)
  c@<Tol> (DAC Channel 0 Volt@Tolerance)
  Note: (For differential bipolar, even channels, voltage read
    is half supplied)
    (For differential bipolar, odd channels, voltage read is
    neg. half supplied)
-f DataFormat (select DAC data format, '2' or 'b')
  -f b,2 (Ch0..3=Offset binary, Ch4..15=Two's complement)
  -f 2/b,2 (Ch0..3 & Ch8..15=Two's complement, Ch4..7=Offset
    binary)
  -f b (Ch0..15=Offset binary)
-F DebugFile (Debug file with menu display -- default "=== None ===")
  #DebugFile (Debug file without display (only summary) -- default
    "=== None ===")
  @DebugFile (Debug file without display -- default "=== None ===")
  @ or # (No debug file and no display -- default "=== None ===")
-l LoopCnt (Loop count -- default is 0)
-n NumChans (Number of channels (1..16) -- default is 16)
-o OutputSelect (DAC output select, 's' or 'd')
  -o d,s (Ch0..3=differential, Ch4..15=single_ended)
  -o s/d,s (Ch0..3 & Ch8..15=single_ended, Ch4..7=differential)
  -o d (Ch0..15=differential)
-s InputSignal (ADC select input signal, 'a', 'e', 'g', '+', '-', 't',
  'f', '0..15')
  -s a,e (Ch0..7=All DAC Channels 0..7, Ch8..15=External ADC
    Input)
  -s e,g (Ch0..7=External ADC input, Ch8..15=ground calibration)
  -s +/e (Ch0..7=Postive calibration, Ch8..15=External ADC input)
  -s - (Ch0..15=Negative calibration)
  -s t (Ch0..15=2.5 volt calibration)
  -s e/f (Ch0..7=External ADC input, Ch8..15=5 volt calibration)
  -s e/12 (Ch0..7=External ADC input, Ch8..15=DAC Channel 12)
-v DacVoltage (DAC Voltage. -10.0 to +20.0)
  -v 1.5,9.9 (Ch0..3=1.5 volts, Ch4..15= 9.9 volts)
  -v 2.5/7.5,12.7 (Ch0..3=2.5 volts, 4..7=7.5 volts, 8..15=12.7 volts)
  -v 9.95 (Ch0..15=9.95 volts)
-V OutputRange (Output Voltage range. u10, u20, b5, b10, b20)
  'u10' - Unipolar 10 volts ( +0 --> +10 )
    single_ended/differential
  'u20' - Unipolar 20 volts ( +0 --> +20 )
    single_ended/differential
  'b5' - Bipolar 5 volts ( -5 --> +5 )
```

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```

        single_ended
        'b10' - Bipolar 10 volts ( -10 --> +10 )
        single_ended/differential
        'b20' - Bipolar 20 volts ( -20 --> +20 )
        differential
-V u10,b10      (Ch0..3=UniPolar 10V, Ch4..15=BiPolar 10V)
-Vb5/b10,u20   (Ch0..3=BiPolar 5V, 4..7=BiPolar 10V, 8..15=UniPolar
                20V)
-V b10         (Ch0..15=BiPolar 10V)
-V b20         (Ch0..15=BiPolar 20V - differential)
-Z            (Display Calibration Offset & Gain Channels)

e.g. ./ccurpmfc_dac -os -s7 -Vb5 -v4.5 -E4.5      (Internal Loopback Testing.
                                                    Generate 4.5V and compare)
      ./ccurpmfc_dac -os -se -Vb5 -v4.5 -E4.5     (External DAC/ADC Loopback
                                                    Testing. Generate 4.5V and
                                                    compare)
      ./ccurpmfc_dac -od -s2 -Vb5 -v5.0 -E2.5     (Internal Loopback Testing.
                                                    Generate 5.0V and compare
                                                    diff 2.5V)
      ./ccurpmfc_dac -od -s3 -Vb5 -v5.0 -E-2.5   (Internal Loopback Testing.
                                                    Generate 5.0V and compare
                                                    diff -2.5V)
      ./ccurpmfc_dac -os -sa -Vb5 -v1,2,3,4 -a100 (display all DAC 0..15
                                                    channels with rolling average
                                                    of 100)
      ./ccurpmfc_dac -os -sa -Vb5 -v3.5 -E3.5@0.01 (Internal Loopback Testing.
                                                    Generate 3.5V and compare
                                                    diff on all chans)

```

Example display:

```
./ccurpmfc_dac -A -os -s7 -Vb5 -v4.5 -E4.5
```

```

local_ptr=0x7ffff7fd7000
Physical Memory Information:
  UserPID          =27364
  PhysMemPtr       =0x1c2000
  DriverVirtMemPtr=0xffff88000001c2000
  MmappedUserMemPtr=0x7ffff7fcc000
  PhysMemSize      =0x00001000
  PhysMemSizeFreed=0x00000000
  EntryInTxTbl     =0
  NumOfEntriesUsed=1
Auto Calibration started...done. (2.574 seconds)

Board Number      [-b]: 0
Update Clock Selected [-C]: Ch00..07 OutputClock=0 (0x7)
                  : Ch08..15 OutputClock=0 (0x7)
Delay             [-d]: 0 milli-seconds
DMA Engine        [-D]: 1
Expected Input Volts [-E]: 4.500000 volts (Tolerance 0.006000 volts)
DAC Data Format    [-f]: Ch00..03=Obin Ch04..07=Obin Ch08..11=Obin Ch12..15=Obin
DAC Output Select [-o]: Ch00..03=Sngl Ch04..07=Sngl Ch08..11=Sngl Ch12..15=Sngl
ADC Input Signal  [-s]: Ch00..07 [1]Calibration Input (0x27: DAC Channel 7)
                  : Ch08..15 [1]Calibration Input (0x27: DAC Channel 7)
DAC Voltage       [-v]: Ch00..03=4.50 Ch04..07=4.50 Ch08..11=4.50 Ch12..15=4.50
DAC Voltage Range [-V]: Ch00..03=b5 Ch04..07=b5 Ch08..11=b5 Ch12..15=b5

Loop Count        [-l]: ***Forever***
Number of Channels [-n]: 16
Scan Count        : 35843
Tolerance Exceeded Count : 0 (=== Passed ===)

```

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Read Duration (microsecs) : 20.739 (min= 20.582/max= 34.028/ave= 21.044)

```

##### Raw Data (DAC Channels) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
====
[0] f333 f333 f333 f333 f333 f333 f333 f333 f333 f333
[1] f333 f333 f333 f333 f333 f333

```

```

##### Volts (DAC Channels) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000
[1] +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000

```

```

-----
##### Raw Data (ADC Readback - 4.50v) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
====
0] -- -- -- -- -- -- -- 7ffd -- --
1] -- -- -- -- -- -- --

```

```

##### Volts (ADC Readback - 4.50v) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] --- --- --- --- --- --- --- -0.0005 --- ---
[1] --- --- --- --- --- --- ---

```

```

=====
Date: Mon Oct 25 14:40:18 2017
Expected Input Volts: 4.500000 volts (Tolerance 0.006000 volts)
Tolerance Exceed Count: 0
Scan Counter: 827984

```

```

=====
<----- (volts) ----->
Chan  Min      Max      Ave      TolerExceededCnt
=====
07  -0.0037   0.0020  -0.0008      -
=====

```

./ccurpmfc_dac -C0 -Z

```

local_ptr=0x7ffff7fd7000
Physical Memory Information:
UserPID           =27381
PhysMemPtr        =0x86439000
DriverVirtMemPtr  =0xffff880086439000
MmappedUserMemPtr=0x7ffff7fcc000
PhysMemSize       =0x00001000
PhysMemSizeFreed  =0x00000000
EntryInTxTbl      =0
NumOfEntriesUsed  =1

```

```

Board Number      [-b]: 0
Update Clock Selected [-C]: Ch00..07 OutputClock=0 (0x7) (300000.000 SPS)
                  : Ch08..15 OutputClock=0 (0x7) (300000.000 SPS)
Delay             [-d]: 0 milli-seconds
DMA Engine        [-D]: 1
Expected Input Volts [-E]: === Not Specified ===
DAC Data Format    [-f]: Ch00..03=Obin Ch04..07=Obin Ch08..11=Obin Ch12..15=Obin
DAC Output Select [-o]: Ch00..03=Sngl Ch04..07=Sngl Ch08..11=Sngl Ch12..15=Sngl
ADC Input Signal   [-s]: Ch00..07 [1]Calibration Input (0x20: DAC Channel 0)
                  : Ch08..15 [1]Calibration Input (0x20: DAC Channel 0)

```

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DAC Voltage [-v]: Ch00..03=99.00 Ch04..07=99.00 Ch08..11=99.00 Ch12..15=99.00
 DAC Voltage Range [-V]: Ch00..03=b5 Ch04..07=b5 Ch08..11=b5 Ch12..15=b5
 Loop Count [-l]: ***Forever***
 Number of Channels [-n]: 16
 Scan Count : 36306
 Read Duration (microsecs) : 20.867 (min= 20.605/max= 35.622/ave= 21.058)

```

##### Raw Data (Offset Calibration DAC Channels) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
====
[0] 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000
[1] 0000 0000 0000 0000 0000 0000

```

```

##### Volts (Offset Calibration DAC Channels) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] +0.0000 +0.0000 +0.0000 +0.0000 +0.0000 +0.0000 +0.0000 +0.0000 +0.0000 +0.0000
[1] +0.0000 +0.0000 +0.0000 +0.0000 +0.0000 +0.0000

```

```

-----
##### Raw Data (Gain Calibration DAC Channels) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
====
[0] 0012 0011 0008 0008 0009 000a 0014 0014 000a 000e
[1] 000f 000f 0010 000e 0012 0011

```

```

##### Volts (Gain Calibration DAC Channels) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] +0.0014 +0.0013 +0.0006 +0.0006 +0.0007 +0.0008 +0.0015 +0.0015 +0.0008 +0.0011
[1] +0.0011 +0.0011 +0.0012 +0.0011 +0.0014 +0.0013

```

```

-----
##### Raw Data (DAC Channels) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
====
[0] f333 f333 f333 f333 f333 f333 f333 f333 f333 f333
[1] f333 f333 f333 f333 f333 f333

```

```

##### Volts (DAC Channels) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000
[1] +4.5000 +4.5000 +4.5000 +4.5000 +4.5000 +4.5000

```

```

-----
##### Raw Data (ADC Readback) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
====
[0] f328 -- -- -- -- -- -- -- --
[1] -- -- -- -- -- --

```

```

##### Volts (ADC Readback) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] +4.4983 --- --- --- --- --- --- --- ---
[1] --- --- --- --- --- ---

```

```

=====
Date: Mon Oct 25 14:42:38 2017
Expected Input Volts: === Not Specified ===
Scan Counter: 223036
=====

```

```

<----- (volts) ----->
Chan Min Max Ave TolerExeededCnt

```

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```
=====
00      4.4969      4.5021      4.4997      -
=====
```

3.2.6 lib/ccurpmfc_dac_calibrate

This test is useful for performing, saving and restoring DAC calibration. If calibration '-A' is specified along with voltage '-V', the board voltage range will first be programmed prior to initiating calibration.

Usage: ./ccurpmfc_dac_calibrate [-A] [-b board] [-c ChanMask] [-f DataFormat] [-i inCalFile] [-o outCalFile] [-V MaxBoardVolts]

```
-A                (perform Auto Calibration)
-b <board>        (board #, default = 0)
-c <ChanMask>     (channel selection mask, default = all channels)
-f DataFormat     (select DAC data format, '2' or 'b')
  -f b,2          (Ch0..3=Offset binary, Ch4..15=Two's complement)
  -f 2/b,2        (Ch0..3 & Ch8..15=Two's complement, Ch4..7=Offset binary)
  -f b           (Ch0..15=Offset binary)
-i <In Cal File>  (input calibration file [input->board_reg])
-o <Out Cal File> (output calibration file [board_reg->output])
-V MaxBoardVolts (Voltage range)
  -V u10,b10      (Ch0..3=UniPolar 10V, Ch4..15=BiPolar 10V)
  -Vb5/b10,u20   (Ch0..3=BiPolar 5V, 4..7=BiPolar 10V, 8..15=UniPolar 20V)
  -V b10          (Ch0..15=BiPolar 10V)
```

```
e.g. ./ccurpmfc_dac_calibrate          (Dump calibration information to
                                        stdout)
      ./ccurpmfc_dac_calibrate -A -o Calfile (Perform Auto calibration and dump
                                        information to 'Calfile')
      ./ccurpmfc_dac_calibrate -i Calfile   (Update board calibration with
                                        supplied 'Calfile')
```

Example display:

```
./ccurpmfc_dac_calibrate -A -oOutputCal
```

```
Device Name      : /dev/ccurpmfc0
Board Serial No: 98765 (0x000181cd)
Auto Calibration started...done. (2.527 seconds)
```

```
==> Dump of 'OutputCal' file
#Date            : Wed Jul 12 15:12:06 2017
```

#Chan	Gain	Offset
=====	=====	=====
ch00:	0.0022888183593750	0.0000000000000000
ch01:	0.0022888183593750	0.0000000000000000
ch02:	0.0013732910156250	0.0000000000000000
ch03:	0.0012207031250000	0.0000000000000000
ch04:	0.0010681152343750	0.0000000000000000
ch05:	0.0012207031250000	0.0000000000000000
ch06:	0.0022888183593750	0.0000000000000000
ch07:	0.0022888183593750	0.0000000000000000
ch08:	0.0013732910156250	0.0000000000000000
ch09:	0.0010681152343750	0.0000000000000000
ch10:	0.0018310546875000	0.0000000000000000
ch11:	0.0018310546875000	0.0000000000000000
ch12:	0.0018310546875000	0.0000000000000000
ch13:	0.0015258789062500	0.0000000000000000
ch14:	0.0024414062500000	0.0000000000000000
ch15:	0.0022888183593750	0.0000000000000000

```
==> Board calibration data written to 'OutputCal' file
```

3.2.7 lib/ccurpmfc_dac_setchan

This test generates voltages on various Analog Output channels.

```
Usage: ./ccurpmfc_dac_setchan [-b board] [-c ChannelSelectMask]
      [-C DacUpdateClock] [-D DMAEngine] [-f format] [-i]
      [-l LoopCnt] [-m WriteMode] [-N] [-o OutputSelect]
      [-S NumSamples] [-u UpdateMode] [-v OutputVolts]
      [-V OutputRange] [-w WaveType]

-A          (Perform DAC Auto Calibration first using reference
            voltage)
-b <board>  (board #, default = 0)
-c <ChannelSelectMask> (channel selection mask, default = all channels)
-C DacUpdateClock (select DAC update clock, 0..6 or 's|S')
  -C s        (Ch0..15=Software Update)
  -C 6@20000.0 (Ch0..15=Clock6 at 20000 SPS)
  -C 4        (Ch0..15=Clock4 at MAX SPS)
-D DMA Engine (DMA Engine number -- default = 0)
-f DataFormat (select DAC data format, '2' or 'b')
  -f b,2      (Ch0..3=Offset binary, Ch4..15=Two's complement)
  -f 2/b,2    (Ch0..3 & Ch8..15=Two's complement, Ch4..7=Offset
            binary)
  -f b        (Ch0..15=Offset binary)
-i          (Enable Interrupts -- default = Disable)
-l LoopCnt  (Loop count -- default is 0)
-m <WriteMode> (Write Mode)
  -mdp      (Driver: (Channel Registers) PIO mode)
  -mlc     (Library: (Channel Registers) program I/O Fast Memory
            Copy)
  -mld     (Library: (Channel Registers) DMA mode)
  -mlp     (Library: (Channel Registers) PIO mode)
  -mup     (User: (Channel Registers) PIO mode)
  -mdP     (Driver: (FIFO) PIO mode)
  -mLD     (Library: (FIFO) DMA mode)
  -mlP     (Library: (FIFO) PIO mode)
-N          (Open device with O_NONBLOCK flag for driver operations)
-o OutputSelect (DAC output select, 's' or 'd')
  -o d,s    (Ch0..3=differential, Ch4..15=single_ended)
  -o s/d,s  (Ch0..3 & Ch8..15=single_ended, Ch4..7=differential)
  -o d      (Ch0..15=differential)
-S <NumSamples> (Number of Samples per channel, default = 512)
-u          (Set DAC Update Mode)
  -ui      (Set DAC Update Mode to Immediate Mode)
  -us      (Set DAC Update Mode to Synchronized Mode)
-v DacVoltage (DAC Voltage. -10.0 to +20.0)
  -v 1.5,9.9 (Ch0..3=1.5 volts, Ch4..15= 9.9 volts)
  -v 2.5/7.5,12.7 (Ch0..3=2.5 volts, 4..7=7.5 volts, 8..15=12.7 volts)
  -v 9.95    (Ch0..15=9.95 volts)
-V OutputRange (Output Voltage range. u10, u20, b5, b10, b20)
  'u10' - Unipolar 10 volts ( +0 --> +10 )
         single_ended/differential
  'u20' - Unipolar 20 volts ( +0 --> +20 )
         single_ended/differential
  'b5'  - Bipolar 5 volts ( -5 --> +5 )
         single_ended
  'b10' - Bipolar 10 volts ( -10 --> +10 )
         single_ended/differential
  'b20' - Bipolar 20 volts ( -20 --> +20 )
         differential
  -V u10,b10 (Ch0..3=UniPolar 10V, Ch4..15=BiPolar 10V)
  -V b5/b10,u20 (Ch0..3=BiPolar 5V, 4..7=BiPolar 10V, 8..15=UniPolar
            20V)
  -V b10     (Ch0..15=BiPolar 10V)
  -V b20     (Ch0..15=BiPolar 20V - differential)
```

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```

-w <WaveType>          (default = 'c' Constant Voltage)
-wc                    (Constant Voltage)
-wu                    (Saw Wave (up))
-wd                    (Saw Wave (down))
-ws                    (Sine Wave)
-wx                    (Square Wave)
-wy                    (Step Wave (down))
-wz                    (Step Wave (up))
-wt                    (Triangle Wave)
-ww                    (All Wave (Sine/Square/StepUp/Triangle/StepDown))

```

```

e.g. ./ccurpmfc_dac_setchan -od,s,d,s -v20,10,5,1 -wx -mdP -Vb20 (dac0&2
                                     differential, dacl&3 single_ended)
     ./ccurpmfc_dac_setchan -ws -ui -od (sine wave,
                                     immediate)

```

Example display:

```
./ccurpmfc_dac_setchan -ws -ui -od
```

```

Device Name      : /dev/ccurpmfc0
Physical Memory Information:
  UserPID        =29005
  PhysMemPtr     =0x86b10000
  DriverVirtMemPtr=0xffff880086b10000
  MmappedUserMemPtr=0x7ffff7fbc000
  PhysMemSize    =0x00008000
  PhysMemSizeFreed=0x00000000
  EntryInTxTbl   =0
  NumOfEntriesUsed=1

DAC 0....
  State = 0x0 (Idle)
  Power Down = 0x0 (Operational)
  Update Mode = 0x0 (Immediate)
  Data Format = 0x0 (Offset Binary)
  Output Select = 0x1 (Differential)
  Output Range = 0x1 (Unipolar 10 Volts - Differential)
DAC 1....
  State = 0x0 (Idle)
  Power Down = 0x0 (Operational)
  Update Mode = 0x0 (Immediate)
  Data Format = 0x0 (Offset Binary)
  Output Select = 0x1 (Differential)
  Output Range = 0x1 (Unipolar 10 Volts - Differential)
DAC 2....
  State = 0x0 (Idle)
  Power Down = 0x0 (Operational)
  Update Mode = 0x0 (Immediate)
  Data Format = 0x0 (Offset Binary)
  Output Select = 0x1 (Differential)
  Output Range = 0x1 (Unipolar 10 Volts - Differential)
DAC 3....
  State = 0x0 (Idle)
  Power Down = 0x0 (Operational)
  Update Mode = 0x0 (Immediate)
  Data Format = 0x0 (Offset Binary)
  Output Select = 0x1 (Differential)
  Output Range = 0x1 (Unipolar 10 Volts - Differential)

Write Mode: -mdp: Driver: (CHANNEL) PIO Mode
Generating a continuous Sine Wave on selected channels: <CTRL-C> to abort
Voltage Selection: 10.00/10.00/10.00/10.00, Channel Mask Selection: 0xffff,
Samples/Write=512

```

9.587 usec/write: 5.093 msec period, 196.343 Hz

3.2.8 lib/ccurpmfc_dio

This test generates, views and tests various digital channels.

```
Usage: ./ccurpmfc_dio [-b BoardNo] [-d Delay] [-F DebugFile] [-l LoopCnt]
                    [-m DIOMode] [-n NumChans] [-p PatternSelect]
                    [-r RunOption] [-s SkipChannelsMask]

-b BoardNo          (Board number -- default is 0)
-d Delay            (Delay between screen refresh -- default is 100)
-F DebugFile        (Debug file -- default "=== None ===")
-l LoopCnt          (Loop count -- default is 0)
-m DIOMode          (DIO mode -- default is 1)
  -m0               (DIO Custom mode)
  -m1               (DIO Normal mode)
-n NumChans         (number of channels -- default is 96)
-p PatternSelect    (DIO mode -- default is to sequence through all
                    patterns)
  -p0               (Rolling Ones)
  -p1               (Rolling Zeros)
  -p2               (Adding Bit)
  -p3               (Toggling 'A' & '5')
  -p@XXXXXXXXXX     (Fixed Pattern XXXXXXXXX selection in Hex)
-r RunOption        (Run option -- default is 0)
  -rd               (Digital Isolators Test)
  -rD               (Fast [no curses] Digital Isolators Test)
  -ri               (Read DIO input channels)
  -rl               (Internal Loopback DIO test)
  -rL               (Fast [no curses] internal loopback DIO test)
  -re               (External Loopback DIO test)
  -rE               (Fast [no curses] external loopback DIO test)
  -ro               (Write pattern to DIO output channels)
-s SkipChannelsMask (Skip channels mask -- default is 0@0x00000000
                    1@0x00000000 2@0x00000000)
  -s0@XXXXXXXXXX    (Channels 31..00=XXXXXXXX in Hex)
  -s1@XXXXXXXXXX    (Channels 63..32=XXXXXXXX in Hex)
  -s2@XXXXXXXXXX    (Channels 95..64=XXXXXXXX in Hex)
e.g. ./ccurpmfc_dio -rl -s1@ffffffff (Internal Loopback Testing. Skip Channels
                                     32-63)
     ./ccurpmfc_dio -rE -s2@ffffffff (External Loopback w/o Curses Testing. Skip
                                     Channels 64-95)
```

Example display:

```
./ccurpmfc_dio -rl -s1@FFFFFFFF
```

In this example we are performing an internal loopback test. In this case, none of the DIO channels should be connected to any external lines, otherwise, the test will fail.

```
Board Number      [-b]: 0
Delay              [-d]: 100 milli-seconds
Loop Count        [-l]: ***Forever***
DIO Mode          [-m]: 0x00000001 (DIO Normal Mode)
Number of Channels [-n]: 96
Pattern Selection [-p]: 2 (Adding Bit)
Run Option        [-r]: 2 (Internal Loopback Test)
Skip Channels Mask [-s]: 31..0=00000000, 63..32=FFFFFFFF, 95..64=00000000
Custom Channels Mask : 31..0=00000000, 63..32=00000000, 95..64=00000000
Channel Mismatch Count : 0 (=== Passed ===)
DIO Direction     : 0xFFFFFFFF (All Output)
DIO Enable        : 0x00000001 (Enable)
```

```

Input Snapshot          : 0x00000001 (Snapshot)
Scan Count              : 183

Write Duration (microsecs) : 1.396 (min= 1.330/max= 1.660/ave= 1.378)
Read Duration (microsecs) : 3.687 (min= 3.562/max= 3.771/ave= 3.683)

```

```

Channels      Output      Input
=====
31..00 [0]: FFFFFFFF FFFFFFFF
63..32 [1]: 00000000 00000000
95..64 [2]: 003FFFFF 003FFFFF

```

```

<----- Input Channels ----->
      [0]  [1]  [2]  [3]  [4]  [5]  [6]  [7]  [8]  [9]
      ===  ===  ===  ===  ===  ===  ===  ===  ===  ===
[0]    +    +    +    +    +    +    +    +    +    +
[1]    +    +    +    +    +    +    +    +    +    +
[2]    +    +    +    +    +    +    +    +    +    +
[3]    +    +    skip skip skip skip skip skip skip skip
[4]  skip skip skip skip skip skip skip skip skip skip
[5]  skip skip skip skip skip skip skip skip skip skip
[6]  skip skip skip skip    +    +    +    +    +    +
[7]    +    +    +    +    +    +    +    +    +    +
[8]    +    +    +    +    +    +    .    .    .    .
[9]    .    .    .    .    .    .

```

(** Enter <CONTROL-C> to Terminate **)

```

local_ptr=0x7ffff7fd7000
AvalonPtr=0x7ffff7fd7000

```

=== Test Passed ===

3.2.9 lib/ccurpmfc_dio_intr

This test is used to validate the DIO change-of-state interrupt detection.

```

Usage: ./ccurpmfc_dio_intr [-b Board] [-d Delay] [-F FallCh] [-l LoopCnt]
      [-L LevelCh] [-R RiseCh] [-X DeleteCh]

```

```

-b <board>          (board #, default = 0)
-d Delay            (Delay between screen refresh -- default is 0
                   milli-seconds)
-F FallCh           (Falling Edge Channel_List)
-l LoopCnt          (Loop count -- default is 0)
-L LevelCh          (Level State Channel_List)
-R RiseCh           (Rising Edge Channel_List)
-X DeleteCh         (Delete COS Channel_List)

```

Examples of Channel_List. Unchanged channels default to Level State Channels:

```

-F -                (set all DIO channels to falling edge)
-R 1,2,7,9          (set channels 1,2,7,9 to rising edge, rest are level state)
-X 5,7-12           (delete channels 5, and 7 to 12. rest are level state)

```

Example display:

In the example below, a signal generator is connected to digital input channels 0, 1, 32 and 64. A 15 KHz, +5/0 volts square wave is injected into the selected channels. The test is run using shielding and directing to CPU 4 and 5 and driver interrupt directed to CPU 2. The reason the display shows approximately 30 KHz rate is because the test defaults to performing level detection, i.e. detecting both rising and falling edge on all channels. Depending on other activities in the system, it is possible to see some Overflow conditions.

In order to run at such high rates without getting overflow or missing user callbacks requires proper shielding and real time running of the test. Additionally, the driver interrupt handler needs to be directed to a dedicated processor in order to minimize overflows. E.g.

```
# === as root ===
# shield -a 2, 4-5                (shield processors 2, 4 and 5)
# cat /proc/ccurpmfc              (get board irq - in this case it is 'irq=56')
# echo 4 > /proc/irq/56/smp_affinity (direct board irq to be handled by processor 2)
# (if irq '56' is not present in the proc/irq directory, then you will need to start the test at least once to get it
  assigned by the kernel)
# run -b4-5 ./ccurpmfc_dio_intr
```

```
0001303506 - COS Interrupt Duration (usec):      34.89 min=22.65 max=44.09
                                                run_ave=33.24 (30081.28 Hz)
Driver Interrupt Response Time (usec):          17.96 min=15.79 max=27.27
                                                run_ave=16.72
```

```
DIO COS Enable (Ch95..0): 0xffffffff 0xffffffff 0xffffffff
DIO COS Mode (Ch95..0): 0x00000000 0x00000000 0x00000000
DIO COS Edge Sense (Ch95..0): 0x00000000 0x00000000 0x00000000
DIO COS Status (Ch95..0): 0x00000001 0x00000001 0x00000003
DIO COS OVFL Status (Ch95..0): 0x00000000 0x00000000 0x00000000
Interrupts Occurred Mask: 0x00001c00
Wakeup Interrupt Mask: 0x00001c00
```

```
Total DIO Interrupts Count:      6520825
User Callback Count:              6520825
Missed User Callback Count:       0
DMA Counts (dma0..0):             0 0
DIO COS Counts (group2..0):      6520825 6520825 6520825
Overflow DIO COS Counts (group2..0): 0 0 0
```

```
<----- Channels COS Status Count ('+' Rise, '-' Fall, '.' Level, 'NC' No COS) ----->
      [0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] 6520825. 6520825. 0. 0. 0. 0. 0. 0. 0. 0.
[1] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[2] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[3] 0. 0. 6520825. 0. 0. 0. 0. 0. 0. 0.
[4] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[5] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[6] 0. 0. 0. 0. 6520825. 0. 0. 0. 0. 0.
[7] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[8] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[9] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
```

```
<----- Channels COS Overflow Count ('+' Rise, '-' Fall, '.' Level, 'NC' No COS) ----->
      [0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[1] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[2] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[3] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[4] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[5] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[6] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[7] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[8] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
[9] 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
```

(*** Enter <CONTROL-C> to Terminate ***)

Rising Edge[-r]: ### No Channels Selected ###

```
Falling Edge[-f]: ### No Channels Selected ###
Level State[-l]: Number of Channels = 96
 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24
25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49
50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74
75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95
Disable COS[-x]: ### No Channels Selected ###
```

```
driver_lib_ptr: 0x7ffff7fdd000
Deactivate DIO
WakeupInterruptMask = 0x00001c00
Activate DIO
### Test Terminated ###
```

```
Destroying User COS Interrupt Handler
```

```
./ccurpmfc_dio_intr -F0,32 -R64
```

In this example, we are detecting the falling edge for channels 0 and 32, rising edge for channel 64 and level detection for the rest of the channels. This is why you will see the count for channel 1 (level detection) double that of channels 0, 32 and 64.

```
0001236827 - COS Interrupt Duration (usec):      32.88 min=20.72 max=46.17
                                                run_ave=33.24 (30080.95 Hz)
Driver Interrupt Response Time (usec):          12.86 min=12.63 max=25.93
                                                run_ave=13.38
```

```
DIO COS Enable (Ch95..0): 0xffffffff 0xffffffff 0xffffffff
DIO COS Mode (Ch95..0): 0x00000001 0x00000001 0x00000001
DIO COS Edge Sense (Ch95..0): 0x00000001 0x00000000 0x00000000
DIO COS Status (Ch95..0): 0x00000001 0x00000001 0x00000002
DIO COS OVFL Status (Ch95..0): 0x00000000 0x00000000 0x00000000
Interrupts Occurred Mask: 0x00001400
Wakeup Interrupt Mask: 0x00001c00
```

```
Total DIO Interrupts Count:      6684258
User Callback Count:              6684258
Missed User Callback Count:       0
DMA Counts (dma0..0):             0      0
DIO COS Counts (group2..0):       3342129 3342129 6684258
Overflow DIO COS Counts (group2..0): 0      0      0
```

	Channels		COS	Status	Count	('+' Rise, '-' Fall, '.' Level, 'NC' No COS)				
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]
[0]	3342129-	6684258.	0.	0.	0.	0.	0.	0.	0.	0.
[1]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[2]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[3]	0.	0.	3342129-	0.	0.	0.	0.	0.	0.	0.
[4]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[5]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[6]	0.	0.	0.	0.	3342129+	0.	0.	0.	0.	0.
[7]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[8]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[9]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.

	Channels		COS	Overflow	Count	('+' Rise, '-' Fall, '.' Level, 'NC' No COS)				
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]
[0]	0-	0.	0.	0.	0.	0.	0.	0.	0.	0.
[1]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[2]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[3]	0.	0.	0-	0.	0.	0.	0.	0.	0.	0.
[4]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[5]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[6]	0.	0.	0.	0.	0+	0.	0.	0.	0.	0.
[7]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[8]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
[9]	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.

```

(***) Enter <CONTROL-C> to Terminate (***)

Rising Edge[-r]: Number of Channels = 1
64
Falling Edge[-f]: Number of Channels = 2
0 32
Level State[-l]: Number of Channels = 93
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25
26 27 28 29 30 31 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51
52 53 54 55 56 57 58 59 60 61 62 63 65 66 67 68 69 70 71 72 73 74 75 76 77
78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95
Disable COS[-x]: ### No Channels Selected ###

driver_lib_ptr: 0x7ffff7fdd000
Deactivate DIO
WakeupInterruptMask = 0x00001c00
Activate DIO
### Test Terminated ###

```

3.2.10 lib/ccurpmfc_disp

Useful program to display the local board registers. This program uses the *curses* library. This test is similar to the previous non-library test.

```

Usage: ./ccurpmfc_disp [-b Board] [-d Delay] [-D DMAEngineNo] [-H] [-i]
                    [-l LoopCnt] [-m XferMode] [-o Offset] [-P Pause]
                    [-s XferSize] [-S DispSize]

-b Board           (Board number -- default board is 0)
-d Delay           (Delay between screen refresh -- default is 0)
-D DMAEngineNo    (DMA Engine number -- default = 1)
-H                (Enable Hyper-Drive Mode -- default "=== Disabled ===")
-i                (Enable Interrupts -- default = Disable)
-l LoopCnt        (Loop Count - default = 0)
-m XferMode       (Transfer Mode -- default = DMA)
  -md             (Avalon Memory: DMA mode)
  -mm             (Avalon Memory: Modular Scatter-Gather DMA mode)
  -mp             (Avalon Memory: Programmed I/O mode)
  -mS             (SDRAM Memory: DMA mode)
  -ms             (SDRAM Memory: Programmed I/O mode)
-o Offset         (Hex offset to read from -- default is 0x0)
-P Pause          (Microseconds to sleep in User Function loop -- default is 0)
-s XferSize       (Number of bytes to transfer -- default is 0x1000)
-S DispSize       (Number of bytes to display -- default is 0x200)

```

Example display:

```

./ccurpmfc_disp

local_ptr=0x7ffff7fe7000
Physical Memory Information:
  UserPID           =18944
  PhysMemPtr        =0x79a50000
  DriverVirtMemPtr=0xffff880079a50000
  MmappedUserMemPtr=0x7ffff7fdc000
  PhysMemSize       =0x00001000
  PhysMemSizeFreed=0x00000000
  EntryInTxTbl      =0
  NumOfEntriesUsed=1
-----
Board Number       [-b]: 0
Delay              [-d]: 0 milli-seconds
DMA Engine         [-D]: 1

```



```

Hyper-Drive          [-H]: Disabled
Interrupts           [-i]: Disabled
Loop Count           [-l]: ***Forever***
Transfer Mode        [-m]: DMA I/O (Avalon Memory)
Offset               [-o]: 0x00000000
Transfer Size        [-s]: 0x00001000 (4096) bytes ( 21.283 MBytes/Second)
Display Size         [-S]: 0x00000200 (512) bytes

ScanCount            : 12029
Read Duration (microsecs) : 192.451 (min= 192.276/max= 262.459/ave= 192.733)

      00      04      08      0C      10      14      18      1C
=====
000000  92900101 05252016 00550003 00000000 00000000 00000000 00000000 00000000
000020  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
000040  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
000060  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
000080  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
0000a0  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
0000c0  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
0000e0  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
000100  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
000120  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
000140  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
000160  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
000180  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
0001a0  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
0001c0  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
0001e0  00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000

```

3.2.11 lib/ccurpmfc_dma

This test transfers data from physical memory to the Local register area and back. There are two modes of operation. One is DMA and the other is programmed I/O. Depending on the number of DMA engines supported by the card, the user can select one of them to perform the DMA. Area select is one of three areas the user can specify. They represent the area in physical memory and local register where the transfer is to occur. The test automatically switches to a different area corresponding to the DMA engine supplied. If multiple copies of this application is run on the same card using the same DMA engine, then the user needs to manually select a different area '-A' so the data mismatch does not occur due to using the same area region.

```

Usage: ./ccurpmfc_dma [-A Area2Select] [-b Board] [-D DMAEngineNo] [-i]
      [-l LoopCnt] [-m XferMode] [-s Size] [-v VerboseNo]
-A Area2Select (Area to select -- default = -1)
-b Board      (Board number -- default = 0)
-D DMAEngineNo (DMA Engine number -- default = 0)
-i           (Enable Interrupts -- default = Disable)
-l LoopCnt   (Loop Count - default = 1000)
-m XferMode  (Transfer Mode -- default = DMA)
  -md       (DMA mode)
  -mp       (Programmed I/O mode)
-s Size      (Transfer Size in bytes (multiple of byte width) -
             default = 12288)
-V VerboseNo (verbose -- default = 0)

e.g. ./ccurpmfc_dma -A1 (perform dma using DMA0 on area 1 )
     ./ccurpmfc_dma -i -D1 (perform dma using DMA1 with interrupts on area 0)

```

Example display:

```

./ccurpmfc_dma

Device Name: /dev/ccurpmfc0

```

```

local_ptr=0x7ffff7fe7000
      Physical Memory Information:
      UserPID           =18950
      PhysMemPtr        =0x5ea00000
      DriverVirtMemPtr  =0xffff88005ea00000
      MmappedUserMemPtr=0x7ffff70f4000
      PhysMemSize       =0x00200000
      PhysMemSizeFreed  =0x00000000
      EntryInTxTbl      =0
      NumOfEntriesUsed  =2
### Avalon Address[A0]: 0x00001000 - 0x00004000
###   DMA Address[A0]: 0x00100400 - 0x00103400
###   Transfer Size: 12288 (0x00003000) bytes (DMA without Interrupts: DMA
      Engine 0) ###
1000: A2P: Total: 566.852us ( 21.68 MB/s): first=0xface0000 last=0xface0bff

```

	(micro-seconds)			(MBytes/second)		
	Min	Max	Ave	Min	Max	Ave
P2A:	514.18	523.39	516.20	23.48	23.90	23.80
A2P:	566.28	594.08	567.11	20.68	21.70	21.67

3.2.12 lib/ccurpmfc_example

This test provides a simple example of programming ADC, DAC and DIO.

```

Usage: ./ccurpmfc_example [-b Board]
      -b Board      (Board number -- default is 0)

```

Example display:

./ccurpmfc_example (for card *without* Modular Scatter-Gather DMA)

```

local_ptr=0x7ffff7fe7000
      Physical Memory Information:
      UserPID           =18954
      PhysMemPtr        =0x8566b000
      DriverVirtMemPtr  =0xffff88008566b000
      MmappedUserMemPtr=0x7ffff7fdb000
      PhysMemSize       =0x00001000
      PhysMemSizeFreed  =0x00000000
      EntryInTxTbl      =1
      NumOfEntriesUsed  =1
### Configuring ADC ###
- Activate ADC
- Configure ADC
- Calibrate ADC
### Configuring DAC ###
- Activate DAC
- Select Software Update
- Configure DAC
- Write 0 to DAC outputs
- Make DAC operational
- Calibrate DAC
### Programming Clocks ###
### Reading ADC Channels ###

==== ADC Channels ==== (length=64)
+DMP+      0  0000ffff  00000001  0000ffff  0000ffff  *.....*
+DMP+     0x10 00000000  00000000  00000000  00000000  *.....*
+DMP+     0x20 00000000  0000ffff  0000ffff  00000000  *.....*
+DMP+     0x30 0000ffff  0000ffff  0000ffff  00000000  *.....*
### Writing DAC Channels ###

```

```

DacCh00: 0x00000000 (0.000000 volts)
DacCh01: 0x00000666 (0.499878 volts)
DacCh02: 0x00000ccc (0.999756 volts)
DacCh03: 0x00001333 (1.499939 volts)
DacCh04: 0x00001999 (1.999817 volts)
DacCh05: 0x00002000 (2.500000 volts)
DacCh06: 0x00002666 (2.999878 volts)
DacCh07: 0x00002ccc (3.499756 volts)
DacCh08: 0x00003333 (3.999939 volts)
DacCh09: 0x00003999 (4.499817 volts)
DacCh10: 0x00004000 (5.000000 volts)
DacCh11: 0x00004666 (5.499878 volts)
DacCh12: 0x00004ccc (5.999756 volts)
DacCh13: 0x00005333 (6.499939 volts)
DacCh14: 0x00005999 (6.999817 volts)
DacCh15: 0x00006000 (7.500000 volts)
### Configuring DIO ###
- Activate DIO
- Set DIO for normal mode
- Set DIO output sync mode
- Set DIO input snapshot mode
- Set DIO ports direction
### Reading DIO Channels 00..47 ###
CCURPMFC_DIO_CHAN_00_31=0xaaaaaaaaab
CCURPMFC_DIO_CHAN_32_63=0x0000aaab
### Writing DIO Channels 48..95 ###
CCURPMFC_DIO_CHAN_32_63=0xbabe0000
CCURPMFC_DIO_CHAN_64_95=0xfeedface

```

`./ccurpmfc_example` (for card *with* Modular Scatter-Gather DMA)

```

local_ptr=0x7ffff7fd7000
Physical Memory Information:
  UserPID           =21311
  PhysMemPtr        =0x35266000
  DriverVirtMemPtr  =0xffff880035266000
  MmappedUserMemPtr=0x7ffff7fcb000
  PhysMemSize       =0x00001000
  PhysMemSizeFreed  =0x00000000
  EntryInTxTbl      =1
  NumOfEntriesUsed  =1
### Configuring ADC ###
- Activate ADC
- Configure ADC
- Calibrate ADC
### Configuring DAC ###
- Activate DAC
- Select Software Update
- Configure DAC
- Write 0 to DAC outputs
- Make DAC operational
- Calibrate DAC
### Programming Clocks ###
### Reading ADC Channels ###

==== ADC Channels ==== (length=64)
+DMP+      0  0000fffd  0000ffff  0000ffff  00000000  *.....*
+DMP+     0x10 00000000  00000000  0000ffff  00000000  *.....*
+DMP+     0x20 0000ffff  00000000  0000ffff  0000ffff  *.....*
+DMP+     0x30 00000000  0000ffff  00000000  0000ffff  *.....*
### Writing DAC Channels ###
DacCh00: 0x00000000 (0.000000 volts)
DacCh01: 0x00000666 (0.499878 volts)

```

```

DacCh02: 0x00000ccd (1.000061 volts)
DacCh03: 0x00001333 (1.499939 volts)
DacCh04: 0x0000199a (2.000122 volts)
DacCh05: 0x00002000 (2.500000 volts)
DacCh06: 0x00002666 (2.999878 volts)
DacCh07: 0x00002ccd (3.500061 volts)
DacCh08: 0x00003333 (3.999939 volts)
DacCh09: 0x0000399a (4.500122 volts)
DacCh10: 0x00004000 (5.000000 volts)
DacCh11: 0x00004666 (5.499878 volts)
DacCh12: 0x00004ccd (6.000061 volts)
DacCh13: 0x00005333 (6.499939 volts)
DacCh14: 0x0000599a (7.000122 volts)
DacCh15: 0x00006000 (7.500000 volts)
### Configuring DIO ###
- Activate DIO
- Set DIO for normal mode
- Set DIO output sync mode
- Set DIO input snapshot mode
- Set DIO ports direction
### Reading DIO Channels 00..47 ###
- CCURPMFC_DIO_CHAN_00_31=0x00000000
- CCURPMFC_DIO_CHAN_32_63=0x00000000
### Writing DIO Channels 48..95 ###
- CCURPMFC_DIO_CHAN_32_63=0xbabe0000
- CCURPMFC_DIO_CHAN_64_95=0xfeedface
### Single (one descriptor) Modular Scatter-Gather DMA ###
- Configure Single MSGDMA (PCIE ==> Avalon)
- Fire Single MSGDMA: Xfer 0x8000 bytes: Pcie ==> Avalon (@0x8000)
- Validating data
- Configure Single MSGDMA (Avalon ==> PCIE)
- Fire Single MSGDMA: Xfer 0x8000 bytes: Avalon (@0x8000) ==> PCIE
- Validating data
### Multi (four descriptor) Modular Scatter-Gather DMA ###
- Allocating memory and seeding with pattern)
- Configure multi MSGDMA (PCIE ==> Avalon ==> PCIE ==> Avalon ==> PCIE)
- Setup Multi MSGDMA
- Fire Multi MSGDMA
- Validating data

```

3.2.13 lib/ccurpmfc_expires

This test is useful in displaying board expires information.

```

Usage: ./ccurpmfc_expires -[b Board] -[s]
        -b <board>                (board #, default = 0)
        -s                          (short display, default = verbose)

```

Example display:

`./ccurpmfc_expires` (for card that has no restrictions)

```

Device Name: /dev/ccurpmfc0
Board Serial No: 98765 (0x000181cd)

```

```

#####
###                               ###
###          UNRESTRICTED FIRMWARE          ###
###                               ###
#####

```

`./ccurpmfc_expires` (for restricted card that has NO expiration date)

```
Device Name: /dev/ccurpmfc0
Board Serial No: 98765 (0x000181cd)
```

```
#####
###
###          RESTRICTED FIRMWARE      ###
###          ###
#####
```

```
=====
=== No Expiration Date ===
=====
```

`./ccurpmfc_expires` (for restricted card that has expiration date)

```
Device Name: /dev/ccurpmfc0
Board Serial No: 98765 (0x000181cd)
```

```
#####
###
###          RESTRICTED FIRMWARE      ###
###          ###
#####
```

```
=====
Local Expiration Date: 03/11/2018 13:21:52
GMT Expiration Date: 03/11/2018 17:21:52
Duration to Expire: Days=122, Hours=2, Minutes=49, Seconds=20
=====
```

`./ccurpmfc_expires -s` (for card that has no restrictions)

Unrestricted

`./ccurpmfc_expires -s` (for restricted card that has NO expiration date)

Restricted: No expiration date

`./ccurpmfc_expires -s` (for restricted card that has expiration date)

Restricted: Expire in 10550462 seconds

3.2.14 lib/ccurpmfc_identify

This test is useful in identifying a particular card by displaying its LED.

```
Usage: ./ccurpmfc_identify -[bsx]
        -b <board>          (board #, default = 0)
        -s <seconds>        (seconds to sleep, default = 10)
        -s 0                (Identify Board: DISABLE)
        -s <negative value> (Identify Board: ENABLE forever)
        -x                  (silent)
```

Example display:

`./ccurpmfc_identify`

```
Device Name   : /dev/ccurpmfc0
Board ID      : 9290
Board Type    : 01
```

```
Board Function : 01
Board Serial No: 98765 (0x000181cd)
```

```
Identify ENABLED on board 0 (LED should start flashing)
Sleeping for 10 seconds...done
Identify DISABLED on board 0 (LED should stop flashing)
```

3.2.15 lib/ccurpmfc_info

This test is useful in getting information for all the *ccurpmfc* devices in the system.

```
Usage: ./ccurpmfc_info -[b Board] -[l] -[v]
       -b <board>          (board #, default = 0)
       -l                  (long display, default = short)
       -v                  (long display and verbose, default = no verbose)
       -l -v               (long display and verbose, default = no verbose)
```

Example display:

```
./ccurpmfc_info
```

```
# IRQ MSI Bu:Sl:Fn VnID:Sub BdID:Ty:Fu:Sub FMaj.Min(mm:dd:yy hh:mm:ss) MC FmFlvCod IPCores
                               Temp:C/F SerialNo RLS# Func
0  57  Y  05:00:00 1542:1542 9290.00.10:0100 0001.0001(10/25/17 03:00:30) ?? babeface 8
                               55/131.0 668603 100 EnginCtrl
1  58  Y  06:00:00 1542:1542 9290.01.01:0100 0003.0002(10/14/16 00:00:00) A5 00000000 0
                               55/131.0 11223344 100 MultiFunc
```

```
./ccurpmfc_info -l
```

```
##### Board 0 #####
Version: 23.0.3
Build: Thu Jun 21 10:23:45 EDT 2018
Module: ccurpmfc
Board Index: 0 (PCIe-CCUR_FPGA_PMFC)
Bus: 0x05
Slot: 0x00
Func: 0x00
Vendor ID: 0x1542
Sub-Vendor ID: 0x1542
Board Info: 0x92900010 (id=9290, type=0x00, func=0x10 (EnginCtrl))
Member Code: 0 (??)
Sub-Device ID: 0x0100
Firmware Date/Time: 0x10252017 0x00030030 (10/25/2017 03:00:30)
Firmware Revision: 0x00010001 (0001.0001)
Firmware Flavor Code: 0xbabeface (3133078222) (****)
Number of Advanced IP Cores: 0x00000008 (8)
Board Serial Number: 0x000a33bb (668603)
Board SPROM Revision: 0x0000 (0)
FPGA Chip Temperature: 0x38 (56 degree C, 132.8 degree F)
Run Level Sector Number: 0x64 (100)
Multi-Firmware Support: 0x1 (Yes)
MSI Support: Enabled
Scatter-Gather DMA Support: Yes
Number of MSG DMA Descriptors: 31
Double-Word Support: No
IRQ Level: 57
Calibration Reference: 9.91 Volts

##### Board 1 #####
Version: 23.0.3
Build: Thu Jun 21 10:23:45 EDT 2018
Module: ccurpmfc
Board Index: 0 (PCIe-CCUR_FPGA_PMFC)
Bus: 0x06
Slot: 0x00
```

```

Func: 0x00
Vendor ID: 0x1542
Sub-Vendor ID: 0x1542
Board Info: 0x92900101 (id=9290, type=0x01, func=0x01 (MultiFunc))
Member Code: 1 (A5)
Sub-Device ID: 0x0100
Firmware Date/Time: 0x10142016 0x00000000 (10/14/2016 00:00:00)
Firmware Revision: 0x00030002 (0003.0002)
Firmware Flavor Code: 0x00000000 (0) (****)
Number of Advanced IP Cores: 0x00000000 (0)
Board Serial Number: 0x00ab4130 (11223344)
Board SPROM Revision: 0x0000 (0)
FPGA Chip Temperature: 0x38 (56 degree C, 132.8 degree F)
Run Level Sector Number: 0x64 (100)
Multi-Firmware Support: 0x1 (Yes)
MSI Support: Enabled
Scatter-Gather DMA Support: No
Double-Word Support: Yes
IRQ Level: 58
Calibration Reference: 9.91 Volts

```

./ccurpmfc_info -l -v

```

##### Board 0 #####
Version: 23.0.3
Build: Thu Jun 21 10:23:45 EDT 2018
Module: ccurpmfc
Board Index: 0 (PCIe-CCUR_FPGA_PMFC)
Bus: 0x05
Slot: 0x00
Func: 0x00
Vendor ID: 0x1542
Sub-Vendor ID: 0x1542
Board Info: 0x92900010 (id=9290, type=0x00, func=0x10 (EnginCtrl))
Member Code: 0 (??)
Sub-Device ID: 0x0100
Firmware Date/Time: 0x10252017 0x00030030 (10/25/2017 03:00:30)
Firmware Revision: 0x00010001 (0001.0001)
Firmware Flavor Code: 0xbabeface (3133078222) (****)
Number of Advanced IP Cores: 0x00000008 (8)
Board Serial Number: 0x000a33bb (668603)
Board SPROM Revision: 0x0000 (0)
FPGA Chip Temperature: 0x38 (56 degree C, 132.8 degree F)
Run Level Sector Number: 0x64 (100)
Multi-Firmware Support: 0x1 (Yes)
MSI Support: Enabled
Scatter-Gather DMA Support: Yes
Number of MSG DMA Descriptors: 31
Double-Word Support: No
IRQ Level: 57
Calibration Reference: 9.91 Volts

```

```

---ADC Information---
Maximum Voltage Range: 10 Volts
Number of ADCs: 2
Number of ADC Channels: 16
Number of ADC Resolution: 16 Bits
All ADC Channels Mask: 0x0000ffff
Maximum ADC Fifo Threshold: 0x00020000

```

```

---DAC Information---
Maximum Voltage Range: 20 Volts
Number of DACs: 4
Number of DAC Channels: 16
Number of DAC Resolution: 16 Bits
All DAC Channels Mask: 0x0000ffff

```

```

---DIO Information---
Number of DIO Channels: 96
Number of DIO Ports: 24
Number of DIO Channels/Port: 4

```

Number of DIO Registers: 3
Number of DIO Channels/Register: 32

```
---DMA Information---
  Driver DMA Size: 524288
  Num of Trans Tbl Entries: 8
  Avalon Page Bits: 20
  Avalon Page Size: 1048576
  TX Interface Base: 8388608
  DMA Maximum Engines: 2
  DMA Maximum Burst Size: 1024
  DMA Maximum Transactions: 32
  DMA Maximum Size: 1048576
  DMA Width in Bytes: 4
  DMA Fire Command: 140

---Analog/DMA Interrupt Information---
  Interrupt Count: 0
  DMA 0 Count: 0
  DMA 1 Count: 0
  MSG DMA Count: 0
  Interrupts Occurred Mask: 0x00000000
  Wakeup Interrupt Mask: 0x00000000
  Timeout Seconds: 0
  DMA Control: 0x00000000

---DIO COS Interrupt Information---
  DIO Interrupt Count: 0
  DIO Group 0 COS Count: 0
  DIO Group 1 COS Count: 0
  DIO Group 2 COS Count: 0
  DIO Group 0 COS OVFL Count: 0
  DIO Group 1 COS OVFL Count: 0
  DIO Group 2 COS OVFL Count: 0
  Interrupts Occurred Mask: 0x00000000
  Wakeup Interrupt Mask: 0x00000000
  DIO Group 0 COS Status: 0x00000000
  DIO Group 1 COS Status: 0x00000000
  DIO Group 2 COS Status: 0x00000000
  DIO Group 0 COS Ovfl Status: 0x00000000
  DIO Group 1 COS Ovfl Status: 0x00000000
  DIO Group 2 COS Ovfl Status: 0x00000000

---Ip Core Information---
  IpCore Code [00]: 0x00000007 ([7]: CCURPMFC_IPCODE_ENGINE_IP - Engine IP)
  IpCore Revision [00]: 0x00010000 (0001.0000)
  IpCore Offset [00]: 0x00010000
  IpCore Information [00]: 0x00000001
  IpCore Mapped Pointer [00]: 0x7ffff7fe7000
  IpCore Code [01]: 0x00000008 ([8]: CCURPMFC_IPCODE_INJ_IGN_PULSE_CAPTURE -
  Inj/Ign Pulse Capture)
  IpCore Revision [01]: 0x00010000 (0001.0000)
  IpCore Offset [01]: 0x00012000
  IpCore Information [01]: 0x00000004
  IpCore Mapped Pointer [01]: 0x7ffff7fe9000
  IpCore Code [02]: 0x00000009 ([9]: CCURPMFC_IPCODE_PWM_INPUT - PWM Input)
  IpCore Revision [02]: 0x00020000 (0002.0000)
  IpCore Offset [02]: 0x00011000
  IpCore Information [02]: 0x00000004
  IpCore Mapped Pointer [02]: 0x7ffff7fe8000
  IpCore Code [03]: 0x0000000a ([10]: CCURPMFC_IPCODE_PWM_OUTPUT - PWM
  Output)
  IpCore Revision [03]: 0x00030000 (0003.0000)
  IpCore Offset [03]: 0x00012000
  IpCore Information [03]: 0x00000004
  IpCore Mapped Pointer [03]: 0x7ffff7fe9000
  IpCore Code [04]: 0x0000000b ([11]: CCURPMFC_IPCODE_TOOTH_WHEEL_GENERATOR -
  Tooth Wheel Generator)
  IpCore Revision [04]: 0x00010000 (0001.0000)
  IpCore Offset [04]: 0x00011800
  IpCore Information [04]: 0x00000002
```



```

IpCore Mapped Pointer [04]: 0x7ffff7fe8800
  IpCore Code [05]: 0x0000000f ([15]: CCURPMFC_IPCODE_ANGULAR_ENCODER -
                                Angular Encoder)
    IpCore Revision [05]: 0x00010000 (0001.0000)
    IpCore Offset [05]: 0x00015400
    IpCore Information [05]: 0x00000001
IpCore Mapped Pointer [05]: 0x7ffff7fec400
  IpCore Code [06]: 0x00000010 ([16]: CCURPMFC_IPCODE_ANGULAR_DECODER -
                                Angular Decoder)
    IpCore Revision [06]: 0x00010000 (0001.0000)
    IpCore Offset [06]: 0x00015500
    IpCore Information [06]: 0x00000001
IpCore Mapped Pointer [06]: 0x7ffff7fec500
  IpCore Code [07]: 0x00000012 ([18]: CCURPMFC_IPCODE_ANALOG_THRESHOLD -
                                Analog Threshold)
    IpCore Revision [07]: 0x00010000 (0001.0000)
    IpCore Offset [07]: 0x00015000
    IpCore Information [07]: 0x00000001
IpCore Mapped Pointer [07]: 0x7ffff7fec000

```

---Memory Regions Information---

```

Region 0: Addr=0xbd620000 Size=32768 (0x8000)
Region 2: Addr=0xbd600000 Size=131072 (0x20000)

```

Board 1

```

Version: 23.0.3
Build: Thu Jun 21 10:23:45 EDT 2018
Module: ccurpmfc
Board Index: 0 (PCIe-CCUR_FPGA_PMFC)
Bus: 0x06
Slot: 0x00
Func: 0x00
Vendor ID: 0x1542
Sub-Vendor ID: 0x1542
Board Info: 0x92900101 (id=9290, type=0x01, func=0x01 (MultiFunc))
Member Code: 1 (A5)
Sub-Device ID: 0x0100
Firmware Date/Time: 0x10142016 0x00000000 (10/14/2016 00:00:00)
Firmware Revision: 0x00030002 (0003.0002)
Firmware Flavor Code: 0x00000000 (0) (****)
Number of Advanced IP Cores: 0x00000000 (0)
Board Serial Number: 0x00ab4130 (11223344)
Board SPROM Revision: 0x0000 (0)
FPGA Chip Temperature: 0x38 (56 degree C, 132.8 degree F)
Run Level Sector Number: 0x64 (100)
Multi-Firmware Support: 0x1 (Yes)
MSI Support: Enabled
Scatter-Gather DMA Support: No
Double-Word Support: Yes
IRQ Level: 58
Calibration Reference: 9.91 Volts

```

---ADC Information---

```

Maximum Voltage Range: 10 Volts
Number of ADCs: 2
Number of ADC Channels: 16
Number of ADC Resolution: 16 Bits
All ADC Channels Mask: 0x0000ffff
Maximum ADC Fifo Threshold: 0x00020000

```

---DAC Information---

```

Maximum Voltage Range: 20 Volts
Number of DACs: 4
Number of DAC Channels: 16
Number of DAC Resolution: 16 Bits
All DAC Channels Mask: 0x0000ffff

```

---DIO Information---

```

Number of DIO Channels: 96
Number of DIO Ports: 24
Number of DIO Channels/Port: 4

```

```
Number of DIO Registers: 3
Number of DIO Channels/Register: 32
```

```
---DMA Information---
  Driver DMA Size: 524288
Num of Trans Tbl Entries: 8
  Avalon Page Bits: 20
  Avalon Page Size: 1048576
  TX Interface Base: 8388608
  DMA Maximum Engines: 2
  DMA Maximum Burst Size: 1024
  DMA Maximum Transactions: 32
  DMA Maximum Size: 1048576
  DMA Width in Bytes: 4
  DMA Fire Command: 140

---Analog/DMA Interrupt Information---
  Interrupt Count: 0
    DMA 0 Count: 0
    DMA 1 Count: 0
  MSG DMA Count: 0
  Interrupts Occurred Mask: 0x00000000
  Wakeup Interrupt Mask: 0x00000000
  Timeout Seconds: 0
  DMA Control: 0x00000000

---DIO COS Interrupt Information---
  DIO Interrupt Count: 0
  DIO Group 0 COS Count: 0
  DIO Group 1 COS Count: 0
  DIO Group 2 COS Count: 0
  DIO Group 0 COS OVFL Count: 0
  DIO Group 1 COS OVFL Count: 0
  DIO Group 2 COS OVFL Count: 0
  Interrupts Occurred Mask: 0x00000000
  Wakeup Interrupt Mask: 0x00000000
  DIO Group 0 COS Status: 0x00000000
  DIO Group 1 COS Status: 0x00000000
  DIO Group 2 COS Status: 0x00000000
  DIO Group 0 COS Ovfl Status: 0x00000000
  DIO Group 1 COS Ovfl Status: 0x00000000
  DIO Group 2 COS Ovfl Status: 0x00000000

---Memory Regions Information---
  Region 0: Addr=0xbd520000 Size=32768 (0x8000)
  Region 2: Addr=0xbd500000 Size=131072 (0x20000)
```

3.2.16 lib/ccurpmfc_msgdma

This test performs a modular scatter-gather DMA test on boards that support it. Additionally, it displays performance information for each mode of operation.

```
Usage: ./ccurpmfc_msgdma [-a AddrOff,ToAddrOff] [-b Board] [-d NumDesc]
      [-f Input,Output] [-i] [-l LoopCnt] [-m Mode]
      [-s TotalXferSize] [-v] [-X]
-a <AddrOff,ToAddrOff> (First Avalon Address Offset, default DiagRam
                        offset)
                        (Second 'ToAddrOff' only for Avalon2Avalon mode)
-b <Board>              (board #, default = 0)
-d <NumDesc>           (Number of Descriptors, default = 2)
-f <Input>,<#Output>  (Use input file as input data. default None)
                        (Use Output file to write 'to' data. default
                        None)
                        (Prepend with '#' to remove comments and
                        address)
-i                     (Use interrupts, default is poll)
-l <LoopCnt>          (Loop Count, default = 1000)
-m <Mode>             (Mode of Operation, default = all)
```

```

'a2p'          (Avalon to Pci)
'p2a'          (Pci to Avalon)
'p2p'          (Pci to Pci)
'a2a'          (Avalon to Avalon)
'all'          (All modes)
-s <TotalXferSize> (Total Transfer Size, default size of DiagRam)
                  (Maximum transfer size is 0x3FFFF)
-v             (Verbose operation. default is quiet)
-X            (Skip Data Validation, default is to validate)

```

Notes:

- 1) For modes 'p2a' or 'a2p' only the first address 'AddrOff' used in option '-a'
- 2) For modes 'a2a' the first address 'AddrOff' is "FROM" and second address 'ToAddrOff' is "TO"
- 3) If Input file is specified in the '-f' option, its contents is used to seed input
- 4) If '-X' option is specified, no pattern is written to input, unless '-f Input' option is specified
- 5) Multiple '-m' options can be specified on a single command line
- 6) When address '-a' option is not specified, DiagRam offset is used for Analog input/output
- 7) Normal running process if no arguments specified is as follows:
 - a) Incrementing pattern written to the input using programmed I/O and readback validated
 - b) Output written with 'baadbeef' pattern using programmed I/O
 - c) Scatter-Gather DMA performed from Input to Output
 - d) Data is read back from both Input and Output using programmed I/O and compared

```

e.g. ./ccurpmfc_msgdma -mall          (Run all transfer modes with validation)
./ccurpmfc_msgdma -a0x8000 -s0x100   (Run all modes with Avalon Address 0x8000 and size 0x100)
./ccurpmfc_msgdma -a0xA000 -s0x200 -ma2a (Run a2a with Avalon Address 0xA000 and size 0x200)
./ccurpmfc_msgdma -mp2a -l1 -dl -fHexFile_16K -a0x10004 -X (Transfer Input file to Avalon memory at 0x10004)
./ccurpmfc_msgdma -ma2p -l1 -dl -f,OutFile -s0x4000 -a0x10004 -X (Transfer Avalon memory at 0x10004 to output file 'OutFile')

```

Example display:

```

./ccurpmfc_msgdma

1000: P2P Total: Size 0x8000, Fire= 109.77us ( 298.53 MB/s) (mi/ma/av
      108.80/ 114.95/ 109.94 us) LastWord=0x007cffff
1000: A2A Total: Size 0x4000, Fire= 103.59us ( 158.16 MB/s) (mi/ma/av
      103.19/ 106.97/ 103.68 us) LastWord=0x003e7fff
1000: P2A Total: Size 0x8000, Fire= 109.19us ( 300.11 MB/s) (mi/ma/av
      109.01/ 120.83/ 109.92 us) LastWord=0x007cffff
1000: A2P Total: Size 0x8000, Fire= 107.35us ( 305.24 MB/s) (mi/ma/av
      107.01/ 110.25/ 107.42 us) LastWord=0x007cffff

```

3.2.17 lib/ccurpmfc_msgdma_info

This test provides useful modular scatter-gather DMA information for cards that support it.

```

Usage: ./ccurpmfc_msgdma_info [-b Board] [-l]
      -b <Board>          (board #, default = 0)

```

Example display:

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./ccurpmfc_msgdma_info

=====
Dispatcher
=====

Status = 0x0000000a
Control = 0x0000000c
ReadFillLevel = 0x00000000
WriteFillLevel = 0x00000000
ResponseFillLevel = 0x00000000
ReadSequenceNumber = 0x00000004
WriteSequenceNumber = 0x00000004

=====
Prefetcher
=====

Status = 0x00000001
Control = 0x00000000
NextDescriptorPointer = 0x0000000000004800 (### Descriptor ID 1 ###)
DescriptorPollingFrequency = 0x00000000

=====
Descriptors
=====

ID	Addr	ReadAddr	WritAddr	Length	Stat	Control	Rbct	Wbct	Rstr	Wstr	ActBytXfr	NextPtr
1	(4800):	00b80000	00008000	003000	0000	80000000	00	00	0000	0000	00000000	00004840 (==> ID 2)
2	(4840):	00008000	00b83000	003000	0000	80000000	00	00	0000	0000	00000000	00004880 (==> ID 3)
3	(4880):	00b83000	0000b000	003000	0000	80000000	00	00	0000	0000	00000000	000048c0 (==> ID 4)
4	(48c0):	0000b000	00b86000	003000	0000	80000000	00	00	0000	0000	00000000	00004fc0 (Terminator)
5	(4900):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
6	(4940):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
7	(4980):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
8	(49c0):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
9	(4a00):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
10	(4a40):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
11	(4a80):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
12	(4ac0):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
13	(4b00):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
14	(4b40):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
15	(4b80):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
16	(4bc0):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
17	(4c00):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
18	(4c40):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
19	(4c80):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
20	(4cc0):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
21	(4d00):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
22	(4d40):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
23	(4d80):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
24	(4dc0):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
25	(4e00):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
26	(4e40):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
27	(4e80):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
28	(4ec0):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
29	(4f00):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
30	(4f40):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000
31	(4f80):	00000000	00000000	000000	0000	00000000	00	00	0000	0000	00000000	00000000

./ccurpmfc_msgdma_info -l

=====
Dispatcher
=====

Status = 0x0000000a
Control = 0x0000000c
ReadFillLevel = 0x00000000
WriteFillLevel = 0x00000000
ResponseFillLevel = 0x00000000
ReadSequenceNumber = 0x00000004
WriteSequenceNumber = 0x00000004

```

===== Prefetcher =====
Status                = 0x00000001
Control               = 0x00000000
NextDescriptorPointer = 0x0000000000004800 (### Descriptor ID 1 ###)
DescriptorPollingFrequency = 0x00000000

===== Descriptor ID 1 (address: 0x4800) =====
ReadAddress           = 0x0000000000b80000
WriteAddress          = 0x0000000000008000
NextDescriptorPointer = 0x0000000000004840 (### Descriptor ID 2 ###)
Status                = 0x0000
Control               = 0x80000000
Length                = 0x00003000 (12288)
ReadBurstCount        = 0x00 (0)
WriteBurstCount       = 0x00 (0)
ReadStride             = 0x0000 (0)
WriteStride           = 0x0000 (0)
ActualBytesTransferred = 0x00000000 (0)

===== Descriptor ID 2 (address: 0x4840) =====
ReadAddress           = 0x0000000000008000
WriteAddress          = 0x0000000000b83000
NextDescriptorPointer = 0x0000000000004880 (### Descriptor ID 3 ###)
Status                = 0x0000
Control               = 0x80000000
Length                = 0x00003000 (12288)
ReadBurstCount        = 0x00 (0)
WriteBurstCount       = 0x00 (0)
ReadStride             = 0x0000 (0)
WriteStride           = 0x0000 (0)
ActualBytesTransferred = 0x00000000 (0)

===== Descriptor ID 3 (address: 0x4880) =====
ReadAddress           = 0x0000000000b83000
WriteAddress          = 0x000000000000b000
NextDescriptorPointer = 0x00000000000048c0 (### Descriptor ID 4 ###)
Status                = 0x0000
Control               = 0x80000000
Length                = 0x00003000 (12288)
ReadBurstCount        = 0x00 (0)
WriteBurstCount       = 0x00 (0)
ReadStride             = 0x0000 (0)
WriteStride           = 0x0000 (0)
ActualBytesTransferred = 0x00000000 (0)

===== Descriptor ID 4 (address: 0x48c0) =====
ReadAddress           = 0x000000000000b000
WriteAddress          = 0x0000000000b86000
NextDescriptorPointer = 0x0000000000004fc0 (### Terminator ###)
Status                = 0x0000
Control               = 0x80000000
Length                = 0x00003000 (12288)
ReadBurstCount        = 0x00 (0)
WriteBurstCount       = 0x00 (0)
ReadStride             = 0x0000 (0)
WriteStride           = 0x0000 (0)
ActualBytesTransferred = 0x00000000 (0)

===== Descriptor ID 5 (address: 0x4900) =====
ReadAddress           = 0x0000000000000000
WriteAddress          = 0x0000000000000000
NextDescriptorPointer = 0x0000000000000000
Status                = 0x0000

```

```

Control                = 0x00000000
Length                 = 0x00000000 (0)
ReadBurstCount         = 0x00          (0)
WriteBurstCount        = 0x00          (0)
ReadStride             = 0x0000       (0)
WriteStride            = 0x0000       (0)
ActualBytesTransferred = 0x00000000 (0)
.
.
.
===== Descriptor ID 30 (address: 0x4f40) =====
ReadAddress            = 0x0000000000000000
WriteAddress           = 0x0000000000000000
NextDescriptorPointer  = 0x0000000000000000
Status                 = 0x0000
Control                = 0x00000000
Length                 = 0x00000000 (0)
ReadBurstCount         = 0x00          (0)
WriteBurstCount        = 0x00          (0)
ReadStride             = 0x0000       (0)
WriteStride            = 0x0000       (0)
ActualBytesTransferred = 0x00000000 (0)

===== Descriptor ID 31 (address: 0x4f80) =====
ReadAddress            = 0x0000000000000000
WriteAddress           = 0x0000000000000000
NextDescriptorPointer  = 0x0000000000000000
Status                 = 0x0000
Control                = 0x00000000
Length                 = 0x00000000 (0)
ReadBurstCount         = 0x00          (0)
WriteBurstCount        = 0x00          (0)
ReadStride             = 0x0000       (0)
WriteStride            = 0x0000       (0)
ActualBytesTransferred = 0x00000000 (0)

```

3.2.18 lib/ccurpmfc_transfer

This test performs various DMA and Programmed I/O transfers between the board components and the PCI memory.

```

Usage: ./ccurpmfc_transfer [-b Board] [-c CaseNum] [-i] [-l LoopCnt]
      [-s XferSize]
-b Board      (Board number -- default is 0)
-c CaseNum    (Select Case Numbers -- default = ALL CASES)
  -c 4,1,7-9  select case 1,4,7,8,9)
  -c 8-       select case 8 to end)
  -c -3       select case 1,2,3)
-i           (Enable Interrupts -- default = Disable)
-l LoopCnt    (Loop Count -- default is 100)
-s XferSize   (Avalon Ram Xfer Size in bytes -- default is 32768)

```

Example display:

```
./ccurpmfc_transfer    (for cards with modular scatter-gather DMA support)
```

```

local_ptr=0x7ffff7fd7000
Size of Avalon RAM = 32768 (0x00008000)
Physical Memory Information:
  UserPID          =22540
  PhysMemPtr       =0x78068000
  DriverVirtMemPtr=0xffff880078068000
  MmappedUserMemPtr=0x7ffff7fc5000
  PhysMemSize      =0x00008000

```

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```

PhysMemSizeFreed=0x00000000
EntryInTxTbl    =0
NumOfEntriesUsed=1

1: Memory -> Avalon RAM (DMA0) (Size=0x8000):      100 (1074.47 us, 30.50 MBytes/Sec)
2: Memory -> Avalon RAM (DMA1) (Size=0x8000):      100 (1074.77 us, 30.49 MBytes/Sec)
3: Memory -> Avalon RAM (MSGDMA) (Size=0x8000):    100 (109.54 us, 299.14 MBytes/Sec)
4: Memory -> Avalon RAM (PIO) (Size=0x8000):       100 (987.92 us, 33.17 MBytes/Sec)
5: Avalon RAM -> Memory (DMA0) (Size=0x8000):      100 (1854.17 us, 17.67 MBytes/Sec)
6: Avalon RAM -> Memory (DMA1) (Size=0x8000):      100 (1854.26 us, 17.67 MBytes/Sec)
7: Avalon RAM -> Memory (MSGDMA) (Size=0x8000):    100 (108.60 us, 301.73 MBytes/Sec)
8: Avalon RAM -> Memory (PIO) (Size=0x8000):       100 (7346.86 us, 4.46 MBytes/Sec)
9: Memory -> Avalon ADC Calibration (DMA0) (Size=0x40): 10000 (8.88 us, 7.21 MBytes/Sec)
10: Memory -> Avalon ADC Calibration (DMA1) (Size=0x40): 10000 (8.80 us, 7.27 MBytes/Sec)
11: Memory -> Avalon ADC Calibration (PIO) (Size=0x40): 10000 (0.69 us, 92.85 MBytes/Sec)
12: Avalon ADC Calibration -> Memory (DMA0) (Size=0x40): 10000 (8.37 us, 7.65 MBytes/Sec)
13: Avalon ADC Calibration -> Memory (DMA1) (Size=0x40): 10000 (8.58 us, 7.46 MBytes/Sec)
14: Avalon ADC Calibration -> Memory (PIO) (Size=0x40): 10000 (19.91 us, 3.21 MBytes/Sec)
15: Memory -> Avalon SDRAM(FIFO) (DMA0) (Size=0x8000): 100 (1074.60 us, 30.49 MBytes/Sec)
16: Memory -> Avalon SDRAM(FIFO) (DMA1) (Size=0x8000): 100 (1074.81 us, 30.49 MBytes/Sec)
17: Memory -> Avalon SDRAM(FIFO) (PIO) (Size=0x8000): 100 (997.24 us, 32.86 MBytes/Sec)
18: Avalon SDRAM(FIFO) -> Memory (DMA0) (Size=0x8000): 100 (1996.39 us, 16.41 MBytes/Sec)
19: Avalon SDRAM(FIFO) -> Memory (DMA1) (Size=0x8000): 100 (1996.46 us, 16.41 MBytes/Sec)
20: Avalon SDRAM(FIFO) -> Memory (PIO) (Size=0x8000): 100 (11406.91 us, 2.87 MBytes/Sec)
**** Test Passed ****

```

`./ccurpmfc_transfer` (for cards without modular scatter-gather DMA support)

```

local_ptr=0x7ffff7fd7000
Size of Avalon RAM = 32768 (0x00008000)
Physical Memory Information:
  UserPID      =22625
  PhysMemPtr   =0x78068000
  DriverVirtMemPtr=0xffff880078068000
  MmappedUserMemPtr=0x7ffff7fc5000
  PhysMemSize  =0x00008000
  PhysMemSizeFreed=0x00000000
  EntryInTxTbl =0
  NumOfEntriesUsed=1

1: Memory -> Avalon RAM (DMA0) (Size=0x8000):      100 (1137.05 us, 28.82 MBytes/Sec)
2: Memory -> Avalon RAM (DMA1) (Size=0x8000):      100 (1136.70 us, 28.83 MBytes/Sec)
3: Memory -> Avalon RAM (PIO) (Size=0x8000):       100 (695.42 us, 47.12 MBytes/Sec)
4: Avalon RAM -> Memory (DMA0) (Size=0x8000):      100 (1857.79 us, 17.64 MBytes/Sec)
5: Avalon RAM -> Memory (DMA1) (Size=0x8000):      100 (1857.76 us, 17.64 MBytes/Sec)
6: Avalon RAM -> Memory (PIO) (Size=0x8000):       100 (4715.11 us, 6.95 MBytes/Sec)
7: Memory -> Avalon ADC Calibration (DMA0) (Size=0x40): 10000 (8.67 us, 7.38 MBytes/Sec)
8: Memory -> Avalon ADC Calibration (DMA1) (Size=0x40): 10000 (8.64 us, 7.41 MBytes/Sec)
9: Memory -> Avalon ADC Calibration (PIO) (Size=0x40): 10000 (0.11 us, 589.24 MBytes/Sec)
10: Avalon ADC Calibration -> Memory (DMA0) (Size=0x40): 10000 (8.69 us, 7.37 MBytes/Sec)
11: Avalon ADC Calibration -> Memory (DMA1) (Size=0x40): 10000 (8.69 us, 7.36 MBytes/Sec)
12: Avalon ADC Calibration -> Memory (PIO) (Size=0x40): 10000 (10.77 us, 5.94 MBytes/Sec)
13: Memory -> Avalon SDRAM(FIFO) (DMA0) (Size=0x8000): 100 (1136.93 us, 28.82 MBytes/Sec)
14: Memory -> Avalon SDRAM(FIFO) (DMA1) (Size=0x8000): 100 (1136.76 us, 28.83 MBytes/Sec)
15: Memory -> Avalon SDRAM(FIFO) (PIO) (Size=0x8000): 100 (1412.14 us, 23.20 MBytes/Sec)
16: Avalon SDRAM(FIFO) -> Memory (DMA0) (Size=0x8000): 100 (2002.71 us, 16.36 MBytes/Sec)
17: Avalon SDRAM(FIFO) -> Memory (DMA1) (Size=0x8000): 100 (2002.95 us, 16.36 MBytes/Sec)
18: Avalon SDRAM(FIFO) -> Memory (PIO) (Size=0x8000): 100 (11354.51 us, 2.89 MBytes/Sec)
**** Test Passed ****

```

3.2.19 lib/ccurpmfc_tst_lib

This is an interactive test that accesses the various supported API calls.

```

Usage: ./ccurpmfc_tst_lib [-b board]
      -b board: board number -- default board is 0

```

Example display:

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./ccurpmfc_tst_lib

Device Name: /dev/ccurpmfc0

01 = Abort DMA	02 = Clear Driver Error
03 = Clear Library Error	04 = Display BOARD Registers
05 = Display CONFIG Registers	06 = Dump Physical Memory List
07 = Get All Boards Driver Information	08 = Get Board CSR
09 = Get Board Information	10 = Get Driver Error
11 = Get Driver Information	12 = Get Library Error
13 = Get Mapped Config Pointer	14 = Get Mapped Driver/Library Pointer
15 = Get Mapped Local Pointer	16 = Get Physical Memory
17 = Get Test Bus Control	18 = Get Value
19 = Initialize Board	20 = MMap Physical Memory
21 = Munmap Physical Memory	22 = Reload Firmware
23 = Reset Board	24 = Set Board CSR
25 = Set Test Bus Control	26 = Set Value
27 = ### ADC MENU ###	28 = ### CALIBRATION MENU ###
29 = ### CLOCK GENERATOR MENU ###	30 = ### DAC MENU ###
31 = ### DIO MENU ###	32 = ### INTERRUPT MENU ###
33 = ### IP CORE MENU ###	34 = ### SDRAM MENU ###
35 = ### SPROM MENU ###	

Main Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 27

Command: ADC_menu()

01 = ADC Activate	02 = ADC Disable
03 = ADC Driver Read Operation	04 = ADC Get CSR
05 = ADC Get Driver Read Mode	06 = ADC Get FIFO Channel Select
07 = ADC Get FIFO Information	08 = ADC Get FIFO Threshold
09 = ADC Read Channels	10 = ADC Reset FIFO
11 = ADC Set CSR	12 = ADC Set Driver Read Mode
13 = ADC Set FIFO Channel Select	14 = ADC Set FIFO Threshold

ADC Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 28

Command: calibration_menu()

01 = ADC: Get Calibrated Values	02 = ADC: Perform Auto Calibration
03 = ADC: Perform External Negative Calib.	04 = ADC: Perform External Offset Calib.
05 = ADC: Perform External Positive Calib.	06 = ADC: Perform Negative Calibration
07 = ADC: Perform Offset Calibration	08 = ADC: Perform Positive Calibration
09 = ADC: Read Channels Calibration	10 = ADC: Reset Calibration
11 = ADC: Write Channels Calibration	12 = DAC: Get Calibrated Values
13 = DAC: Perform Auto Calibration	14 = DAC: Perform Gain Calibration
15 = DAC: Perform Offset Calibration	16 = DAC: Read Channels Calibration
17 = DAC: Reset Calibration	18 = DAC: Write Channels Calibration
19 = Get Calibration CSR	20 = Set Calibration CSR

Calibration Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 29

Command: clock_generator_menu()

01 = Clock Get Generator CSR	02 = Clock Get Generator Dividers
03 = Clock Get Generator Information	04 = Clock Get Generator Input Clock Enable
05 = Clock Get Generator Input Clock Select	06 = Clock Get Generator Input Clock Status
07 = Clock Get Generator Output Config	08 = Clock Get Generator Output Format
09 = Clock Get Generator Output Mode	10 = Clock Get Generator Output Mux
11 = Clock Get Generator P-Divider Enable	12 = Clock Get Generator Revision
13 = Clock Get Generator Value	14 = Clock Get Generator Voltage Select
15 = Clock Get Generator Zero Delay	16 = Clock Set Generator CSR
17 = Clock Set Generator Dividers	18 = Clock Set Generator Input Clock Enable
19 = Clock Set Generator Input Clock Select	20 = Clock Set Generator Output Config
21 = Clock Set Generator Output Format	22 = Clock Set Generator Output Mode
23 = Clock Set Generator Output Mux	24 = Clock Set Generator P-Divider Enable
25 = Clock Set Generator Value	26 = Clock Set Generator Voltage Select
27 = Clock Set Generator Zero Delay	28 = Compute All Output Clocks
29 = Program All Output Clocks	30 = Read Clock Registers

31 = Reset Clock (Hardware) 32 = Soft Reset
33 = Update Clock Generator Divider 34 = Write Clock Registers

Clock Generator Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 30

Command: DAC_menu()
01 = DAC Activate 02 = DAC Disable
03 = DAC Driver Write Operation 04 = DAC Get CSR
05 = DAC Get Driver Write Mode 06 = DAC Get FIFO Channel Select
07 = DAC Get FIFO Information 08 = DAC Get FIFO Threshold
09 = DAC Get FIFO Write Count 10 = DAC Get Update Select
11 = DAC ReadBack Channels 12 = DAC Read Channels
13 = DAC Reset FIFO 14 = DAC Set CSR
15 = DAC Set Driver Write Mode 16 = DAC Set FIFO Channel Select
17 = DAC Set FIFO Threshold 18 = DAC Set FIFO Write Count
19 = DAC Set Update Select 20 = DAC Write Channels

DAC Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 31

Command: DIO_menu()
01 = DIO Activate 02 = DIO Disable
03 = DIO Get Channels Polarity 04 = DIO Get COS Channels Edge Sense
05 = DIO Get COS Channels Enable 06 = DIO Get COS Channels Mode
07 = DIO Get COS Channels Overflow 08 = DIO Get COS Channels Status
09 = DIO Get Input Channels Filter 10 = DIO Get Input Snapshot
11 = DIO Get Mode 12 = DIO Get Output Sync
13 = DIO Get Ports Direction 14 = DIO Information
15 = DIO Read Custom Channels 16 = DIO Read Input Channels
17 = DIO Read Output Channels 18 = DIO Set Channels Polarity
19 = DIO Set COS Channels Edge Sense 20 = DIO Set COS Channels Enable
21 = DIO Set COS Channels Mode 22 = DIO Set Input Channels Filter
23 = DIO Set Input Snapshot 24 = DIO Set Mode
25 = DIO Set Output Sync 26 = DIO Set Ports Direction
27 = DIO Set Ports Direction to Inputs 28 = DIO Set Ports Direction to Outputs
29 = DIO Write Output Channels 30 = DIO Write Output Channels High
31 = DIO Write Output Channels Low

DIO Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 32

Command: interrupt_menu()
01 = Add Irq 02 = Disable Pci Interrupts
03 = Enable Pci Interrupts 04 = Get Interrupt Status
05 = Get Interrupt Timeout 06 = Remove Irq
07 = Set Interrupt Status 08 = Set Interrupt Timeout

Interrupt Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 33

Command: IPCORE_menu()
01 = IpCore COS Activate 02 = IpCore COS Configure
03 = IpCore COS Disable 04 = IpCore COS Get Information
05 = IpCore COS Read 06 = IpCore COS Read (AGAIN)
07 = IpCore COS Start/Stop Capture 08 = IpCore Get Ip Information
09 = IpCore Get Ip Mapped Pointer

IP Core Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 34

Command: SDRAM_menu()
01 = SDRAM Activate 02 = SDRAM Disable
03 = SDRAM Get CSR 04 = SDRAM Read
05 = SDRAM Set CSR 06 = SDRAM Write

SDRAM Selection ('h'=display menu, 'q'=quit)->

Main Selection ('h'=display menu, 'q'=quit)-> 35

Command: SPROM_menu()
01 = Clear Serial Prom 02 = Read Serial Prom

```

03 = Read Serial Prom Item          04 = Write Override
05 = Write Serial Prom              06 = Write Serial Prom Item

```

```
SPROM Selection ('h'=display menu, 'q'=quit)->
```

3.2.20 lib/IpCore/ccurpmfc_ipcore_cos

This program demonstrates the features of the IP Core Change of State card.

```

Usage: ./ccurpmfc_ipcore_cos [-b Board] [-c ChannelMask] [-d Delay]
                                [-D DMAEngineNo] [-F DebugFile] [-l LoopCnt]
                                [-m XferMode] [-n Element2Display] [-T TestNumber]
                                [-V VerifyPattern] [-w Control] [-x]

-b Board          (Board number -- default board is 0)
-c ChannelsMask  (select channels mask)
  -c0@XXXXXXXXXX (Channels 31..00=XXXXXXXXXX in Hex)
  -c1@XXXXXXXXXX (Channels 63..32=XXXXXXXXXX in Hex)
-d Delay          (Delay in milli-secs between screen refresh -- default is 0)
-D DMAEngineNo   (DMA Engine number -- default = 1)
-F DebugFile     (Debug file with menu display -- default "=== None ===")
  @DebugFile     (Debug file without display)
  @              (No debug file and no display)
-l LoopCnt       (Loop Count - default = 0)
-m XferMode      (Transfer Mode -- default = DMA)
  -md            (Library ccurPMFC_Transfer_Data(): DMA mode)
  -mp            (Library ccurPMFC_Transfer_Data(): Progammed I/O mode)
-n Element2Display (Number of Elements to Display -- default is 128)
-T TestNumber    (Execute Self test 0=alternate or 1=increment pattern)
  -T0           (Atlernate pattern test -- AAAAAAAAA/55555555)
  -T1           (Increment pattern test)
-V VerifyPattern (Verify capture rate, increment or alternate test pattern)
  -Vr          (compute capture rate)
  -Vp          (verify increment or alternate test pattern (-winc or -walt))
-w Control      (select control: Normal/Test(increment/alternate pattern,
  div=1,2,4,8,16,32,64,128), Start/Stop
  -wte -wsta   (select 'test; mode and 'start' capture)
  -wn -wStop   (select 'normal' mode and 'stop' capture)
  -walt -wtest (select 'alternation - 5555/AAAA' and 'test' mode capture)
  -winc -wtest (select 'increment - 5555/AAAA' and 'test' mode capture)
  -winc -w128 -wtest
                (select 'increment - 5555/AAAA' and 'test' mode capture with
                time divider of 128)
-x             (Skip decoding of timestamp)

e.g. ./ccurpmfc_ipcore_cos -c0@ffff -c1@ffff0000 -wtest -wstart (select channels
                                00..15 and 63..48, test mode, start capture)
     ./ccurpmfc_ipcore_cos -c0@ffffffff -c1@ffffffff -wtest -walt -wstart -Vp
                                (verify alternate 5555/AAAA pattern)
     ./ccurpmfc_ipcore_cos -T0 (verify alternate 5555/AAAA pattern)
     ./ccurpmfc_ipcore_cos -T1 (verify increment pattern test)

```

Example display:

```
./ccurpmfc_ipcore_cos -b1 -T1
```

```

Board Number [-b]: 1
Delay [-d]: 20 milli-seconds
DMA Engine [-D]: 1
Loop Count [-l]: ***Forever***
Transfer Mode [-m]: (-d) Library ccurPMFC_Transfer_Data(): DMA I/O
Number of Elements to Display [-n]: 24
Verify Pattern [-V]: Incrementing
COS Control: 0x0000070f (Enable, Test Mode[Increment, Div=128], Start

```

```

                                Capture)
                                COS Status: 0x9a500004 (Enabled, No Overflow, FIFO not Full)
                                COS Channel Mask: 0xffffffff 0xffffffff (63..32 31..0)
                                COS FIFO Count: 0x0000007c (124)
Number of Overflows Occurred: 0
                                ScanCount: 1218
Number of Elements Returned: 31, Total COS Occurred: 37706

Read Duration (microsecs):      34.674 (min= 17.104/max= 42.532/ave= 34.769)
Element TimeStamp (Raw)         ChannelMask          TimeStamp (Decoded)
                                63....32 31....00      63....32 31....00      Day:HH:MM:SS:Mil.MicroSec
 1 00000000 49958001 - 0000932c 0000932c - 000:00:00:24:690.688020
 2 00000000 49960001 - 0000932d 0000932d - 000:00:00:24:691.343380
 3 00000000 49968001 - 0000932e 0000932e - 000:00:00:24:691.998740
 4 00000000 49970001 - 0000932f 0000932f - 000:00:00:24:692.654100
 5 00000000 49978001 - 00009330 00009330 - 000:00:00:24:693.309460
 6 00000000 49980001 - 00009331 00009331 - 000:00:00:24:693.964820
 7 00000000 49988001 - 00009332 00009332 - 000:00:00:24:694.620180
 8 00000000 49990001 - 00009333 00009333 - 000:00:00:24:695.275540
 9 00000000 49998001 - 00009334 00009334 - 000:00:00:24:695.930900
10 00000000 499a0001 - 00009335 00009335 - 000:00:00:24:696.586260
11 00000000 499a8001 - 00009336 00009336 - 000:00:00:24:697.241620
12 00000000 499b0001 - 00009337 00009337 - 000:00:00:24:697.896980
13 00000000 499b8001 - 00009338 00009338 - 000:00:00:24:698.552340
14 00000000 499c0001 - 00009339 00009339 - 000:00:00:24:699.207700
15 00000000 499c8001 - 0000933a 0000933a - 000:00:00:24:699.863060
16 00000000 499d0001 - 0000933b 0000933b - 000:00:00:24:700.518420
17 00000000 499d8001 - 0000933c 0000933c - 000:00:00:24:701.173780
18 00000000 499e0001 - 0000933d 0000933d - 000:00:00:24:701.829140
19 00000000 499e8001 - 0000933e 0000933e - 000:00:00:24:702.484500
20 00000000 499f0001 - 0000933f 0000933f - 000:00:00:24:703.139860
21 00000000 499f8001 - 00009340 00009340 - 000:00:00:24:703.795220
22 00000000 49a00001 - 00009341 00009341 - 000:00:00:24:704.450580
23 00000000 49a08001 - 00009342 00009342 - 000:00:00:24:705.105940
24 00000000 49a10001 - 00009343 00009343 - 000:00:00:24:705.761300

```

3.2.21 lib/Sprom/ccurpmfc_sprom

This is a simple program to demonstrate sprom access.

```

Usage: ./ccurpmfc_sprom [-b board] [-C] [-D] [-S serialNo]
-b <board>          (Board #, default = 0)
-C                  (Clear ENTIRE serial PROM first)
-D                  (Dump entire serial prom)
-S <serialNo>      (Program board serial number)

e.g.  ./ccurpmfc_sprom -C          -> Clear Entire Serial Prom First
      ./ccurpmfc_sprom -D          -> Dump Entire Serial Prom
      ./ccurpmfc_sprom -S 12345678 -> Write Serial Number

```

Example display:

```

./Sprom/ccurpmfc_sprom

Device Name:          /dev/ccurpmfc0
Board Serial Number: 12345 (0x00003039)
Serial PROM Revision: 0 (0x0000)

```

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